



MC6850
(1.0 MHz)
MC68A50
(1.5 MHz)
MC68B50
(2.0 MHz)

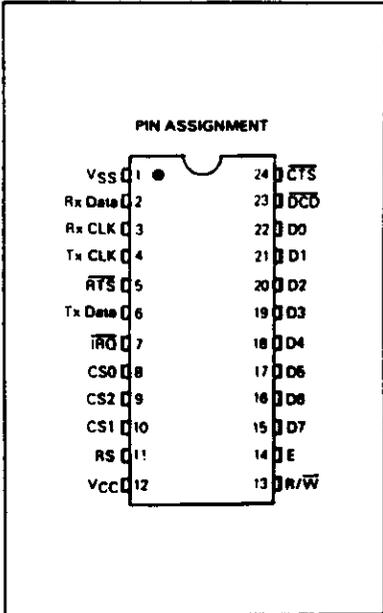
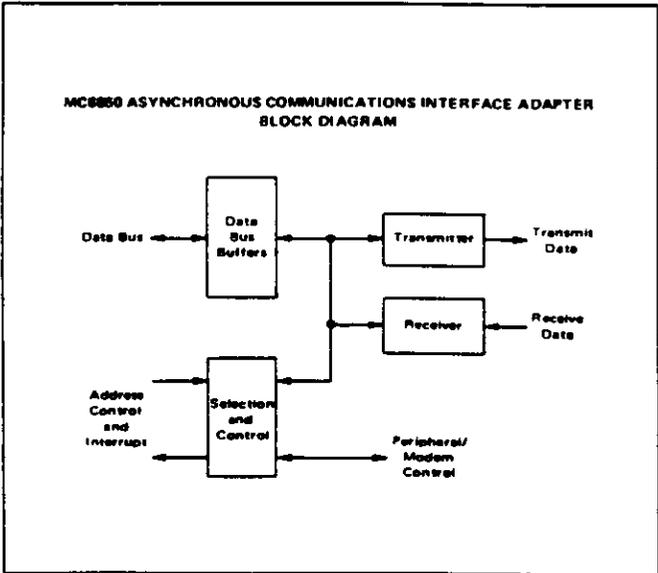
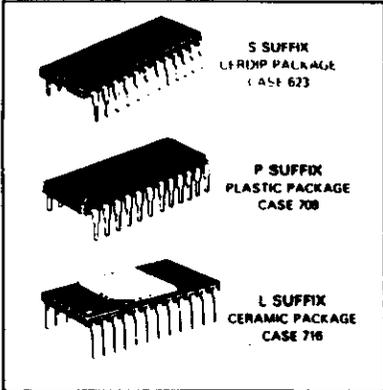
ASYNCHRONOUS COMMUNICATIONS INTERFACE ADAPTER (ACIA)

The MC6850 Asynchronous Communications Interface Adapter provides the data formatting and control to interface serial asynchronous data communications information to bus organized systems such as the MC6800 Microprocessing Unit.

The bus interface of the MC6850 includes select, enable, read/write, interrupt and bus interface logic to allow data transfer over an 8-bit bidirectional data bus. The parallel data of the bus system is serially transmitted and received by the asynchronous data interface, with proper formatting and error checking. The functional configuration of the ACIA is programmed via the data bus during system initialization. A programmable Control Register provides variable word lengths, clock division ratios, transmit control, receive control, and interrupt control. For peripheral or modem operation, three control lines are provided. These lines allow the ACIA to interface directly with the MC6860L 0-600 bps digital modem.

- 8- and 9-Bit Transmission
- Optional Even and Odd Parity
- Parity, Overrun and Framing Error Checking
- Programmable Control Register
- Optional $\times 1$, $\times 16$, and $\times 64$ Clock Modes
- Up to 1.0 Mbps Transmission
- False Start Bit Deletion
- Peripheral/Modem Control Functions
- Double Buffered
- One- or Two-Stop Bit Operation

MOS
(IN-CHANNEL, SILICON-GATE)
ASYNCHRONOUS COMMUNICATIONS INTERFACE ADAPTER



MC6850•MC68A50•MC68B50

SERIAL DATA TIMING CHARACTERISTICS

Characteristic	Symbol	MC6850		MC68A50		MC68B50		Unit
		Min	Max	Min	Max	Min	Max	
Data Clock Pulse Width, Low (See Figure 1)	PW_{CL}	900	—	450	—	280	—	ns
Data Clock Pulse Width, High (See Figure 2)	PW_{CH}	900	—	450	—	280	—	ns
Data Clock Frequency	f_C	—	0.8	—	1.0	—	1.5	MHz
		—	500	—	750	—	1000	kHz
Data Clock-to-Data Delay for Transmitter (See Figure 3)	t_{TDD}	—	900	—	540	—	480	ns
Receive Data Setup Time (See Figure 4)	t_{RDS}	250	—	100	—	30	—	ns
Receive Data Hold Time (See Figure 5)	t_{RDH}	250	—	100	—	30	—	ns
Interrupt Request Release Time (See Figure 6)	t_{IR}	—	1.2	—	0.9	—	0.7	μ s
Request-to-Send Delay Time (See Figure 6)	t_{RTS}	—	560	—	480	—	400	ns
Input Rise and Fall Times (for 10% of the pulse width if smaller)	t_r, t_f	—	1.0	—	0.5	—	0.25	μ s

FIGURE 1 — CLOCK PULSE WIDTH, LOW-STATE

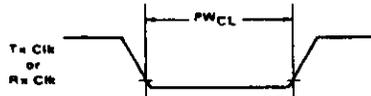


FIGURE 2 — CLOCK PULSE WIDTH, HIGH-STATE



FIGURE 3 — TRANSMIT DATA OUTPUT DELAY

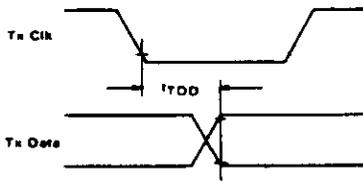


FIGURE 4 — RECEIVE DATA SETUP TIME (-1 Mode)

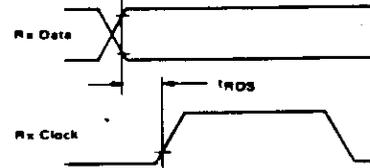


FIGURE 5 — RECEIVE DATA HOLD TIME (-1 Mode)

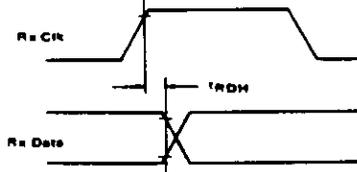
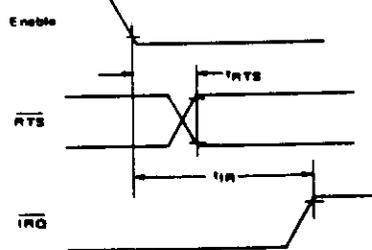
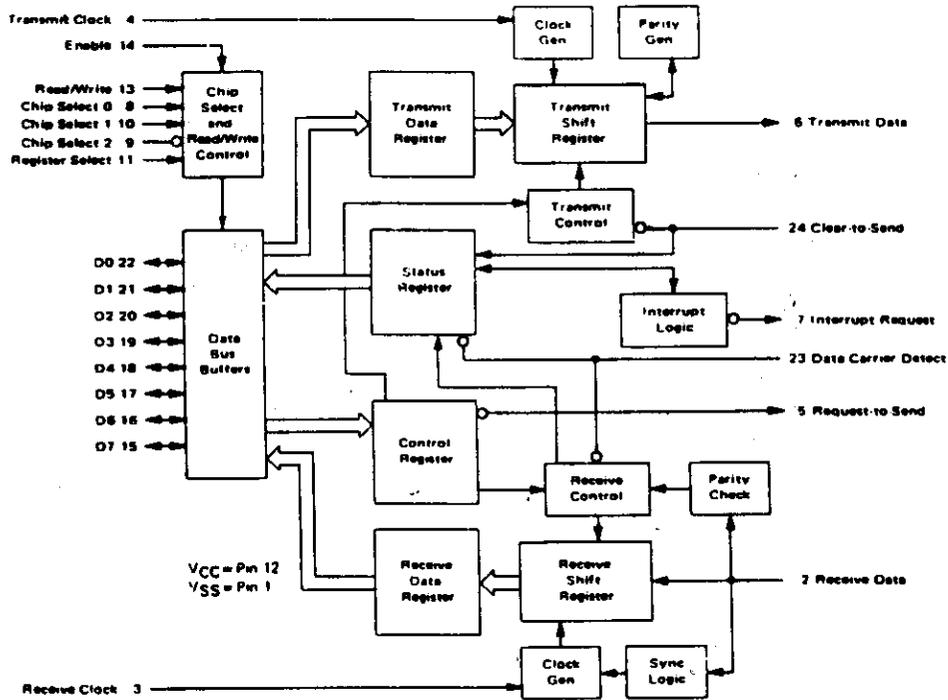


FIGURE 6 — REQUEST-TO-SEND DELAY AND INTERRUPT-REQUEST RELEASE TIMES



Note: Timing measurements are referenced to and from a low voltage of 0.8 volts and a high voltage of 2.0 volts, unless otherwise noted.

FIGURE 9 — EXPANDED BLOCK DIAGRAM



DEVICE OPERATION

At the bus interface, the ACIA appears as two addressable memory locations. Internally, there are four registers: two read-only and two write-only registers. The read-only registers are Status and Receive Data; the write-only registers are Control and Transmit Data. The serial interface consists of serial input and output lines with independent clocks, and three peripheral/modem control lines.

POWER ON/MASTER RESET

The master reset (CR0, CR1) should be set during system initialization to insure the reset condition and prepare for programming the ACIA functional configuration when the communications channel is required. During the first master reset, the \overline{IRQ} and \overline{RTS} outputs are held at level 1. On all other master resets, the \overline{RTS} output can be programmed high or low with the \overline{IRQ} output held high. Control bits CR5 and CR6 should also be programmed to define the state of \overline{RTS} whenever master reset is utilized. The ACIA also contains internal power-on reset logic to detect the power line turn-on transition and hold the chip in a reset state to prevent erroneous output transitions prior to initialization. This circuitry depends on clean power turn-on transitions. The

power-on reset is released by means of the bus-programmed master reset which must be applied prior to operating the ACIA. After master resetting the ACIA, the programmable Control Register can be set for a number of options such as variable clock divider ratios, variable word length, one or two stop bits, parity (even, odd, or none), etc.

TRANSMIT

A typical transmitting sequence consists of reading the ACIA Status Register either as a result of an interrupt or in the ACIA's turn in a polling sequence. A character may be written into the Transmit Data Register if the status read operation has indicated that the Transmit Data Register is empty. This character is transferred to a Shift Register where it is serialized and transmitted from the Transmit Data output preceded by a start bit and followed by one or two stop bits. Internal parity (odd or even) can be optionally added to the character and will occur between the last data bit and the first stop bit. After the first character is written in the Data Register, the Status Register can be read again to check for a Transmit Data Register Empty condition and current peripheral status. If the register is empty, another character can be loaded for transmission even though the first character is in the process of being transmitted (because of

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SERIAL INPUT/OUTPUT LINES

Receive Data (Rx Data) — The Receive Data line is a high-impedance TTL-compatible input through which data is received in a serial format. Synchronization with a clock for detection of data is accomplished internally when clock rates of 16 or 64 times the bit rate are used.

Transmit Data (Tx Data) — The Transmit Data output line transfers serial data to a modem or other peripheral.

PERIPHERAL/MODEM CONTROL

The ACIA provides several functions that permit limited control of a peripheral or modem. The functions included are Clear-to-Send, Request-to-Send and Data Carrier Detect.

Clear-to-Send (CTS) — This high-impedance TTL-compatible input provides automatic control of the transmitting end of a communications link via the modem Clear-to-Send active low output by inhibiting the Transmit Data Register Empty (TDRE) status bit.

Request-to-Send (RTS) — The Request-to-Send output enables the MPU to control a peripheral or modem via the data bus. The RTS output corresponds to the state of the Control Register bits CR5 and CR6. When CR6=0 or both CR5 and CR6=1, the RTS output is low (the active state). This output can also be used for Data Terminal Ready (DTR).

Data Carrier Detect (DCD) — This high-impedance TTL-compatible input provides automatic control, such as in the receiving end of a communications link by means of a modem Data Carrier Detect output. The DCD input inhibits and initializes the receiver section of the ACIA when high. A low-to-high transition of the Data Carrier Detect initiates an interrupt to the MPU to indicate the occurrence of a loss of carrier when the Receive Interrupt Enable bit is set. The Rx CLK must be running for proper DCD operation.

ACIA REGISTERS

The expanded block diagram for the ACIA indicates the internal registers on the chip that are used for the status, control, receiving, and transmitting of data. The content of each of the registers is summarized in Table 1.

TRANSMIT DATA REGISTER (TDR)

Data is written in the Transmit Data Register during the negative transition of the enable (E) when the ACIA has been addressed with RS high and R/W low. Writing data into the register causes the Transmit Data Register Empty bit in the Status Register to go low. Data can then be transmitted. If the transmitter is idling and no character is being transmitted, then the transfer will take place within 1-bit time of the trailing edge of the Write command. If a character is being transmitted, the new data character will commence as soon as the previous character is complete. The transfer of data causes the Transmit Data Register Empty (TDRE) bit to indicate empty.

RECEIVE DATA REGISTER (RDR)

Data is automatically transferred to the empty Receive Data Register (RDR) from the receiver deserializer (a shift register) upon receiving a complete character. This event causes the Receive Data Register Full bit (RDRF) in the status buffer to go high (full). Data may then be read through the bus by addressing the ACIA and selecting the Receive Data Register with RS and R/W high when the ACIA is enabled. The non-destructive read cycle causes the RDRF bit to be cleared to empty although the data is retained in the RDR. The status is maintained by RDRF as to whether or not the data is current. When the Receive Data Register is full, the automatic transfer of data from the Receiver Shift Register to the Data Register is inhibited and the RDR contents remain valid with its current status stored in the Status Register.

TABLE 1 — DEFINITION OF ACIA REGISTER CONTENTS

Data Bus Line Number	Buffer Address			
	RS = R/W	RS = R/W	RS = R/W	RS = R/W
	Transmit Data Register (Write Only)	Receive Data Register (Read Only)	Control Register (Write Only)	Status Register (Read Only)
0	Data Bit 0*	Data Bit 0	Counter Divide Select 1 (CR0)	Receive Data Register Full (RDRF)
1	Data Bit 1	Data Bit 1	Counter Divide Select 2 (CR1)	Transmit Data Register Empty (TDRE)
2	Data Bit 2	Data Bit 2	Word Select 1 (CR2)	Data Carrier Detect (DCD)
3	Data Bit 3	Data Bit 3	Word Select 2 (CR3)	Clear to Send (CTS)
4	Data Bit 4	Data Bit 4	Word Select 3 (CR4)	Framing Error (FE)
5	Data Bit 5	Data Bit 5	Transmit Control 1 (CR5)	Receiver Interrupt (RIRI)
6	Data Bit 6	Data Bit 6	Transmit Control 2 (CR6)	Parity Error (PE)
7	Data Bit 7***	Data Bit 7**	Receive Interrupt Enable (RRIE)	Interrupt Request (IRI)

* Leading bit, LSB, Bit 0
 ** Data bit will be zero in 7 bit plus parity modes
 *** Data bit is "don't care" in 7 bit plus parity modes

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been read. The RDRF bit remains set until the Overrun is reset. Character synchronization is maintained during the Overrun condition. The Overrun indication is reset after the reading of data from the Receive Data Register or by a Master Reset.

Parity Error (PE), Bit 6 — The parity error flag indicates that the number of highs (ones) in the character does not agree with the preselected odd or even parity. Odd parity is defined to be when the total number of ones is odd. The parity error indication will be present as long as the data

character is in the RDR. If no parity is selected, then both the transmitter parity generator output and the receiver parity check results are inhibited.

Interrupt Request (\overline{IRQ}), Bit 7 — The \overline{IRQ} bit indicates the state of the \overline{IRQ} output. Any interrupt condition with its applicable enable will be indicated in this status bit. Anytime the \overline{IRQ} output is low the \overline{IRQ} bit will be high to indicate the interrupt or service request status. \overline{IRQ} is cleared by a read operation to the Receive Data Register or a write operation to the Transmt Data Register.