

```

d
d
d
ddd d   y   y   eeee   r rrr
d   dd  y   y   e   e   rr   r
d   d   y   y   eeeee  r
d   d   y   y   e       r
d   dd  y   yy  e   e   r
ddd d   yyy y   eeee   r
      y   y
      yyyy

```

```

      ll
      l
      l
r rrr   eeee   l   oooo   cccc   ssss
rr   r   e   e   l   o   o   c   c   s   s
r       eeeee  l   o   o   c       ss
r       e       l   o   o   c       ss
r       e   e   l   o   o   c   c   s   s
r       eeee   ll   oooo   cccc   ssss

```

(BIOS LISTING)

```

      i
u   u   n nnn   ii   x   x
u   u   nn   n   i   x   x
u   u   n   n   i   xx
u   u   n   n   i   xx
u   uu   n   n   i   x   x
uuu u   n   n   iii  x   x

```

Job: reloc.s  
Date: Tue Jul 9 12:43:17 1985

\*---- Conditional assembly equates:

```
rom          =          0          ; generate ROMable system
ram          =          1          ; generate loadable system

usa          =          0          ; for USA
germany     =          1          ; for Deutschland
france      =          2          ; for France
uk          =          3          ; for Britain
```

\*---- Version information:

```
version     equ          $0100      ; system version number (VVR)
date       equ          $06141985   ; date system was built
```

\*---- Conditional assembly switches:

```
systype     =          ram          ; type of system
country     =          usa          ; country
```

\*\*+

\* Parameters for RAM and ROM systems;  
 \* Adjust these equates with system size and location changes.  
 \* 'endos' points to the last bit of RAM the system uses (plus one).  
 \* 'the\_magic' points to a parameter block containing information  
 \* about the location of the AES, and how much RAM it uses.

\*

\*-

```
ifeq systype-rom          * For ROM:
endos                     equ          $5000      ; end of OS memory usage
the_magic                 equ          $fefff4    ; -> magic stuff (top of the ROM)
endc
```

```
ifeq systype-ram          * For RAM:
endos                     equ          $19c00     ; end of OS memory usage
the_magic                 equ          endos-$c   ; -> magic stuff (at the top of the OS)
endc
```

```
*-----
*
*      ST Series BIOS
*      (C)1985 Atari Corp.
*      All Rights Reserved.
*
*      System Initialization
*      ROM header
*      RAM variable equates
*
*----- Edit history:
*
* (lost history)          [From Oct '84, incarnations as part of
*                          the debugger cart, and the CP/M-68K BIOS]
```

```

* 02-Feb-1985 lmd      Converted from CP/M BIOS.
* 24-Feb-1985 lmd      I munge this file every day.
* 25-Feb-1985 lmd      Added _cmdload flag (load COMMAND.COM from disk):
* 25-Feb-1985 lmd      Changed _get_mpb, added "hard_reset" conditional:
*                          assembly switch.
* 27-Feb-1985 lmd      Added hard disk hooks.
* 1-Mar-1985 lmd       Added _supstk (from GEMDOS)
* 1-Mar-1985 lmd       Added _mediach BIOS function
* 4-Mar-1985 lmd       Added 'cartscan' and associated calls to it
* 7-Mar-1985 lmd       Integrate new character I/O
* 8-Mar-1985 lmd       Critical error handler, random trap hacking
* 9-Mar-1985 lmd       BIOS traps are re-entrant to 3 levels, and
*                          callable from user mode.
* 10-Mar-1985 lmd      Consolidated BSS, installed "extended" traps
* 15-Mar-1985 lmd      Re-integration with RBIOS. 200hz raw sysTick
* 16-Mar-1985 lmd      Warmstart banished. Procdump on uncaught traps
* 27-Mar-1985 lmd      Added "_scremp" trap#14 function
* 27-Mar-1985 lmd      Added "getshift" trap#13 function
* 8-Apr-1985 lmd       Re-integration with serial code
* 8-Apr-1985 lmd       Moved floppy/FIFO lock to public basepage
* 9-Apr-1985 lmd       get/set shift bits (trap #13, $0b)
* 9-Apr-1985 lmd       Added _dskbufp -> _diskbuf
* 13-Apr-1985 lmd      Added _autopath (autoexec path pointer)
* 15-Apr-1985 lmd      Happy IRS day.
* 15-Apr-1985 lmd      Moved _vblqueue to low memory (thank Ghu!)
* 17-Apr-1985 lmd      Added _prtblk primitive
* 17-Apr-1985 lmd      Hblank (vector interrupt #2) hacks caller's IPL
*                          to 3.
* 1-May-1985 lmd       Added supexec() & wvbl() extended functions
* 8-May-1985 lmd       RAM-loaded system wired 'memcntrl' to 512K;
*                          now it takes whatever the boot ROMs give it.
* 9-May-1985 lmd       Added _asc_out to character device table.
* 15-May-1985 lmd      Moved _cursconf to escape module.
* 23-May-1985 lmd      Added 'magic' parameter -- makes it easy to
*                          blow the GEM AES away. Huzzah!
* 24-May-1985 lmd      Added mushroom cloud display on processor
*                          exception, out of sheer boredom.
* 28-May-1985 lmd      Added new _prtblk. Screen dump understands high:
*                          quality print mode.

```

-----  
text

```

*----- Exports:
.globl endosbss          ; (informative) end OS bss
.globl _dumpflag, _prtcnt ; screen dump flag (& its alias)
.globl _prtabt          ; printer abort flag
.globl flock           ; floppy/FIFO lock
.globl sshiftmd        ; shiftmd shadow
.globl etv_timer       ; timer handoff vector
.globl _membot         ; (best guess) bottom of TPA

```

```

.globl _memtop ; top of TPA (first unusable byte)
.globl _timr_ms ; system timer calibration (in ms)
.globl _vblqueue ; vbl queue
.globl _vbclock ; count of unblocked vblank interrupts
.globl _frclock ; count of all vblank interrupts
.globl _v_bas_ad ; video base addr
.globl con_state ; state of conout() parser
.globl save_row ; saved row# for cursor X-Y addressing
.globl _buf1 ; two buffer-list headers
.globl _bootdev ; default boot device [0]
.globl _cmdload ; nonzero: exec shell on boot device
.globl conterm ; terminal emulator bitSwitches
.globl _nflops ; "Hey! Clams got floppies!"
.globl _critic ; critical error handler binding for C
.globl _hz_200 ; 200hz raw system timer tick
.globl seekrate ; default floppy seek rate
.globl _fverify ; nonzero: verify on floppy write
.globl _drvbits ; long bitmap of block devices
.globl conterm ; console/vt52 bits

.globl _hinit ; go through hdv_init
.globl _dskboot ; boot from somewhere
.globl _fastcpy ; fast copy (for unaligned DMA)

```

\*----- Imports:

```

.globl _cursconf ; cursor configuration
.globl _asc_out ; "raw" character output to screen
.globl pconfig ; printer configuration word
.globl _prtblk ; _prtblk primitive
.globl esce ; {escape.s} "hard" turn on cursor
.globl _osi ; initialize OS
.globl initmfp ; init character I/O
.globl esc_init ; init glass tty
.globl initmous ; mouse vector init
.globl _mediach ; media change inquiry
.globl _proto_bt ; prototype boot sector
.globl _flopwr ; write sector(s)
.globl _flopver ; verify sector(s)
.globl _flopfmt ; format track
.globl _rand ; generate random number

.globl auxistat ; input-status
.globl constat
.globl midstat
.globl _lstin ; input
.globl auxin
.globl conin
.globl midin
.globl _lstostat ; output-status
.globl _auxostat
.globl conoutst
.globl ikbdost

```

```

.globl midiost
.globl _lstout      ; output
.globl _auxout
.globl conout
.globl midiwc
.globl ikbdwc

.globl midiws      ; write MIDI string
.globl mfpint      ; setup MFP interrupt
.globl iorec       ; configure I/O record
.globl rsconf      ; configure RS-232
.globl keytrans    ; store keyboard translation
.globl settime     ; set ikbd date
.globl gettime     ; get ikbd date
.globl bioskeys    ; reset keyboard to power-up defaults
.globl ikbdws      ; write string to ikbd

.globl line1010    ; line 1010 handler
.globl kbshift     ; keyboard shift status

.globl jdisint
.globl jenabint
.globl giaccess
.globl offgibit
.globl ongibit
.globl xbtimer
.globl dosound
.globl setprt
.globl kbrate
.globl ikbdvecs

.globl _supstk     ; GEMDOS super stack
.globl _diskbuf    ; disk buffer

.globl _getdsb     ; return disk's state pointer
.globl _boot       ; load and check boot sector
.globl _rwabs      ; read/write on block dev
.globl _getbpb     ; get bios parameter block
.globl _dskinit    ; disk system initialization
.globl _flopvbl    ; floppy vblank handler
.globl _floprd     ; read sector(s)
.globl blink       ; cursor blink (vblank)

```

\*-----

\* Default System Parameters.

\* Do not change these much.

\*-----

```

df_seek      equ      $0003      ; default seek-rate (3ms)
dnpvbls     equ      8          ; default number of vbl queue entries
nlevels      equ      5          ; max # recursive BIOS calls

```

savsiz equ 23 ; size (.W) of BIOS trap save-context

\*----- Magic Numbers

resmagic equ \$31415926 ; validates 'resvalid'  
 diaggmagic equ \$fa52235f ; validate diagnostic cartridge  
 apmagic equ \$abcdef42 ; validate application cartridge  
 memmagic equ \$752019f3 ; validates 'memvalid'  
 memmag2 equ \$237698aa ; validates 'memval2'  
 bootmagic equ \$1234 ; magic checksum for boot sector

\*----- Data Structures

\*---- Floppy state variables:

dfused equ 0 ; nonzero: floppy has been accessed  
 dcurtrack equ dfused+2 ; current track#  
 dseekrt equ dcurtrack+2 ; floppy's seek-rate

\*---- Cartridge application:

ca\_next equ 0 ; (.L) link to next application  
 ca\_flags equ 4 ; (.B) run flags (MSB of ca\_init)  
 ca\_init equ 4 ; (.L) pointer to init code  
 ca\_run equ 8 ; (.L) pointer to run code  
 ca\_time equ \$c ; (.W) DOS-format creation time  
 ca\_date equ \$e ; (.W) DOS-format creation date  
 ca\_size equ \$10 ; (.L) application size  
 ca\_name equ \$14 ; application name (NNNNNNNN.EEE\0)

\*----- Ram configuration equates

bank1 equ \$200000 ; address of 2Mb second bank  
 twomb equ 1024\*2048 ; two megabytes  
 one28 equ \$20000 ; 128K

\*----- Hardware Equates

\*----- ROM addresses:

romstart equ \$fa0000 ; lowest ROM address  
 romend equ \$ff0000 ; first byte not in ROM  
 cartbase equ \$fa0000 ; start of cartridge ROM  
 cartsiz equ \$20000 ; size of cartridge (128K)

\*---- Shifter:

memconf equ \$ffff8001 ; memory controller  
 syncmode equ \$ffff820a ; video sync mode

```

dbasel      equ      $ffff8203      ; display base low
dbaseh      equ      $ffff8201      ; display base high
color0      equ      $ffff8240      ; color palette #0
shiftmd     equ      $ffff8260      ; video shift mode (resolution)

```

\*--- DMA chip:

```

diskctl     equ      $ffff8604      ; disk controller data access
fifo        equ      $ffff8606      ; DMA mode control
dmahigh     equ      $ffff8609      ; DMA base high
dmamid      equ      $ffff860b      ; DMA base medium
dmalow      equ      $ffff860d      ; DMA base low

```

\*--- 1770 select values:

```

cmdreg      equ      $80             ; 1770/FIFO command register select
trkreg      equ      $82             ; 1770/FIFO track register select
secreg      equ      $84             ; 1770/FIFO sector register select
datareg     equ      $86             ; 1770/FIFO data register select

```

\*--- GI ("psg") sound chip:

```

giselect    equ      $ffff8800      ; (W) sound chip register select
giread      equ      $ffff8800      ; (R) sound chip read-data
giwrite     equ      $ffff8802      ; (W) sound chip write-data
gimixer     equ      7              ; I/O control/volume control register
giporta     equ      $e             ; GI register# for I/O port A
giportb     equ      $f             ; Centronics output register

```

\*----- Bits in "giporta":

```

xrts        equ      8              ; RTS output
dtr         equ      $10            ; DTR output
strobe      equ      $20            ; Centronics strobe output
gpo         equ      $40            ; "general purpose" output

```

\*--- 68901 ("mfp") sticky chip:

```

mfp         equ      $fffffa00      ; mfp base
gpip        equ      mfp+1          ; general purpose I/O
aer         equ      mfp+3          ; active edge reg
ddr         equ      mfp+5          ; data direction reg
iera        equ      mfp+7          ; interrupt enable A & B
ierb        equ      mfp+9          ; interrupt pending A & B
ipra        equ      mfp+$b         ; interrupt pending A & B
iprb        equ      mfp+$d         ; interrupt pending A & B
isra        equ      mfp+$f         ; interrupt inService A & B
isrb        equ      mfp+$11        ; interrupt pending A & B
imra        equ      mfp+$13        ; interrupt mask A & B
imrb        equ      mfp+$15        ; interrupt mask A & B
vr          equ      mfp+$17        ; interrupt vector base
tacr        equ      mfp+$19        ; timer A control
tbc         equ      mfp+$1b        ; timer B control
tcdr        equ      mfp+$1d        ; timer C & D control
tadr        equ      mfp+$1f        ; timer A data
tbd         equ      mfp+$21        ; timer B data
tcd         equ      mfp+$23        ; timer C data
tdd         equ      mfp+$25        ; timer D data
scr         equ      mfp+$27        ; sync char
ucr         equ      mfp+$29        ; USART control reg
rst         equ      mfp+$2b        ; receiver status

```

```

tsr      equ      mfp+$2d      ; transmit status
udr      equ      mfp+$2f      ; USART data

*--- 6850 registers:
keyctl   equ      $fffffc00    ; keyboard ACIA control
keybd    equ      keyctl+2     ; keyboard data
midictl  equ      $fffffc06    ; MIDI ACIA control
midi     equ      midictl+2    ; MIDI data

```

```

**
* Dump area
* Processor state is dumped here after an uncaught trap
*

```

```

*-
proc_lives    equ      $380      ; lives if $12345678
proc_regs     equ      proc_lives+4 ; D0-D7/A0-A7
proc_pc       equ      proc_regs+$40 ; PC
proc_usp      equ      proc_pc+4  ; USP
proc_stk      equ      proc_usp+4 ; six words of stack

```

```

**
* Base of system BSS.
* Starts at $400, just above interrupt vector RAM.
*
* These will never change in future releases of the system.
*
*-

```

bss

```

* "extended" trap vectors:
etv_timer:    ds.l    1      ; (400) vector for timer interrupt chain
etv_critc:    ds.l    1      ; (404) vector for critical error chain
etv_term:     ds.l    1      ; (408) vector for process terminate
etv_xtra:     ds.l    5      ; (40c) 5 reserved vectors

memvalid:     ds.l    1      ; (420) indicates system state on RESET
memcntl:     ds.w    1      ; (424) mem controller config nibble
resvalid:     ds.l    1      ; (426) validates 'resvector'
resvector:    ds.l    1      ; (42a) [RESET] bailout vector
phystop:     ds.l    1      ; (42e) physical top of RAM
_membot:     ds.l    1      ; (432) bottom of available memory;
_memtop:     ds.l    1      ; (436) top of available memory;
memval2:     ds.l    1      ; (43a) validates 'memcntl' and 'memconf'
flock:       ds.w    1      ; (43e) floppy disk/FIFO lock variable
seekrate:    ds.w    1      ; (440) default floppy seek rate
_timr_ms:    ds.w    1      ; (442) system timer calibration (in ms)
_fverify:    ds.w    1      ; (444) nonzero: verify on floppy write
_bootdev:    ds.w    1      ; (446) default boot device
palmode:     ds.w    1      ; (448) nonzero ==> PAL mode
defshiftmd:  ds.w    1      ; (44a) default video rez (first byte)

```

```

sshiftmd:      ds.w      1      ; (44c) shadow for 'shiftmd' register
_v_bas_ad:    ds.l      1      ; (44e) pointer to base of screen memory
vblsem:       ds.w      1      ; (452) semaphore to enforce mutex in vbl
nvbls:        ds.w      1      ; (454) number of deferred vectors
_vblqueue:    ds.l      1      ; (456) pointer to vector of deferred vfuncs
colorptr:     ds.l      1      ; (45a) pointer to palette setup (or NULL)
screenpt:     ds.l      1      ; (45e) pointer to screen base setup (NULL)
_vbclock:     ds.l      1      ; (462) count of unblocked vblanks
_frclock:     ds.l      1      ; (466) count of every vblank

hdv_init:     ds.l      1      ; (46a) hard disk initialization
swv_vec:      ds.l      1      ; (46e) video change-resolution bailout
hdv_bpb:      ds.l      1      ; (472) disk "get BPB"
hdv_rw:       ds.l      1      ; (476) disk read/write
hdv_boot:     ds.l      1      ; (47a) disk "get boot sector"
hdv_mediach:  ds.l      1      ; (47e) disk media change detect

_cmdload:     ds.w      1      ; (482) nonzero: load COMMAND.COM from boot
conterm:      ds.b      1      ; (484) console/vt52 bitSwitches (%0..%2)
              ds.b      1      ; (485) [unused, reserved]

trpi4ret:     ds.l      1      ; (486) saved return addr for _trap14
criticret:    ds.l      1      ; (48a) saved return addr for _critic
themd:        ds.l      4      ; (48e) memory descriptor (MD)
_____md:    ds.w      2      ; (49e) (more MD)
savptr:       ds.l      1      ; (4a2) pointer to register save area

_nflops:      ds.w      1      ; (4a6) number of disks attached (0, 1+)
con_state:    ds.l      1      ; (4a8) state of conout() parser
save_row:     ds.w      1      ; (4ac) saved row# for cursor X-Y addressing
sav_context:  ds.l      1      ; (4ae) pointer to saved processor context
_buf1:        ds.l      2      ; (4b2) two buffer-list headers
_hz_200:      ds.l      1      ; (4ba) 200hz raw system timer tick
              ds.l      1      ; (4be) reserved for future use
_drvbits:     ds.l      1      ; (4c2) bit vector of "live" block devices
_dskbufp:     ds.l      1      ; (4c6) pointer to common disk buffer
_autopath:    ds.l      1      ; (4ca) pointer to autoexec path (or NULL)
_vbl_list:    ds.l      8      ; (4ce) initial _vblqueue (to $4ee)
_prtcnt:      *         ; (4ee) screen-dump flag alias
_dumpflg:     ds.w      1      ; (4ee) screen-dump flag
_prtabt:      ds.w      1      ; (4f0) printer abort flag
_sysbase:     ds.l      1      ; (4f2) -> base of OS
_shell_p:     ds.l      1      ; (4f6) -> global shell info
end_os:       ds.l      1      ; (4fa) -> end of OS memory usage
exec_os:      ds.l      1      ; (5fe) -> address of shell to exec on startup

```

\* Start of no-man's land (locations beyond this point subject to change):

```

the_env:      ds.b      20      ; space for a small environment string
savarea:      ds.w      savsiz*nlevels ; register save area
savend:       *         ; * end of register sav area
endosbss:    *         ; * end of "base" BSS

```

```

        .text
**
* System startup parameters
*
* In ROM, these are found at $FC0000.
* In any event, they are found at *(_st_begos).
*
*--
ostext:      bra.s   reseth           ; ($0) branch to reset handler
             dc.w   version         ; ($2) OS version number
             dc.l   reseth           ; ($4) -> system reset handler
os_beg:      dc.l   ostext           ; ($8) -> base of OS
os_end:      dc.l   endos            ; ($c) -> end of OS memory usage
os_exec:     dc.l   reseth           ; ($10) -> default shell
os_magic:    dc.l   the_magic        ; ($14) -> GEM magic (or NULL)
os_date:     dc.l   date             ; ($18) date the system was built
os_conf:     dc.w   0                ; ($1a) configuration bits

```

ifeq systype--rom

```

**
* [ROM based system]
* reseth - System reset handler
*
* Gains control of the system upon power-up reset,
* or when the RESET button is pressed,
* or after a really messy system crash.
*
*--

```

```

reseth:      move.w  #$2700, sr        ; super mode, no interrupts
             reset                   ; reset hardware
endc

```

ifeq systype--ram

```

**
* [RAM based system]
* reseth - Startup the system
*
* Gains control from the boot loader
* as soon as the OS has been relocated.
*
*--

```

```

reseth:      move.w  #$2700, sr        ; super mode, no interrupts
endc

```

ifeq systype--rom

```

**
* [ROM based system]
* Check for a diagnostic cartridge;
* if one is inserted, load a return address
* into A6 and jump to the cart's entry point.

```

```

*
*--
    cmp.l    #diaggmagic,cartridge    ; is the magic number there?
    bne     reset1                    ; (no)
    lea     reset1(pc),a6              ; a6 -> return address
    jmp     cartridge+4                ; execute diagnostic cartridge
endc

```

```

ifeq systype-rom

```

```

*+
* [ROM based system]
* If this is a warm reset, setup the memory
* controller configuration register so that
* the reset-bailout vector has something to
* stand on ....
*

```

```

*--
reset1:
    lea     ret_1(pc),a6                ; load return addr
    bra     val_memval                  ; check memory configuration validity
ret_1:   bne     reset2                  ; (invalid -- don't set anything up)
        move.b memcntl,memconf         ; initialize memory controller
endc

```

```

ifeq systype-rom

```

```

*+
* [ROM based system]
* RESET bailout vector check.
* Check to make sure we have a clean, well-bred
* bailout vector. The high byte must be zero,
* it must be even, and cannot be entirely zero.
*

```

```

*--
reset2:  clr.l    a5                      ; quick zeropage
        cmp.l    #resmagic,resvalid(a5) ; is resvalid the magic number?
        bne     reset3                    ; (no)
        move.l   resvector(a5),d0        ; d0 = reset bailout vector
        tst.b   resvector(a5)           ; bits 24..31 must be zero
        bne     reset3                    ; (they aren't, so punt)
        btst   #0,d0                     ; the vector must be even
        bne     reset3                    ; (it isn't, so punt)
        move.l   d0,a0                    ; a0 -> reset handler
        lea     reset2(pc),a6            ; a6 -> return address
        jmp     (a0)                     ; execute reset bailout
endc

```

```

ifeq systype-ram

```

```

*+
* [RAM based system]
* Setup the reset-bailout vector to point
* to our own system-reset handler.
*

```

```

*
*--

```

```

        move.l  reseth,resvector
        move.l  #resmagic,resvalid
    endc

**
* Initialize PSG output ports.
* Make ports A and B output-only;
* initialize floppy select lines (so
* that none are selected).
*
*--
reset3: lea    giselect,a0          ; a0 -> giselect, giwrite-2
        move.b #7,(a0)             ; set porta & portb to output
        move.b #$c0,2(a0)
        move.b #$e,(a0)           ; deselect disks
        move.b #7,2(a0)

**
* Determine 50hz or 60hz.
* The hardware RESETs to 60hz. Check a bit in the
* ROM configuration byte to see if we have to twiddle
* the hardware into 50hz mode.
*
*--
        btst.b #0,os_conf(pc)      ; check bit: configured for 50hz?
        beq   notpal              ; (nope -- we're good ol' NTSC)
        move.b #$02,syncmode      ; yes -- twiddle to 50hz
notpal:

**
* Initialize palette registers to
* their default values.
*
*--
        lea    color0,a1           ; a1 -> hardware reg
        move.w #16-1,d0           ; setup 16 colors
        lea    colors(pc),a0      ; a0 -> table of default colors
sysic1: move.w (a0)+,(a1)+        ; copy palette assignment
        dbra  d0,sysic1          ; (loop for more colors)

    ifeq systype-rom
**
* On a ROM system, put the screen (temporarily)
* at $10000, so the icon-drawing routines won't
* blow away any system variables.
*
*--
        move.b #$01,dbaseh        ; set high ptr
        move.b #$00,dbasel        ; set low ptr
    endc

```

```

ifeq systype-rom
*+
* [ROM based system]
* Determine how much memory there is, and initialize
* the memory controller configuration register.
*
* Algorithm from Jim Tittsler, Art Morgan, et al.
* but shamelessly modified for the hell of it.
*
* The bottom 1K of memory is only touched on the first RESET,
* to size memory and setup the memory controller. The first 1K
* is never cleared.
*
*-
        clr.l    a5                ; quick zeropage
        move.b   memcntl(a5),d6    ; d6 = memory controller configuration
        move.l   phystop(a5),d5    ; d5 -> (possible) top of physical mem
        lea     ret_2(pc),a6       ; load return address
        bra     val_memval        ; get memory controller validation
ret_2:   beq     reset4           ; already sized -- don't size or test

*--- init vars + hardware:
        clr.w    d6                ; d6 = configuration byte
        clr.l    d5                ; d5 -> physical top of RAM
        move.b   #$0a,memconf     ; setup controller for 2Mb/2Mb

*--- write test-pattern to both banks:
        move.w   #8,a0             ; a0 -> bank0 (skip ROM shadow)
        lea     bank1+8,a1        ; a1 -> bank1
        clr.w    d0                ; d0 = start of pattern
fmem1:   move.w   d0,(a0)+         ; write to bank 0
        move.w   d0,(a1)+         ; write to bank 1
        add.w   #$fa54,d0         ; bump pattern with a magic number
        cmp.l   #$200,a0         ; filled $200 bytes?
        bne     fmem1            ; (no, loop)

*+
* Determine size of both banks
* from test-pattern signatures:
*-
        move.l   #bank1,d1        ; d1 = bank offset (start with bank 1)
mem1:    lsr.w   #2,d6            ; (shift bank1's size into position)
        move.w   #$208,a0         ; pattern matches at $208?
        lea     memr1(pc),a5      ; a5 -> return addr
        bra     memchk           ; (check the pattern)
memr1:   beq     mem2            ; yes -- 128K
        move.w   #$408,a0         ; pattern matches at $408?
        lea     memr2(pc),a5      ; a5 -> return addr
        bra     memchk           ; (check it)
memr2:   beq     mem3            ; yes -- 512K
        move.w   #8,a0            ; pattern matches at $8?
        lea     memr3(pc),a5      ; a5 -> return addr
        bra     memchk           ; (attempt match)
memr3:   bne     mem4            ; no -- nothing in this bank
        add.l   #bank1-$80000-$20000,d5 ; adjust size for 2M bank
        addq.w  #4,d6            ; adjust config byte for 2M

```

```

mem3:   add.l   #$80000-$20000, d5      ; adjust size for 512K bank
        addq.w  #4, d6                 ; adjust config byte for 512K
mem2:   add.l   #$20000, d5           ; adjust size for 128K bank
mem4:   sub.l   #bank1, d1            ; decrement bank number
        beq     mem1                  ; repeat check for bank 0
cold3:  move.b  d6, memconf           ; setup memory controller
        endc

```

```

ifeq systype-rom
**
* [ROM based system]
* Clear memory from $400 to 'd5' (phystop).
*
*-
        move.l  d5, a0                 ; start at the end
        move.l  #$400, d4              ; where to end
        movem.l zeros(pc), d0-d3     ; get some cheap zeros
clm_1:  movem.l d0-d3, -(a0)          ; ... work our way back
        cmp.l   d4, a0                ; done?
        bne    clm_1                 ; (loop for more bytes)
        endc

```

```

ifeq systype-rom
**
* Indicate that memory has successfully
* been sized and tested. Set two variables
* to magic values ...
*
*-
        clr.l   a5                    ; cheap zeropage
        move.b  d6, memcntl(a5)       ; save configuration byte
        move.l  d5, phystop(a5)       ; save physical top-of-memory
        move.l  #memmagic, memval1(a5) ; indicate memory was configured
        move.l  #memmag2, memval2(a5) ; ditto (paranoia variable)
        endc

```

```

reset4:
        clr.l   a5                    ; quick zeropage

```

```

ifeq systype-rom
**
* [ROM system]
* Clear bottom 64K (or so) of memory.
* (this is sufficient for GEMDOS and the AES,
* which require their BSS to be zero when
* they are started up).
*
*-
        move.w  #endosbss, a0         ; a0 -> start
        move.l  #$10000, a1          ; a1 -> end
        endc

```

```

ifeq systype-ram
**
* [RAM loaded system]
* Clear OS bss (from 'endosbss' to 'ostext')
*
*-
        move.w  #endosbss,a0           ; a0 -> start
        move.w  #ostext,a1            ; a1 -> end
endc

*--- common code to clear memory:
        moveq   #0,d0                 ; quick zero
clrml:  move.w  d0,(a0)+              ; clobber a word
        cmp.l   a0,a1                ; at end?
        bne    clrml_1               ; (no -- loop for more words)

**
* Setup display base,
* clear display memory.
*
*-
        move.l  phystop(a5),a0        ; video_base = phystop - 0x8000
        sub.l  #$8000,a0
        move.l  a0,_v_bas_ad(a5)
        move.b  _v_bas_ad+1(a5),dbaseh ; load high addr
        move.b  _v_bas_ad+2(a5),dbasel ; load low (really, medium) addr
        move.w  #$800-1,d1            ; d1 = # 16-byte chunks to zero
clrml_2: move.l  d0,(a0)+             ; zero a longword
        dbra   d1,clrml_2            ; (loop for more longwords)

**
* Initialize all kinds of OS variables
*
*-

*--- OS parameters:
        move.l  os_magic(pc),a0       ; get pointer to magic
        cmp.l  #$87654321,(a0)       ; is the magic there?
        beq    usem                   ; yes -- use numbers there
        lea    os_end-4(pc),a0        ; no, use default numbers
usem:   move.l  4(a0),end_os           ; init end-of-OS pointer
        move.l  8(a0),exec_os         ; init default-shell pointer

*--- Disk vectors:
        move.l  #_dskinit,hdv_init(a5) ; initialization
        move.l  #_rwabs,hdv_rw(a5)     ; read/write absolute sectors
        move.l  #_getbpb,hdv_bpb(a5)   ; get BIOS parameter block
        move.l  #_mediach,hdv_mediach(a5) ; media change inquiry

```

```

        move.l  #_boot,hdv_boot(a5)      ; boot-from-device

*--- Randoms:
        move.l  _v_bas_ad(a5),_memtop(a5) ; _memtop = _v_bas_ad
        move.l  end_os(a5),_membot(a5)   ; set bottom of memory (for DOS)
        lea     _supstk+2048,sp           ; setup supervisor stack
        move.w  #dntvbls,nvbls(a5)       ; default number of vbl queue entries
        st      _fverify(a5)            ; enable write-verify
        move.w  #df_seek,seekrate(a5)    ; set default seek-rate
        move.l  #_diskbuf,_dskbufp(a5)   ; setup pointer to disk buffer
        move.w  #-1,_prtcnt(a5)          ; initialize print-count
        move.l  #ostext,_sysbase(a5)     ; -> base of OS
        move.l  #savend,savptr(a5)       ; register-save pointer for traps 13&14
        move.l  #_rts,swv_vec(a5)        ; ignore monitor changes for now

**
* Initialize interrupt vectors
*
* If a diagnostic cartridge is inserted, the "random" vectors
* (for Bus Error, Address Error, and so on) are left alone.
*
* Otherwise, the random vectors are pointed to the system critical
* error handler (_term). The high byte of the vector (bits 24..31)
* contains the exception number. [Yes, this will lose on a 68020.]
*
* Trap 2 and Divide-by-zero are pointed at an RTE.
*
* The HBLANK, VBLANK, line 1010, [someday: line 1111], trap 13, trap 14,
* and "extended" trap vectors are initialized appropriately.
*
*--
        lea     _rte(pc),a3               ; a3 -> handy RTE
        lea     _rts(pc),a4               ; a4 -> handy RTS

*--- diagnostic cartridge check:
        cmp.l   #diagmagic,carbbase     ; check cartridge magic
        beq     sei2                      ; (it's there -- leave vectors alone)

*--- setup 62 vectors:
        lea     _term(pc),a1              ; a1 -> "terminate process" handler
        add.l   #$02000000,a1             ; a1 += vector number (high byte)
        lea     8,a0                      ; a0 -> interrupt RAM
        move.w  #64-2-1,d0                 ; d0 = count
sei1:    move.l  a1,(a0)+                  ; write vector
        add.l   #$01000000,a1             ; bump vector number in bits 24..31
        dbra   d0,sei1                    ; (loop to write more vectors)
        move.l  a3,$14                     ; divide-by-zero vector -> rte

*--- install OS interrupt vectors:
sei2:    move.l  #vbl,$70(a5)              ; vblank handler
        move.l  #hbl,$68(a5)              ; hblank handler
        move.l  a3,$88(a5)                ; (empty) trap#2 handler
        move.l  #trp13h,$b4(a5)           ; trap #13 handler
        move.l  #trp14h,$b8(a5)           ; trap #14 handler
        move.l  #line1010,$28(a5)         ; line 1010 handler

```

```

    move.l a4,etv_timer(a5)      ; default timer-tick vector -> rts
    move.l #_critich,etv_critic(a5) ; default critical error handler
    move.l a4,etv_term(a5)      ; default terminate vector -> rts

```

```

**
* Setup the vblank deferred vector list.
* (This data structure is ugly,
* but we seem to be stuck with it).
*
*-

```

```

    lea    _vbl_list(a5),a0      ; a0 -> default list of vbl locs
    move.l a0,_vblqueue(a5)     ; install ptr to them
    move.w #dnvb1s-1,d0         ; clear vbl vectors
avbl:    clr.l (a0)+             ; one at a time
    dbra  d0,avbl

```

```

**
* "The other half" of the BIOS handles character I/O;
* call its initialization hook.
* (It can "never fail". This will get interesting
* if we ever do a detachable keyboard ....)
*
*-

```

```

    bsr    initmfp

```

```

**
* Fire up %%2 cartridges
*
*-

```

```

    moveq  #2,d0                ; bit# = 2
    bsr    cartscan            ; execute cartridge aps

```

```

**
* Initialize screen resolution,
* kludge color lookup RAM for medium-rez (if we're in it).
*
*-

```

```

    clr.l  a5                  ; quick zero page (again)
    bsr    wvbl                ; flush pending VBI
    bsr    wvbl                ; wait for next VBI
    move.b #2,d0               ; assume high-rez monitor
    btst.b #7,gpip             ; test "HighRez" panic input
    beq    setvb1              ; (set high-resolution)
    move.b defshiftmd(a5),d0   ; get default color mode
    cmp.b  #2,d0               ; if(mode >= 2) mode = 0
    blt    setvb1
    clr.b  d0
setvb1:  move.b d0,sshiftmd(a5) ; set rez shadow
    move.b d0,shiftmd          ; set rez hardware register

```

```

*--- if in medium rez, hack color3 := color15 (for GSX)
    cmp.b  #1,d0              ; in medium rez?

```

```

        bne     setvb2          ; (no, so don't fiddle)
        move.w  color0+$1e,color0+6 ; copy color 15 to color 3

setvb2: jsr     esc_init        ; clear screen, initialize cursor
        move.l  #reseth,swv_vec(a5) ; RESET system on monitor change
        move.w  #1,vblsem      ; enable vblank processing

**
* [1] Fire up %ZO cartridges;
* [2] Enable interrupts;
* [3] Fire up %Z1 cartridges
*
*--
        clr.w   d0              ; magic bit# = 0
        bsr    cartscan        ; execute cartridge aps
        move.w  #$2300,sr      ; go to IPL 3
        moveq   #1,d0          ; magic bit# = 1
        bsr    cartscan        ; execute cartridge aps

**
* Load shell (if _cmdload is nonzero)
* or execute GEM in ROM
*
*--
        bsr    _osi            ; initialize DOS
        bsr    _dskboot        ; attempt to boot from disk
        tst.w  _cmdload        ; load shell from disk?
        beq    st_1            ; (no -- execute GEM in ROM)

        bsr    esce           ; turn on cursor
        bsr    _auto          ; do auto-exec

        pea   nullenv(pc)     ; null enviroment string
        pea   nullenv(pc)     ; null argument string
        pea   cmdname(pc)     ; push shell filename
        clr.w  -(sp)           ; load-and-go flavor of exec
        bra   st_x            ; exec shell ("never return")

*--- bring up GEM:
st_1:   bsr    _auto          ; do auto-exec

*--- kludge up an enviroment string:
        lea   orig_env(pc),a0 ; a0 -> original enviroment string
        move.w #the_env,a1    ; a1 -> place to put it
st_2:   cmp.b  #'#',(a0)      ; look for drive# character
        bne   st_3            ; (not it)
        move.l a1,a2          ; a2 -> place to put drive#
st_3:   move.b (a0)+,(a1)+    ; copy a byte
        bpl   st_2            ; loop while not end-of-string

        move.b _bootdev,d0    ; compute drive#, and shove it
        add.b  #'A',d0        ; into the env string at the
        move.b d0,(a2)        ; appropriate spot

```

\* kludge up an enviroment string:

```

    pea    the_env          ; push address of enviroment string
    pea    nullenv         ; no arguments

```

\* ifeq systype-ram

```

*     pea    gemname(pc)    ; exec GEM.PRG
*     clr.w  -(sp)         ; load-and-go

```

\* endc

\* ifeq ramloaded

```

    pea    nullenv(pc)     ; null shell name (in ROM, after all)
    move.w #5, -(sp)       ; createPSP flavor of exec
    move.w #$4b, -(sp)     ; exec function#
    trap   #1              ; get pointer to PSP
    add.w  #14, sp         ; (clean up cruft)
    move.l d0, a0          ; a0 -> PSP
    move.l exec_os, B(a0)  ; stuff saddr of GEM in PSP

```

```

    pea    the_env         ; our enviroment string
    move.l a0, -(sp)       ; push addr of PSP
    pea    nullenv(pc)     ; null filename
    move.w #4, -(sp)       ; just-go

```

\* endc

```

st_x:  move.w #$4b, -(sp)  ; function = exec
        trap   #1          ; do it
        add.w  #14, sp     ; cleanup stack

```

\*\*

\* When startup fails (or if the exec returns,  
 \* which "cannot happen") fake a system reset:

```

*-
    jmp    reseth          ; back to the beginning...

```

\*\*

\* Default enviroment string

\* Cannot be more than 20 chars long without modifying

\* the declaration for the\_env;

\* Any char >= \$80 terminates the string (and is included in it)

\* The last '#' character is replaced by the boot drive's name (A, B, ...)

\*-

```

orig_env: dc.b  "PATH=", 0    ; default pathname
           dc.b  ":\", 0     ; is the boot device
           dc.b  0           ; terminate env string
           dc.b  $ff        ; end of env string (for our copy)

```

```

cmdname: dc.b  "COMMAND.PRG", 0 ; shell name
gemname: dc.b  "GEM.PRG"        ; desktop name
nullenv: dc.b  0, 0             ; null string (and enviroment)
even

```

\*\*

```

* _dskboot - boot (or return diagnostics)
* Passed:      nothing
* Returns:     D0.W = error number (if nonzero)
*--
_dskboot:
    moveq    #3,d0                ; %%3 ap cart
    bsr     cartscan
    move.l   hdv_boot,a0         ; go through boot vector
    jsr     (a0)
    ifeq systype-rom
        tst.w  d0                ; any errors?
        bne   dskb1              ; (yes -- punt)
        lea   _diskbuf,a0       ; a0 -> disk buffer
        jsr   (a0)              ; execute boot sector (it might return)
    endc
dskb1:     rts                    ; return status

```

```

**
* cartscan - scan cartridge memory for runnable applications
* Passed:     d0 = bit# to test in application's initialization vector
* Returns:    after all applications have been examined
* Uses:      a0,d0
*--
cartscan:
    lea     cartbase,a0          ; a0 -> cartridge memory
    cmp.l   #apmagic,(a0)+      ; correct magic number?
    bne     ca_r                 ; (no, so return)

ca_1:     btst.b  d0,ca_flags(a0) ; test bit in MSB of INIT address
          beq     ca_2           ; (not set, so don't execute)
          movem.l d0-d7/a0-a6,-(sp) ; save everything
          move.l  ca_init(a0),a0  ; a0 -> initialization address
          jsr     (a0)           ; call cartridge application
          movem.l (sp)+,d0-d7/a0-a6 ; restore everything
ca_2:     tst.l   (a0)           ; test link address
          move.l  (a0),a0        ; a0 -> next header (or NULL)
          bne     ca_1           ; loop on next header
ca_r:     rts

_rts:     rts

```

```

**
* memchk - check pattern written to memory
* Passed:   d1.l = offset
*           a0 = base of pattern ($1f8 bytes long)
*           a5 -> return address
*
* Returns:  EQ: the pattern matched
*           NE: the pattern didn't match
*
* Uses:    d0.w, a1
*

```

```

*      Called-by:      Coldstart memory-sizing routine.
*--
memchk:
    add.l    d1,a0          ; a0 -> memory to check
    clr.w   d0             ; zap pattern seed
    lea     $1f8(a0),a1    ; a1 -> ending address
memchk1:  cmp.w   (a0)+,d0  ; match?
    bne     memchkr       ; (no -- return NE)
    add.w   $$fa54,d0     ; yes -- bump pattern
    cmp.l   a0,a1        ; matched entire pattern?
    bne     memchk1      ; (no)
memchkr:  jmp     (a5)     ; "return" to caller

```

```

    ifeq systype-rom
**+
* sysfail - we drop dead gracefully (sort of)
*
* If on a high-rez system, set video configuration to high-rez;
* Put up some diagnostic info;
* Display some kind of icon in the screen's center;
* Then loop forever, incrementing a bit of screen memory ....
*
*--
sysfail:
    btst.b  #7,gpip       ; test "HighRez" panic input
    bne     sysf1         ; (keep low rez)
    move.b  #$02,shiftmd  ; set high rez, cross our fingers

sysf4:   lea     sysf1(pc),a6      ; load return address
    lea     failure(pc),a1       ; a1 -> icon form
    bra     sysfdraw            ; draw icon
sysf1:   moveq   #0,d0           ; delay a while
sysf5:   dbra    d0,sysf5
    lea     sysf2(pc),a6        ; load return address
    lea     failure1(pc),a1     ; a1 -> icon form
    bra     sysfdraw            ; draw it
sysf2:   moveq   #0,d0           ; delay a while
sysf3:   dbra    d0,sysf3
    bra     sysf4               ; back to the beginning ....

sysfdraw:
    clr.l   a0                ; draw in middle of screen
    moveq   #0,d7             ; count = 1
    lea     failure(pc),a1    ; a1 -> icon form
    bra     _draw_icon        ; draw the icon

**+
* "Sad" icon form
* ... or something like that ....
*
*--
failure:

```

```
dc.w %1111111111111111
dc.w %10000000000000001
dc.w %1000001111000001
dc.w %10000000000000001
dc.w %1000001111000001
dc.w %1000001111000001
dc.w %10000000000000001
dc.w %1000001111000001
dc.w %10000000000000001
dc.w %1111111111111111
```

\*--- alternate form of the thing:  
failure1:

```
dc.w %1111111111111111
dc.w %10000000000000001
dc.w %1111111111111111
```

endc

\*+

```
* val_memval - test memory configuration validation
* Passed:      a6 -> return addressd
* Returns:    a5 -> 0 (quick zeropage)
*             EQ: memory setup OK
*             NE: memory never configured succesfully
```

\*-

val\_memval:

```
    clr.l    a5                ; a5 -> quick zeropage
    cmp.l    #memmagic,memvalid(a5) ; check first magic number
    bne     val_mr            ; (mismatched -- return NE)
    cmp.l    #memmag2,memval2(a5) ; check once more (for paranoia)
val_mr: jmp     (a6)          ; return EQ/NE
```

\*+

```
* Four longwords of zero
```

```

*
*--
zeros:   dc.l    $00000000,$00000000,$00000000,$00000000

**
* _draw_icon - Draw an icon
* Passed:     a6 -> return address
*             a1 -> source form
*             d5 = #icons to draw - 1
*             a0 = destination:
*                 a0 == 0:      draw in middle of screen
*                 a0 < $8000:   draw at offset on screen
*                 a0 >= $8000:  draw in memory
*
* Uses:       d0-d7/a0-a3/a5
*
*--
_draw_icon:
    move.b    shiftmd,d4
    and.w     #$0003,d4
    add.w     d4,d4                ; d4 = rez index

    cmp.l     #$8000,a0           ; if (a0 >= 0x8000) just_use_it;
    bhi      di_na
    cmp.l     #0,a0              ; if (a0 == 0) a0 = icn_index[d4]
    bne      di_na1
di_na1:     move.w    icn_index(pc,d4.w),a0 ; get offset of middle of screen
    clr.l    d0                 ; d0 = base_of_screen
    move.b    dbaseh,d0
    lsl.w     #8,d0
    move.b    dbasel,d0
    lsl.l    #8,d0
    add.l     d0,a0              ; a0 += base_of_screen;

di_na:     moveq     #15,d7        ; d7 = scanline count
di_1:     move.w    icn_repeat(pc,d4.w),d6 ; d6 = #scanlines to repeat
di_2:     move.w    d5,d3         ; d3 = count of # to draw
    move.l     a0,a2             ; a2 -> next scanline
    add.w     icn_width(pc,d4.w),a2

di_3:     move.b    (a1),d0       ; get word from source form
    lea      di_rt1(pc),a5       ; (a5->return address)
    bra      dup8                ; expand MSW of icon
di_rt1:   move.w    d2,d1
    move.b    1(a1),d0           ; expand LSW of icon
    lea      di_rt2(pc),a5       ; (a5->return address)
    bra      dup8
di_rt2:   move.w    (a1),d0       ; get original icon word
    jmp      di_jump(pc,d4.w)    ; jump to draw routine

di_jump:   bra.s    di_low
    bra.s    di_med
    bra.s    di_hi

di_low:   move.w    d0,(a0)+      ; store all four planes in lorez

```

```

        move.w  d0, (a0)+
        move.w  d0, (a0)+
        move.w  d0, (a0)+
        bra.s   di_cn                ; (continue)

di_med: move.w  d1, (a0)+            ; store plane 0
        move.w  d1, (a0)+            ; store plane 1
        move.w  d2, (a0)+            ; store plane 0
        move.w  d2, (a0)+            ; store plane 1
        bra.s   di_cn                ; (continue)

di_hi:  move.w  d1, (a0)+            ; store plane 0
        move.w  d2, (a0)+            ; store plane 1

di_cn:  dbra    d3, di_3             ; loop to do more on this line
        move.l  a2, a0               ; a0 -> next scanline
        dbra   d6, di_2             ; dup scanlines
        addq   #2, a1                ; bump source form
        dbra   d7, di_1             ; do another scanline
        jmp    (a6)                 ; return

```

```

**
* dup8 - expand d0.b into d2.w
* Passed:    d0.b = source bits
*           a5 -> return address
*
* Returns:   d2.w = d0.b, with every bit doubled
*
* Uses:      a3 (to save d3)
*
*-

```

```

dup8:   move.l  d3, a3                ; save d3
        moveq   #0, d2                ; d2 is pristine
        moveq   #7, d3                ; d3 = bit count
dB_1:   roxl.b  #1, d0                ; get MSB into carry + X
        move.w  sr, -(sp)             ; (save X)
        roxl.w  #1, d2                ; then rotate X in once
        move.w  (sp)+, sr             ; (restore X)
        roxl.w  #1, d2                ; then rotate X in twice
        dbra   d3, dB_1              ; (loop for more bits)
        move.l  a3, d3                ; restore d3
        jmp    (a5)                 ; return

```

```

**
* Screen-res dependent parameters:
* o index to center of screen
* o width of screen in bytes
* o number of scanlines to repeat
*
*-

```

```

icn_index:    dc.w    100*160+72, 100*160+72, 200*80+36
icn_width:    dc.w    160, 160, 80
icn_repeat:   dc.w    0, 0, 1

```

++

\* Default palette assignments.  
 \* Sort of corresponding to the GSX spec.

\*-

```

colors: dc.w    $777           ; 0 white
        dc.w    $700           ; 1 red
        dc.w    $070           ; 2 green
        dc.w    $770           ; 3 yellow
        dc.w    $007           ; 4 blue
        dc.w    $707           ; 5 magenta
        dc.w    $077           ; 6 cyan
        dc.w    $555           ; 7 "low white"
        dc.w    $333           ; 8 grey
        dc.w    $733           ; 9 light red
        dc.w    $373           ; 10 light green
        dc.w    $773           ; 11 light yellow
        dc.w    $337           ; 12 light blue
        dc.w    $737           ; 13 light magenta
        dc.w    $377           ; 14 light cyan
        dc.w    $000           ; 15 black
    
```

++

\* hbl - force caller to IPL  
 \* Oh-well: "Yeah, it sucks, but it works" (--!t)

\*

\* Note: Hacks caller's IPL to 3 (if it was 0). This is  
 \* a kludge against fascist programs and certain  
 \* debuggers that insist on starting processes up  
 \* at IPL 0.

\*

\*-

```

hbl:    move.w  d0, -(sp)       ; save d0
        move.w  2(sp), d0      ; get pushed SR
        and.w   #$0700, d0     ; strip crufty bits
        bne    hbl_r          ; not IPL 0, so punt
        or.w    #$0300, 2(sp)  ; force caller to IPL 3
hbl_r:  move.w  (sp)+, d0      ; restore d0, back to victim
        rte
    
```

++

\* vbl - vertical blank interrupt handler

\*

\*-

```

vbl:    addq.l  #1, _frclock    ; bump frame clock
        subq.w  #1, vblsem     ; P(vblsem) -- vblank locked?
        bmi    vblret

        movem.l d0-d7/a0-a6, -(sp) ; save registers
        addq.l  #1, _vbclock    ; bump unblocked-frame clock
        clr.l   a5              ; a5 -> zero page
    
```

\*----- Video monitor fail-safe anti-burnout check:

```

        move.b  shiftmd, d0                ; get current rez
        and.b   #3, d0                    ; strip bucky bits
        cmp.b   #2, d0                    ; low or high rez?
        bge     swmon1                     ; (high)

*--- low rez: switch to high if gpip%%7 == 0
        btst.b  #7, gpip                  ; get "High rez" input
        bne     swmon3                     ; no change: punt
        move.b  #2, d0                    ; trans to high rez
        bra     swmon2

*--- high rez: switch to low (hopefully defshiftmd) if gpip%%7 == 1
swmon1: btst.b  #7, gpip                  ; get "High rez" input
        beq     swmon3                     ; no change (still highrez)
        move.b  defshiftmd(a5), d0        ; get preferred rez
        cmp.b   #2, d0                    ; if high-rez, then force low rez
        blt     swmon2                     ; (low or med rez)
        clr.b   d0
swmon2: move.b  d0, sshiftmd(a5)          ; set shadow & hardware shift-mode
        move.b  d0, shiftmd
        move.l  swv_vec(a5), a0           ; go through "change rez" panic vector
        jsr    (a0)
swmon3:

        bsr     blink                     ; blink cursor

*--- reload color palettes
        clr.l   a5                        ; a5 -> zero page
        tst.l   colorptr(a5)              ; if(colorptr != NULL)...
        beq     vbl1                       ; (its NULL, so don't reload)
        move.l  colorptr(a5), a0          ; a0 -> user's color base
        lea    color0, a1                 ; a1 -> hardware palette base
        move.w  #16-1, d0                 ; d0 = count
vbl2:   move.w  (a0)+, (a1)+               ; load a palette
        dbra   d0, vbl2                   ; ...and repeat
        clr.l   colorptr(a5)              ; zap colorptr

*--- reload display base register
vbl1:   tst.l   screenpt(a5)               ; if(screenpt == NULL) don't;
        beq     vbl5
        move.l  screenpt(a5), _v_bas_ad(a5) ; set OS variable
        move.l  _v_bas_ad(a5), d0         ; d0 -> screen bottom
        lsr    #8, d0                      ; strip lower 8 bits
        move.b  d0, dbasel                 ; load "low" pointer
        lsr    #8, d0                      ; strip lower 8 bits
        move.b  d0, dbaseh                 ; load "high" pointer

*----- Floppy drive-select timeout:
vbl5:   bsr     _flopvbl                   ; (no args)

*----- Call deferred interrupt vectors:
        move.w  nvbls, d7                  ; d7 = # of deferred vblank vectors
        beq     vbl12                       ; (punt if no vectors)
        subq.l  #1, d7                      ; turn into DBRA count
        move.l  _vblqueue, a0              ; a0 -> vectors
vbl10:  move.l  (a0)+, a1                   ; a1 -> deferred vector

```

```

        cmp.l    #0,a1                ; if(a1 == NULL) continue;
        beq     vbl11
        movem.l d7/a0,-(sp)          ; save registers
        jsr     (a1)                 ; call routine
        movem.l (sp)+,d7/a0         ; restore registers
vbl11:  dbra     d7,vbl10             ; loop for more vectors

```

```

*--- monitor screen dump flag
vbl12:  clr.l    a5                    ; quick zeropage
        tst.w   _prtcnt(a5)          ; printscreen active?
        bne     no_print             ; no

```

```

*+
* printScreen
*
* We re-enable vblanks here, until the printScreen finishes.
*
*-

```

```

        bsr     _scrdmp              ; dump screen
        move.w  #-1,_prtcnt          ; unlock printScreen
no_print:

```

```

*--- restore registers & return (and a handy RTE)
        movem.l (sp)+,d0-d7/a0-a6
vblret: addq.w  #1,vblsem             ; V(vblsem) [release vblank]
_rte:   rte

```

```

*+
* wvbl - wait for next vblank
* Passed:      nothing
* Returns:     at beginning of next vblank
* Uses:       DO
*-

```

```

wvbl:
        move.w  sr,-(sp)              ; save psw
        and.w   #$ffff-$700,sr       ; enable vbl interrupts
        move.l  _frclock,d0          ; d0 = frame clock
wvbl1:  cmp.l   _frclock,d0           ; wait for clock to change
        beq     wvbl1
        move.w  (sp)+,sr              ; then restore psw & return
        rts

```

```

*+
* _critic - critical error handler binding for C
* Falls-into: _critich
* (screwy way to save two bytes...)
*
*-
_critic:
        move.l  etv_critic,-(sp)      ; jump through critic vector

```

```

**
* _critich - default critical error handler
* Loads -1 into D0 and returns.
*
*--
_critich:
    moveq    #-1,d0          ; default return value = ERROR
    rts                    ; return to trap invoker

**
* trp13h - GEMDOS BIOS trap handler (trap 13)
* trp14h - Atari BIOS extensions (trap 14)
* traph - trap handler
*
* On the stack:
*      From super-          From user
*      visor mode:         mode:
*      -----
*      N(sp) args          N(usp) args
*      6(sp) func#         6(usp) func#
*      2(sp) ret           2(ssp) ret
*      (sp) SR             (ssp) SR
*
* Returns:      anything in D0
*
* Uses:         d0-d2/a0-a2
* Keeps:       C registers
*
* Notes:       BIOS traps are re-entrant to 'nlevels' (declared near the
*              beginning of this file). Attempts to recurse more than
*              'nlevels' will probably result in a crash.
*
*              BIOS calls may be made from user mode. (This differs from
*              the current GEMDOS spec, which states that BIOS traps are
*              available from supervisor mode only).
*--
trp14h: lea    trp14tab(pc),a0      ; a0 -> trap14 jump table
        bra.s  traph
trp13h: lea    trp13tab(pc),a0     ; a0 -> trap13 jump table

* save registers, twiddle stack:
traph:  move.l  savptr,a1          ; a1 -> register save area
        move.w  (sp)+,d0          ; pop SR and save it
        move.w  d0,-(a1)         ; (need in D0 for user-mode test)
        move.l  (sp)+,-(a1)      ; save return addr
        movem.l d3-d7/a3-a7,-(a1) ; save C registers + super stack
        move.l  a1,savptr        ; update save-area pointer

* make sure we have the right stack, call function:
        btst   #13,d0            ; was in user mode?
        bne   b_supr            ; (was in super: use super stack)
        move.l  usp,a7          ; use user stack
b_supr: move.w  (sp)+,d0        ; get function#
        cmp.w   (a0)+,d0        ; out of range?

```

```

    bge      b_exit      ; (yes, so punt)
    lsl.w   #2,d0       ; turn d0 into longword index
    move.l  (a0,d0.w),d0 ; get pointer to function handler
    move.l  d0,a0       ; (quick and dirty test-for-negative)
    bpl     b_1         ; points to code
    move.l  (a0),a0     ; indirect through RAM...
b_1:  clr.l  a5         ; a5 -> zero page
    jsr     (a0)        ; call BIOS function

```

\* restore registers, cleanup stack and return:

```

b_exit: move.l  savptr,a1      ; a1 -> register save area
    movem.l (a1)+,d3-d7/a3-a7 ; restore C registers + super stack
    move.l  (a1)+,-(sp)       ; push return address
    move.w  (a1)+,-(sp)       ; push old SR
    move.l  a1,savptr        ; update save-pointer
    rte                      ; return to caller

```

\*----- jump table for GEMDOS functions:

```

trp13tab:
dc.w   12                ; number of entries in jump table
dc.l   _get_mpb         ; 0: get memory parameter block
dc.l   bconstat        ; 1: console status (input)
dc.l   bconin          ; 2: console input
dc.l   bconout         ; 3: console output
dc.l   hdv_rw+$80000000 ; 4: [indirect] disk read/write
dc.l   _setexc         ; 5: set exception vector
dc.l   _tickcal        ; 6: return tick calibration
dc.l   hdv_bpb+$80000000 ; 7: [indirect] get BPB
dc.l   bcostat         ; 8: console status (output)
dc.l   hdv_mediach+$80000000 ; 9: [indirect] media change inquiry
dc.l   _drvmap         ; 10: get active-drive bit vector
dc.l   _shift          ; 11: get/set keyboard shift bits

```

\*----- jump table for Atari BIOS extensions:

```

trp14tab:
dc.w   40                ; number of entry points
dc.l   initmous        ; 0: initialize mouse
dc.l   _rts            ; 1: (reserved)
dc.l   _physbase      ; 2: get physical screen base
dc.l   _logbase       ; 3: get logical screen base
dc.l   _getrez        ; 4: get screen resolution
dc.l   _setscreen     ; 5: set video parameters
dc.l   _setpalette    ; 6: set palette
dc.l   _setcolor      ; 7: set single color
dc.l   _flopprd       ; 8: read floppy sector(s)
dc.l   _flopwr        ; 9: write floppy sector
dc.l   _flopfmt       ; 10: format floppy track
dc.l   _getdsb        ; 11: get device status block ptr

dc.l   midiws         ; 12: write string to MIDI port
dc.l   mfpint         ; 13: initialize MFP interrupt

```

```

dc.l   iorec           ; 14: set I/O record
dc.l   rsconf         ; 15: configure RS-233 communications
dc.l   keytrans       ; 16: set keyboard translation tables

dc.l   _rand          ; 17: generate 24-bit random number
dc.l   _proto_bt      ; 18: prototype boot sector
dc.l   _flopver       ; 19: floppy verify

dc.l   _dumpit        ; 20: dump screen
dc.l   _cursconf      ; 21: get/set cursor configuration
dc.l   setttime       ; 22: set ikbd time
dc.l   gettime        ; 23: get ikbd time
dc.l   bioskeys       ; 24: reset keyboard to powerup default
dc.l   ikbdws        ; 25: write string to ikbd

dc.l   jdisint        ; 26: disable mfp interrupt
dc.l   jenabint       ; 27: enable mfp interrupt
dc.l   giaccess       ; 28: read/write sound chip
dc.l   offgibit       ; 29: reset bit in sound chip register
dc.l   ongibit        ; 30: set bit in sound chip register
dc.l   xbtimer        ; 31: initialize mfp timer
dc.l   dosound        ; 32: startup sound daemon
dc.l   setprt         ; 33: get/set printer configuration
dc.l   ikbdvecs       ; 34: return ptr to base of kbd vars
dc.l   kbrate         ; 35: get/set keyboard repeat rate
dc.l   _prtblk        ; 36: _prtblk primitive
dc.l   wvbl          ; 37: wait for next vblank
dc.l   supexec        ; 38: execute in super mode
dc.l   puntaes       ; 39: throw away AES

```

```

**
* supexec - execute some code in supervisor mode
*

```

```

*-
supexec:
    move.l 4(sp),a0      ; a0 -> code
    jmp   (a0)          ; execute it

```

```

**
* Character device I/O
*
* No check is made for "bogus" device numbers. A wierd device
* number will result in a crash.
*

```

```

*-
bconstat: lea    tconstat(pc),a0      ; a0 -> stat table
           bra.s  chsw

bconin:   lea    tconin(pc),a0        ; a0 -> input table
           bra.s  chsw

bcostat:  lea    tcostat(pc),a0       ; a0 -> ostat table
           bra.s  chsw

```

```

bconout: lea    tconout(pc),a0      ; a0 -> output table
chsw:    move.w 4(sp),d0           ; get device number
        lsl.w  #2,d0              ; turn into longword index
        move.l (a0,d0.w),a0       ; get address of handler
        jmp   (a0)                ; jump to it

```

```

**
* Jump tables for
* 0 - lst: (printer)
* 1 - aux: (rs232)
* 2 - con: (screen)
* 3 - Atari midi
* 4 - Atari keyboard (output only)
* 5 - raw console output (bypass vt52 pressure cooker)
*
* No range checking is performed. If a bogus device number
* is passed to the BIOS' character I/O handler, the system
* will crash or become funky duex.
*
*-

```

```

tconstat: dc.l _rts,auxistat,constat,midstat,_rts,_rts
tconin:    dc.l _lstin,auxin,conin,midin,_rts,_rts
tcostat:  dc.l _lstostat,_auxostat,conoutst,ikbdost,midiost,_rts
tconout:   dc.l _lstout,_auxout,conout,midiwc,ikbdwc,_asc_out

```

```

**
* _drvmap - return "active drive" bit vector
* Passed:    nothing
* Returns:   DO.L = a bit vector of live (rwabs'able) block devices
*
*-

```

```

_drvmap
        move.l _drvbits(a5),d0
        rts

```

```

**
* _shift - get/set keyboard shift state
* Synopsis: LONG _shift(bits)
*           WORD bits
*
* Returns:  DO.B = shift/alt/ctl/shift' bits
*
* Note:    Since the shift bits are changed at interrupt
*          level, any set from a get of the shift state
*          must be done as a critical section.
*
*-

```

```

_shift:
        moveq   #0,d0
        move.b  kbshift(a5),d0
        move.w  4(sp),d1
        bmi    shifr
        move.b  d1,kbshift(a5)

```

shifr: rts

\*\*

\* \_get\_mpb - return initial memory parameter block

\* Synopsis: \_get\_mpb(mpb)

\* MPB \*mpb;

\*

\* Returns: The properly initialized MPB.

\* The MPB points to an MD somewhere in BSS. The MD /must/ be in RAM since DOS will modify it.

\*--

\_get\_mpb:

```

    move.l 4(sp),a0          ; a0 -> MPB
    lea   themd(a5),a1      ; a1 -> MD

```

\*--- initialize MPB:

```

    move.l a1,(a0)          ; mp_mfl = &themd;
    clr.l 4(a0)             ; mp_mal = NULL;
    move.l a1,8(a0)        ; mp_rover = &themd;

```

\*--- initialize MD:

```

    clr.l (a1)              ; m_link = NULL;
    move.l _membot(a5),4(a1) ; m_start = _membot;
    move.l _memtop(a5),d0   ; m_length = _memtop - _membot;
    sub.l _membot(a5),d0
    move.l d0,8(a1)
    clr.l $(a1)            ; m_own = NULL;
    rts

```

\*\*

\* \_setexc - set exception vector

\* Synopsis: setexc(vecno, addr)

\* If 'addr' &lt; 0, the vector is not set.

\*

\* Extended vectors (\$100 through \$107) are located in the first eight longwords of BSS, at \$400. This is for convenience -- they could really be located anywhere.

\*

\* Returns: D0.L = original vector value

\*

\*--

\_setexc:

```

    move.w 4(sp),d0          ; d0 = vector#
    lsl.w #2,d0             ; turn into longword index
    clr.l a0
    lea   (a0,d0.w),a0      ; a0 -> vector
    move.l (a0),d0          ; d0 = current vector address
    move.l 6(sp),d1         ; d1 = what_to_change_it_to
    bmi  setex1             ; punt if (d1 < 0)
    move.l d1,(a0)         ; set vector address

```

setex1: rts

\*\*

```

* _tickcal - return system timer calibration value (in ms)
*
*-
_tickcal:
    clr.l    d0                ; cast to unsigned longword
    move.w   _timr_ms(a5),d0   ; get calibration
    rts

**+
* _physbase - get physical display base
*
*-
_physbase:
    moveq    #0,d0             ; cleanup pointer-to-be
    move.b   dbaseh,d0         ; load and shift bits 16..23
    lsl.w    #8,d0
    move.b   dbasel,d0        ; load and shift bits 8..15
    lsl.l    #8,d0
    rts                        ; return pointer in d0

**+
* _logbase - get logical display base
*
*-
_logbase:
    move.l   _v_bas_ad(a5),d0 ; set software shadow
    rts

**+
* _getrez - get current screen rez
*
*-
_getrez:
    moveq    #0,d0             ; cleanup dirty bits
    move.b   shiftmd(a5),d0    ; get screen resolution
    and.b    #$03,d0           ; strip garbage bits
    rts                        ; return rez

**+
* _setscreen - set screen location(s), rez
*
*     _setscreen(logicalLoc, physicalLoc, rez)
*     LONG logicalLoc, physicalLoc;
*     WORD rez;
*
*-
_setscreen:

*--- set logical location:
    tst.l    4(sp)             ; if(logloc < 0) then ignore it
    bmi     f5a
    move.l   4(sp),_v_bas_ad(a5) ; set software pointer from logloc

```

```

*--- set physical location:
f5a:   tst.l   8(sp)           ; if(physloc < 0) then ignore it
      bmi    f5b
      move.b 9(sp),dbaseh     ; set bits 16..23 of hardware pointer
      move.b $a(sp),dbasel   ; set bits 8..15 of hardware pointer

```

```

*--- change screen resolution (clears the screen, clobbers the cursor):
f5b:   tst.w   $c(sp)         ; if(rez < 0) then ignore it
      bmi    f5r
      move.b $d(sp),sshiftmd(a5) ; set software shadow
      bsr    wvbl            ; wait for start of vertical-blank
      move.b sshiftmd(a5),shiftmd ; set hardware location
      clr.w  vblsem(a5)      ; disable vblank processing
      jsr    esc_init       ; re-initialize glass tty routines
      move.w #1,vblsem      ; re-enable vblanks
f5r:   rts

```

```

**+

```

```

* _setpalette - set palette (on next vblank)
*   _setpalette(LONG palettePtr)

```

```

*

```

```

*--

```

```

_setpalette:
      move.l 4(sp),colorptr(a5) ; set software pointer
      rts ; (updated by vbl handler)

```

```

**+

```

```

* _setcolor - set single color, return old color
*   _setcolor(WORD colorNum, WORD colorValue)

```

```

*

```

```

*--

```

```

_setcolor:
      move.w 4(sp),d1           ; get color number
      add.w  d1,d1              ; turn into word index
      and.w  #$1f,d1           ; force color range (prevent buserr)
      lea   color0,a0          ; a0 -> base of palette memory
      move.w (a0,d1.w),d0       ; return old color
      and.w  #$0777,d0         ; mask dirty bits
      tst.w  6(sp)             ; if new color is <0, don't set it
      bmi   _setcl             ; (punt)
      move.w 6(sp),(a0,d1.w)    ; set new color
_setcl: rts

```

```

**+

```

```

* puntaes - throw-away AES, restart the system

```

```

* Passed:   nothing

```

```

* Uses:     everything

```

```

* Returns:  if AES was already thrown away

```

```

*

```

```

*--

```

```

puntaes:
      move.l  os_magic(pc),a0    ; get pointer to magic
      cmp.l   #$87654321,(a0)   ; is the magic still there?

```

```

    bne     paes1          ; no -- just return

    cmp.l   phystop,a0     ; is it in ROM?
    bge     paes1          ; yes -- we can't do anything about it
    clr.l   (a0)           ; clobber AES!
    bra     reseth         ; restart the system

```

```
paes1: rts
```

```

**
* _term - terminate current process
* Called-by: Uncaught traps (bus errors, and so on)
* Saves:     processor state (in a bailout area)
*
*-

```

```

_term:
    bsr     savp_2         ; stack PC
    nop                                     ; (never executed)
savp_2: move.l (sp)+,proc_pc ; save bogus PC + exception number
    movem.l d0-d7/a0-a7,proc_regs ; common registers
    move.l  usp,a0         ; save USP
    move.l  a0,proc_esp    ;
    move.w  #15,d0         ; save 16 words off top of
    lea    proc_stk,a0    ; the stack (enough for
    move.l  sp,a1         ; any possible 68000 exception)
savp_1: move.w (a1)+,(a0)+ ; save a word
    dbra   d0,savp_1
    move.l  #$12345678,proc_lives ; set magic number (procdump lives)

```

```

*--- draw an appropriate number of 'shrooms on the screen:
    moveq   #0,d1
    move.b  proc_pc,d1
    subq   #1,d1          ; 2 for bus error, 3 for address, etc.
    bsr    do_shroom

    move.l  #savend,savptr ; clobber BIOS top level
    move.w  #1,-(sp)       ; "error" return condition
    clr.l  -(sp)          ; GEMDOS function #0
    trap   #1             ; "terminate process"
    bra    reseth         ; on return, reset system

```

```

**
* do_shroom - draw little mushroom clouds on the screen
* Passed:    d1.w = #shrooms to draw (DBRA count)
* Returns:   some shrooms on display
* Uses:      d0-d7/a0-a2
*
* Discussion: The graphics ain't all that great. And this is silly.
*
*-

```

```

do_shroom:
    move.b  shiftmd,d7
    and.w   #$0003,d7
    add.w   d7,d7          ; d7 = rez index

```

```

clr.l    d0
move.b   dbaseh,d0
lsl.w    #8,d0
move.b   dbasel,d0
lsl.l    #8,d0
move.l   d0,a0
add.w    mindex(pc,d7.w),a0      ; a0 -> base of mem to draw at

lea      mushroom(pc),a1        ; a1 -> source form
move.w   #15,d6                 ; d6 = scanline count

dm0:     move.w   d1,d2          ; d3 = # to draw on this line
         move.l   a0,a2          ; save ptr to beg of line
dm1:     move.w   mcount(pc,d7.w),d5 ; d5 = #words to replicate
dm2:     move.w   (a1),(a0)+      ; draw a word
         dbra     d5,dm2         ; (complete single shroom)
         dbra     d2,dm1         ; another, on the same line
         addq     #2,a1          ; next source word
         add.w    mwidth(pc,d7.w),a2 ; next dest line
         move.l   a2,a0
         dbra     d6,dm0         ; (loop for next line)
         rts                    ; byebye

```

```

mindex:   dc.w    100*160,100*160,200*80
mcount:   dc.w    3,1,0
mwidth:   dc.w    160,160,80

```

\*--- what it is:

mushroom:

```

dc.w     %0000011111000000
dc.w     %0001111111110000
dc.w     %0011101111111000
dc.w     %0111011111110100
dc.w     %1011011111111010
dc.w     %1011101111111010
dc.w     %1101111111110110
dc.w     %0110011011111100
dc.w     %0011001010001000
dc.w     %0000001010000000
dc.w     %0000010001000000
dc.w     %0000010001000000
dc.w     %0000010101000000
dc.w     %0000010100100000
dc.w     %0000100100100000
dc.w     %0000100100100000
dc.w     %0001001010010000

```

#+

\* \_fastcpy - "fast" 512-byte copy  
\* Synopsis: fastcpy(src, dest)

\*  
\*  
\*  
\*

Used by \_rwabs to fake disk DMA to odd addresses. Therefore,  
disk I/O on odd addresses is very slow. Lose, lose.

```

*-
_fastcpy:
    move.l 4(sp),a0          ; a0 -> src
    move.l 8(sp),a1          ; a1 -> dest
    move.w #63,d0           ; d0 = move count (64*B = 512)
fast1:  move.b (a0)+,(a1)+   ; copy 8 bytes at a time
        move.b (a0)+,(a1)+   ;           to minimize loop overhead
        move.b (a0)+,(a1)+
        move.b (a0)+,(a1)+
        move.b (a0)+,(a1)+
        move.b (a0)+,(a1)+
        move.b (a0)+,(a1)+
        move.b (a0)+,(a1)+
        dbra  d0,fast1
    rts

```

```

**
* Go through hard-disk initialization vector
*

```

```

*-
_hinit: move.l hdv_init,-(sp)
        rts

```

```

autopath: dc.b  '\AUTO\'
autofile: dc.b  '*.PRG',0
          dc.w  $1234,$5678,$9abc,$def0
even

```

```

**
* _auto - exec auto-startup files in the appropriate subdirectory
* _auto1 - exec (with filename args)
* Passed:
*         a0 -> full filespec (pathname)
*         a1 -> filename part of filespec
*         _drvbits: bit vector of active drives
*         _bootdev: contains device to exec from
*
* Returns: nothing
*
* Note:   If _drvbits%_bootdev is zero, _auto simply quits (since
*         the device isn't active...)
*
* Uses:   everything
*-

```

```

        .globl _auto          ; for debugging
_auto:  lea  autopath(pc),a0   ; -> path
        lea  autofile(pc),a1  ; -> filename

_auto1: move.l (sp)+,autoret   ; return addr (used by execlr)
        clr.l a5              ; quick zeropage
        move.l a0,pathname(a5) ; setup filename/pathname ptrs
        move.l a1,filename(a5)

        move.l _drvbits(a5),d0 ; d0 = active dev vector
        move.w _bootdev,d1     ; d1 = dev# to exec from

```

```

    btst    d1,d0                ; is the dev alive?
    beq     autoq                ; (no -- so punt)

    lea     nullenv(pc),a0       ; a0 -> \0\0
    move.l  a0,-(sp)             ; null enviroment
    move.l  a0,-(sp)             ; null command tail
    move.l  a0,-(sp)             ; null shell name
    move.w  #5,-(sp)             ; Create-PSP subfunction
    move.w  #$4b,-(sp)           ; exec function#
    trap    #1                   ; do DOS call
    add.w   #16,sp

    move.l  d0,a0                ; a0 -> PSP
    move.l  #fauto,8(a0)         ; initial PC -> autoexec prog

    move.l  a3,-(sp)             ; null enviroment
    move.l  d0,-(sp)             ; -> PSP
    move.l  a3,-(sp)             ; null shell name
    move.w  #4,-(sp)             ; just-go
    move.w  #$4b,-(sp)           ; function = exec
    trap    #1                   ; do it
    add.w   #16,sp               ; cleanup stack & goodbye

autoq:  rts

**
* fauto - exec'd by _auto to do autostartup
*
* Passed:      pathname -> path part of filespec
*              filename -> file part of filespec
*
*-
fauto:
    clr.l   -(sp)                ; get into super mode
    move.w  #$20,-(sp)
    trap    #1
    addq    #6,sp                 ; cleanup
    move.l  d0,a4                 ; a4 -> saved super stack

*--- free up some memory:
    move.l  4(a7),a5              ; a5 -> base page
    lea     $100(a5),sp           ; sp -> new, safer addr
    move.l  #$100,-(sp)           ; keep $100 (just the basepage)
    move.l  a5,-(sp)              ; -> start of mem to keep
    clr.w   -(sp)                 ; junk word
    move.w  #$4a,-(sp)           ; setblock(...)
    trap    #1
    addq    #6,sp
    tst.w   d0
    bne     au_dn                 ; punt on error

    move.w  #$0007,-(sp)          ; find r/o+hidden+system files
    move.l  pathname,-(sp)        ; -> filename (on input)
    move.w  #$4e,-(sp)           ; searchFirst

```

```

au1:    moveq    #8, d7                ; d7 = cleanup amount
        pea     autodma                ; setup DTA (for search)
        move.w  #$1a, -(sp)
        trap   #1
        addq   #6, sp

        trap   #1                    ; search first/search next
        add.w  d7, sp                 ; cleanup stack
        tst.w  d0                     ; test for match
        bne   au_dn                   ; (no match -- quit)

*--- construct filename from path and the name we just found:
        move.l  pathname, a0          ; copy pathname
        move.l  filename, a2         ; a2 -> end+1 of pathname
au3:    move.b  (a0)+, (a1)+          ; copy path part of name
        cmp.l  a0, a2                 ; finished?
        bne   au3                     ; (no)
        lea   autodma+30, a0         ; copy fname to end of pathname
au2:    move.b  (a0)+, (a1)+
        bne   au2

        pea   nullenv(pc)            ; null enviroment
        pea   nullenv(pc)            ; no command tail
        pea   autoname                ; -> file to exec
        clr.w  -(sp)                  ; load-and-go
        move.w #$4b, -(sp)           ; exec(...)
        trap  #1
        add.w  #16, sp

        moveq  #2, d7                 ; reset cleanup amount
        move.w #$4f, -(sp)           ; searchNext
        bra   au1

```

```

*+
* The first GEMDOS process can never terminate.
* This is not a good feature.
* Kludge around it -- re-initialize the stack
* and return to the guy who called us to begin with.
*
*-

```

```

au_dn:  lea    _supstk+2048, sp       ; setup supervisor stack
        move.l autoret, -(sp)       ; get return addr
        rts                          ; just jump there ...

```

\*--- bss for auto-exec:

```

        bss
autoret: ds.l 1                      ; -> _auto's caller (ycccch)
pathname: ds.l 1                     ; -> filespec's pathname
filename: ds.l 1                     ; -> filename part of path
autodma:  ds.b 44                    ; 44 bytes for directory search
autoname: ds.b 32                    ; 32 bytes for path+filename
        even
        text

```

```

**
* _dumpit: dump screen
*
*-
_dumpit:
    clr.w    _prtcnt
    bsr     _scrdmp
    move.w  #$ffff, _prtcnt
    rts

**
* _scrdmp - printScreen(), front-end to _prtblk()
* Passed:    nothing
* Returns:   nothing
* Uses:     everything
*
*-
_scrdmp:
    clr.l    a5 ; easy zeropage
    move.l   _v_bas_ad(a5), p_blkptr(a5) ; -> screen mem
    clr.w    p_offset(a5) ; offset = 0
    clr.w    d0
    move.b   sshiftmd(a5), d0 ; get w & h
    move.w   d0, p_srcres(a5)
    add.w    d0, d0
    lea     rextab(pc), a0
    move.w   (a0, d0.w), p_width(a5) ; set display width, height
    move.w   6(a0, d0.w), p_height(a5)
    clr.w    p_left(a5) ; left = right = 0
    clr.w    p_right(a5)
    move.l   #$ff8240, p_colpal(a5) ; -> hardware palettes
    clr.w    p_masks(a5) ; default masks ptr

* draft or final mode
    move.w   pconfig(a5), d1 ; p_dstres = pconfig%%3
    lsr.w    #3, d1
    and.w    #1, d1
    move.w   d1, p_dstres(a5)

* printer or rs232 port
    move.w   pconfig(a5), d1 ; p_port = pconfig%%4
    move.w   d1, d0
    lsr.w    #4, d0
    and.w    #1, d0
    move.w   d0, p_port(a5)

* select printer flavor
    and.w    #7, d1 ; p_type = ptype[pconfig & 7]
    move.b   ptype(pc, d1.w), d0
    move.w   d0, p_type

* do it
    pea     prtargs(a5) ; -> beginning of parameter area
    bsr     _prtblk ; print it (finally)

```

```

    addq    #4, sp      ; cleanup stack
    rts                    ; and return

```

\*--- screen resolution table (pixels) for printScreen

```

reztab: dc.w    320, 640, 640 ; widths
        dc.w    200, 200, 400 ; heights

```

\*--- printer flavors (based on low 3 bits of pconfig)

```

ptype:
    dc.b    0          ; atari mono dot
    dc.b    2          ; atari mono daisy
    dc.b    1          ; atari color dot
    dc.b   -1          ; [atari color daisy???]
    dc.b    3          ; epson mono dot
    dc.b   -1          ; [epson mono daisy]
    dc.b   -1          ; [epson color dot]
    dc.b   -1          ; [epson color daisy]
    even

```

\*--- parameter storage for printScreen:

```

    bss
prtargs:
p_blkptr:    ds.l    1      ; -> bitmap to print
p_offset:    ds.w    1      ; offset on page
p_width:     ds.w    1      ; width and height
p_height:    ds.w    1
p_left:      ds.w    1      ; left & right leading
p_right:     ds.w    1
p_srcres:    ds.w    1      ; source rez (0, 1, 2)
p_dstres:    ds.w    1      ; destination rez (0, 1)
p_colpal:    ds.l    1      ; -> color palettes
p_type:      ds.w    1      ; printer type (0, 1)
p_port:      ds.w    1      ; printer port (0, 1)
p_masks:     ds.l    1      ; -> halftone masks

```

```

-----
*
*      Position-independent OS mover
*      (C)1985 Atari Corp.
*
*      Takes over from the Loader,
*      cleans up the display;
*      moves RAM-loaded OS from where it is to where it should be.
*
* 23-May-1985 lmd      Re-write from old, crufty version.
*
-----

*--- interface equates to OS:
lowstart      equ      $580           ; start of low BSS to clear
src_offset    equ      $100          ; offset from 'start' to OS image
os_size       equ      $38000        ; size of OS

*--- hardware:
dbase0       equ      $ff8203        ; display base low (really, medium)
dbasehi      equ      $ff8201        ; display base high
color0       equ      $ff8240        ; base of palette mem
gpip         equ      $fffa01        ; general porpoise input

**
* Take control from the Loader;
* turn on interrupts and clean up the screen:
*
*-
start:  move.w  #$2700, sr           ; supermode, no interrupts
        bsr    ramp                ; cleanup display

        lea    start(pc), a0        ; a0 -> base of loaded OS.
        lea    src_offset(a0), a0
        move.l 8(a0), a1             ; a1 = a2 = a3 -> destination
        move.l a1, a2               ; a2 -> saddr
        move.l a1, a3               ; a3 -> dest
        move.w #(os_size/16)-1, d0  ; d0 = d1 = size (16-byte chunks)
        move.w d0, d1

*--- copy OS to destination:
mvit:   move.l  (a0)+, (a1)+        ; copy 16 bytes /fast/
        move.l  (a0)+, (a1)+
        move.l  (a0)+, (a1)+
        move.l  (a0)+, (a1)+
        dbra   d0, mvit            ; ...until we're done

*--- startup the system:
        jmp    (a2)                ; jump to OS base addr

```

```

**+
* ramp - pretty transition from boot screen (the Fog)
* Takes about 0.5 seconds for a color display;
* No time at all for a mono system.
*
*-
ramp:
    btst.b    #7,gpip           ; are we mono?
    beq      itsmono          ; yes, we ARE devo

**+
* a color monitor is attached (attached)?
* anyway, bring up the fog...
*
*-
ramp_1: clr.l    d0             ; assume we're done
        lea     color0,a0      ; a0 -> palette RAM
        move.w  #15,d7         ; d7 = count (do all colors)
ramp_2: move.w  (a0),d1        ; get palette bits
        and.w   #$777,d1       ; strip garbage ones
        cmp.w   #$777,d1       ; are we already at white?
        beq    ramp_3          ; (yes, so don't increment this one)

*--- bump color up one notch:
        move.w  #$700,d2       ; d2 = mask
        moveq   #2,d3          ; d3 = count (do this three times)
ramp_4: move.w  d1,d4          ; d4 = color & mask
        and.w   d2,d4
        move.w  #$777,d5       ; d5 = $777 & mask
        and.w   d2,d5
        cmp.w   d5,d4          ; if we're already at 7, just continue
        beq    incq
        move.w  d2,d4          ; d4 = $111 & mask
        and.w   #$111,d4
        add.w   d4,d1          ; d1 += d4; bump the color
        moveq   #1,d0          ; not done yet (set notDone flag)
incq:   lsr.w   #4,d2          ; shift the mask down four bits
        dbra   d3,ramp_4       ; do some more fields

ramp_3: move.w  d1,(a0)+       ; shove new value into palette register
        dbra   d7,ramp_2       ; loop for more registers

        move.w  #$6000,d1      ; delay a while
ramp_d: dbra   d1,ramp_d

        tst.l   d0             ; are all palettes at $x777?
        bne   ramp_1          ; (no -- so ramp again)

**+
* Done with the ramp
* (or, we're on a mono system).
*

```

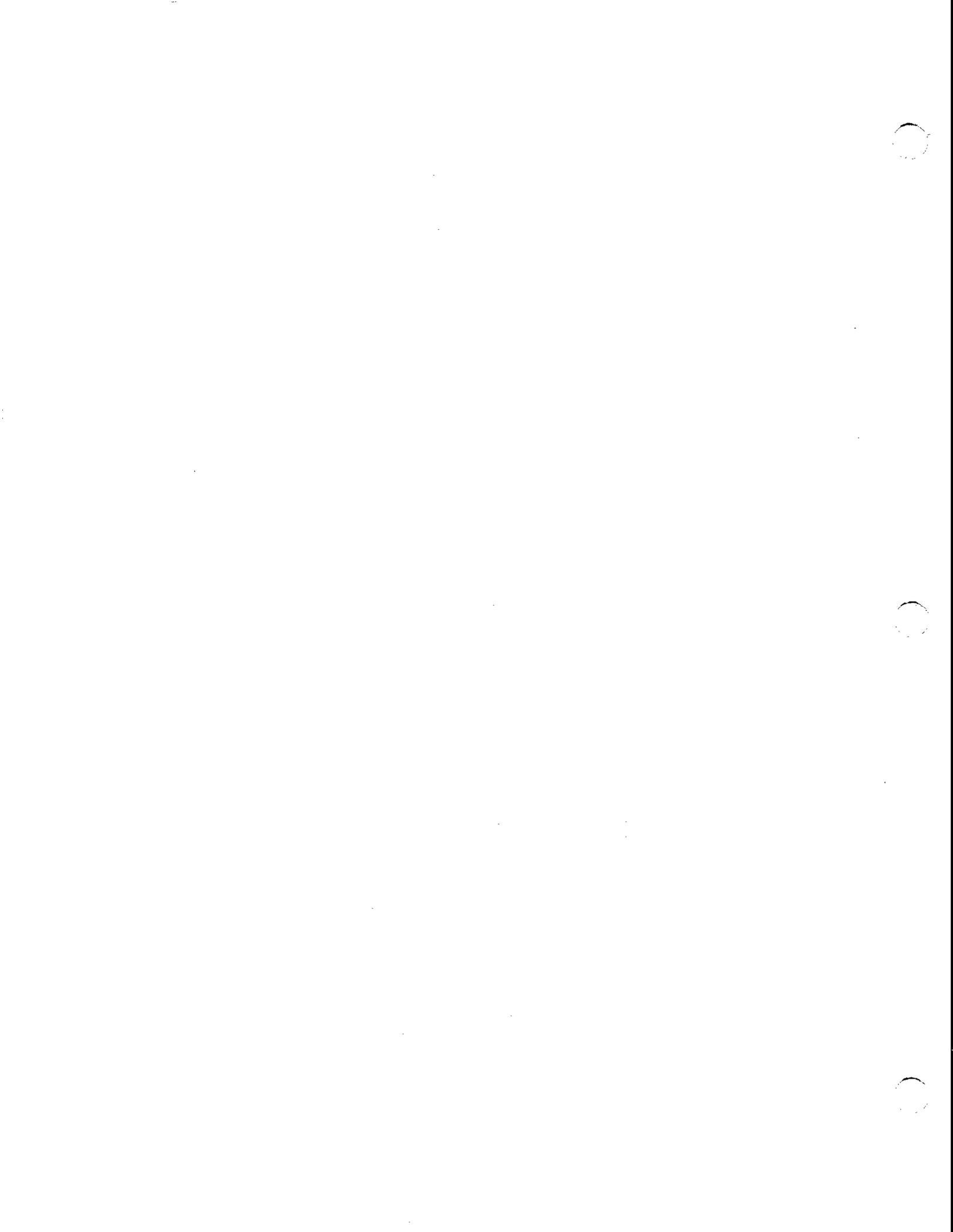
\* Clobber last 32K of a 512K system  
\* and move the display there.

\*  
\*--

itsmono:

```
    lea    $78000, a0          ; a0 -> base of new display
    move.w #$7ff, d0
    moveq  #0, d1              ; cheap zero
zap:  move.l d1, (a0)+         ; clear 16 bytes /real fast/
      move.l d1, (a0)+
      move.l d1, (a0)+
      move.l d1, (a0)+
      dbra  d0, zap           ; ...$800 times....

      move.b #$07, dbasehi    ; point display at new base
      move.b #$80, dbaselo
      rts
```



```

/*
 * Initialize OS
 * Start something up (either GEM or COMMAND.COM).
 * Return when that thing is done.
 *
 * 4-Mar-1985 lmd      Cleanup (removed some lint)
 * 4-Mar-1985 lmd      Wired for new GEM system.
 * 11-Mar-1985 lmd      split out osi()
 * 13-Mar-1985 lmd      migrated buf1[] to base BSS (for future expansion)
 * 13-Mar-1985 lmd      ripped out main() [why keep this file around?]
 */

```

```
#include "fs.h"
```

```
extern long oscall();
#define xexec(a,b,c,d) oscall(0x4b,a,b,c,d)
```

```

/*
 * Sector buffers,
 * four seems to be about right (hard-coded in osi())
 * Extensible through base-BSS links.
 */
char secbuf[4][512];          /* sector buffers */
BCB bcbx[4];                 /* bcb for each buffer */

```

```

/*
 * Initialize GEMDOS
 */
osi()
{
    extern BCB *buf1[2];      /* two buffer lists */
    extern int bootdev;
    extern int cmdload;

    /*
     * Setup sector buffers (four of 'em)
     */
    bcbx[0].b_link = &bcbx[1];
    bcbx[2].b_link = &bcbx[3];
    bcbx[0].b_bufdrv = -1;
    bcbx[1].b_bufdrv = -1;
    bcbx[2].b_bufdrv = -1;
    bcbx[3].b_bufdrv = -1;
    bcbx[0].b_buftr = &secbuf[0][0];
    bcbx[1].b_buftr = &secbuf[1][0];
    bcbx[2].b_buftr = &secbuf[2][0];
    bcbx[3].b_buftr = &secbuf[3][0];

    /*
     * Setup links in buffer-list
     * First one caches FATs,
     * second one caches directory and data blocks.
     */
}

```

```
buf1[0] = &bcbx[0];          /* fat buffers */
buf1[1] = &bcbx[2];          /* dir/data buffers */

/*
 * Initialize OS, login boot device:
 */
osinit();                    /* initialize OS */
xsetdrv(bootdev);            /* set default drive# */
```

}

```

#include "portab.h"
/* #define      DAS_BOOT 1
*/

/*
 * ST Disk support (and random BIOS functions)
 * (C)1985 Atari Corp.
 *
 *-----
 * 23-Feb-1985 lmd      Added multiple-sector floppy read support.
 * 23-Feb-1985 lmd      Added "rand()" function.
 * 24-Feb-1985 lmd      Added hard disk hooks.
 * 24-Feb-1985 lmd      Added floppy and hard boot code.
 * 25-Feb-1985 lmd      boot() goes to default boot device
 * 28-Feb-1985 lmd      boot() returns diagnostics, initializes disk system
 * 1-Mar-1985 lmd       Added proto_bt() boot sector prototyper
 * 1-Mar-1985 lmd       Added mediach(dev) BIOS call
 * 4-Mar-1985 lmd       getbpb() sets disk mode to "SAFE"
 * 4-Mar-1985 lmd       fixed bugs in proto_bt()
 * 9-Mar-1985 lmd       Added critical error handler hook
 * 13-Mar-1985 lmd      getbpb() returns NULL on read failure
 * 17-Mar-1985 lmd      Added write-verify switch
 * 22-Mar-1985 lmd      Added magic r/w mode to rwabs (rw = 2, 3)
 * 1-Apr-1985 lmd       Moved DSBs to flop.s (hooray!)
 * 8-Apr-1985 lmd       Cleaned up installable dev interface
 * 15-Apr-1985 lmd      Happy IRS day.
 * 15-Apr-1985 lmd      check for dev>=2 (only floppies allowed...)
 * 6-May-1985 lmd       Added access-timing depended UNSURE checking
 *-----
 */
#define MAXACCTIM      300L          /* 1.5seconds "free" time */

#define READ          0
#define WRITE          1

#define low8bits(x) ((x)&0xff)      /* unsigned coercion of char to int */

/*
 * Information we need from an IBM-PC-format
 * boot sector:
 */
#define VOL_SERIAL      0x08        /* (.A) 24-bit volume serial# */
#define IBM_BPS         0x0b        /* (.W) #bytes/sector */
#define IBM_SPC         0x0d        /* (.B) #sectors/cluster */
#define IBM_RES         0x0e        /* (.W) #reserved sectors */
#define IBM_NFATS        0x10        /* (.B) #FATs */
#define IBM_NDIRS        0x11        /* (.W) #root directory entries */
#define IBM_NSECTS        0x13        /* (.W) #sectors on media */
#define IBM_MEDIA        0x15        /* (.B) media descriptor byte */
#define IBM_SPF          0x16        /* (.W) #sectors/FAT */
#define IBM_SPT          0x18        /* (.W) #sectors/track */
#define IBM_NSIDES        0x1a        /* (.W) #sides on dev */
#define IBM_NHID         0x1c        /* (.W) #hidden sectors */

```

```

#define CRITICAL_RETRY 0x00010000L          /* "retry" return code */

/*
 * Error codes
 * Sort of like the PC-DOS ones
 */
#define OK 0                                /* the anti-error */
#define ERROR (-1)                         /* anti-success */
#define DRIVE_NOT_READY (-2)
#define UNKNOWN_CMD (-3)
#define CRC_ERROR (-4)
#define BAD_REQUEST (-5)
#define SEEK_ERROR (-6)
#define UNKNOWN_MEDIA (-7)
#define SECTOR_NOT_FOUND (-8)
#define NO_PAPER (-9)                      /* how can a disk do this? */
#define WRITE_FAULT (-10)
#define READ_FAULT (-11)
#define GENERAL_MISHAP (-12)              /* Captain_Catastrophe? */
#define WRITE_PROTECT (-13)
#define MEDIA_CHANGE (-14)
#define UNKNOWN_DEVICE (-15)
#define BAD_SECTORS (-16)                 /* bad sectors on media */
#define INSERT_DISK (-17)                 /* fake two drives */
#define WRONG_DISK_DUMMY (-18)           /* luser stuck in wrong disk */

/*
 * BPB structure
 * as defined by GEMDOS:
 */
struct bpb {
    WORD    recsiz,          /* physical sector size in bytes */
           clsiz,          /* cluster size in sectors */
           clsizb,         /* cluster size in bytes */
           rdlen,          /* root directory length in sectors */
           fsiz,           /* FAT size in sectors */
           fatrec,         /* sector# of 1st sector of 2nd FAT */
           datrec,         /* sector# of 1st data sector */
           numcl,          /* number of data clusters on disk */
           bflags;         /* various flags */
};

/*
 * Flags in bpb.bflags:
 */
#define BPB_16BIT_FAT 0x0001              /* indicates 16-bit FAT entries */

/*
 * "Device State Block"
 * as defined by us.

```

```

* The DSB is used by drivers to hold a device's state.
* Most devices require a pointer to this beastie as a parameter
* in their calls.
*/

```

```

struct dsb {
    /*
     * Loaded (or computed from) the boot sector:
     */
    struct bpb b; /* JDOS' BPB */
    WORD dntracks, /* #tracks (cylinders) on dev */
        dnslides, /* #sides per cylinder */
        dspc, /* #sectors/cylinder */
        dspt, /* #sectors/track */
        dhiddens; /* #hidden tracks */
    char dserial[3]; /* 24-bit volume serial number */
} dsbtab[2];

```

```

/*
 * Variables maintained by floppy vblank monitor:
 */
extern char wpstatus[]; /* write-protect status */
extern char wplatch[]; /* write-protect status latch */
extern WORD motoron; /* motor-on status (for both drives) */

```

```

/*
 * Other floppy variables:
 */
unsigned extern long hz_200; /* system timer tick */
extern char diskbuf[]; /* disk buffer somewhere in BSS */
extern int nflops; /* number of active floppies {0,1,2} */
unsigned extern long acctim[]; /* time of last floppy access */
long maxacctim; /* delay for floppy to turn UNSAFE */

char diskmode[2]; /* floppy mode {SAFE, UNSURE, CHANGED} */
int flopok[2]; /* 0: drive OK; -1: drive unusable */
int curflop; /* current floppy# inserted */

```

```

/*
 * Floppy modes
 * (states for disk-change detection)
 */
#define SAFE 0 /* media has definitely not changed */
#define UNSURE 1 /* media might have changed (we don't know) */
#define CHANGED 2 /* media has definitely changed */

```

```

/*
 * dskinit - initialize floppy drives
 */
dskinit()
{
    LONG getbpb();

```

```

extern LONG drvbits;

WORD i, j;
char *s, *d;

maxacctim = MAXACCTIM;
for (i = curflop = nflops = 0; i < 2; ++i)
{
    diskmode[i] = SAFE;
    if ((flopok[i] = flopini(OL, OL, i, 0, 0, 0)) == 0)
    {
        ++nflops;
        drvbits |= 3;
    }
}

}

/*
 * getdsb - return pointer to DSB
 */
LONG getdsb(dev)
WORD dev;
{
    return OL;
}

/*
 * getbpb - return pointer to BPB
 * Reset disk mode to "SAFE"
 */
long getbpb(dev)
WORD dev;
{
    register struct dsb *q;
    register struct bpb *p;
    register int i, j;
    char *s, *d;
    LONG ret, floprd(), critic();

    if (dev >= 2)
        return NULL;

    q = &dsbtab[dev];
    p = &q->b;

    /* only floppies here */
    /* can't do much ... */

    /* Read the boot sector.
     * Compute the DOS BPB from the MSDOS one.
     */
    do {
        ret = floprd(diskbuf, OL, dev, 1, 0, 0, 1);
        if (ret < 0) ret = critic((WORD)ret, dev);
    } while (ret == CRITICAL_RETRY);
}

```

```

if (ret < 0) return NULL;

/*
 * If recsiz or clsiz turns out to be zero,
 * don't attempt to use the BPB.
 */
if (!(i = u2i(diskbuf + IBM_BPS)) ||
    !(j = low8bits(diskbuf[IBM_SPC])))
    return NULL;

/*
 * Build the BPB from the MSDOS-format information:
 */
p->recsiz = i;
p->clsiz = j;
p->fsiz = u2i(diskbuf + IBM_SPF);
p->fatrec = p->fsiz + 1;
p->clsizb = p->recsiz * p->clsiz;
p->rdlen = (u2i(diskbuf + IBM_NDIRS) << 5) / p->recsiz;
p->datrec = p->fatrec + p->rdlen + p->fsiz;
p->numcl = (u2i(diskbuf + IBM_NSECTS) - p->datrec) / p->clsiz;

q->dnsides = u2i(diskbuf + IBM_NSIDES);           /* "extra" info */
q->dspt = u2i(diskbuf + IBM_SPT);
q->dspc = q->dnsides * q->dspt;
q->dhhidden = u2i(diskbuf + IBM_NHID);
q->dntracks = u2i(diskbuf + IBM_NSECTS) / q->dspc;

for (i = 0; i < 3; ++i)                          /* copy serial# */
    q->dserial[i] = diskbuf[VOL_SERIAL + i];

/* make safe/unsure */
diskmode[dev] = (wplatch[dev] == wpstatus[dev]) ? UNSURE : SAFE;

return (long)q;                                  /* return BPB ptr */
}

/*
 * mediach - determine if media has changed
 * Return SAFE if the media definitely has not changed.
 * Return UNSURE if we're not sure if it's changed.
 * Return CHANGED if we're sure the media changed.
 */
WORD mediach(dev)
WORD dev;
{
    register WORD dv;
    register char *dm;

    if (dev >= 2)                                /* only floppies here */
        return UNKNOWN_DEVICE;
}

```

```

dv = dev;
dm = &diskmode[dv];

if (*dm == CHANGED) return CHANGED;          /* always hack CHANGED */
if (wplatch[dv]) *dm = UNSURE;               /* ==> UNSURE */
if ((hz_200 - acctim[dv]) < maxacctim)      /* SAFE if within time limit */
    return SAFE;
return *dm;                                  /* return UNSURE or SAFE */
}

/*
 * rwabs - read multiple sectors from dev, into a buffer:
 */
LONG rwabs(rw, buf, count, recno, dev)
WORD rw;
LONG buf;
WORD count, recno, dev;
{
    register int i;
    register WORD dv;
    register LONG rtn;
    register struct dsb *p;
    LONG ret;
    WORD mediach();
    LONG floprw();

    if (dev >= 2)                             /* only floppies here */
        return UNKNOWN_DEVICE;

    dv = dev;

    if (rw < 2)
    {
        p = &dsbtabs[dv];

        /*
         * Check for media change.
         * If the media is UNSAFE, then read the boot sector to
         * determine if the media really was changed.
         * If the media was changed, return an error to the caller.
         */
        i = mediach(dv);
        if (i == CHANGED) return MEDIA_CHANGE;
        else if (i == UNSURE)
        {
            /*
             * Read boot sector and compare volume's serial number with
             * the one in the DSB.
             */
            do {
                ret = floprd(diskbuf, OL, dv, 1, 0, 0, 1);
                if (ret < 0) ret = critic((WORD)ret, dv);
            } while (ret == CRITICAL_RETRY);
            if (ret < 0) return ret;
        }
    }
}

```

```

        for (i = 0; i < 3; ++i)
            if (diskbuf[VOL_SERIAL + i] != p->dserial[i])
                return MEDIA_CHANGE;

        /* Reset write-protect latch */
        if (!(wplatch[dv] = wpstatus[dv]))
            diskmode[dv] = SAFE;
    }
}

if (!nflops) return DRIVE_NOT_READY;
if (rw > 1) rw -= 2; /* fix magic r/w */
return floprw(rw, buf, recno, dv, count);
}

/*
 * floprw - floppy read/write sectors
 */
LONG floprw(rw, buf, recno, dev, count)
WORD rw;
LONG buf;
WORD recno, dev, count;
{
    LONG critic(), flopver(), floprd(), floprw();
    int u2i();
    extern WORD fverify;

    register struct dsb *p;
    register LONG ret;
    register WORD track, side, sect, cnt;
    WORD oddflag;
    LONG bf;

    p = &dsbtab[dev];
    oddflag = ((buf & 1) == 1);
    if (!p->dspc) /* "cannot happen" */
        p->dspt = p->dspc = 9;

    /*
     * Read or write sectors.
     * Optimize for multi-sector transfers
     * (as much of a track as possible):
     */
    while (count)
    {
        bf = oddflag ? diskbuf : buf; /* choose a buffer */
        track = recno / p->dspc; /* compute track# */
        sect = recno % p->dspc; /* compute sector# */
        if (sect < p->dspt) /* single-sided media */
            side = 0;
        else /* two-sided media */
        {
            side = 1;
            sect -= p->dspt;
        }
    }
}

```

```

    }
    if (oddflag) cnt = 1; /* unaligned: read 1 sector */
    else if ((p->dspt - sect) < count) /* rest of track */
        cnt = p->dspt - sect; /* part of track */
    else cnt = count;

    ++sect; /* physical sector number */

    do {
        if (rw) /* write */
        {
            if (bf != buf) fastcpy(buf, bf);
            ret = floplr(bf, OL, dev, sect, track, side, cnt);

            if (!ret && fverify) /* verify */
            {
                ret = floplr(diskbuf, OL,
                               dev, sect, track, side, cnt);
                if (!ret && u2i(diskbuf))
                    ret = BAD_SECTORS;
            }
        }
        else /* read */
        {
            ret = floprd(bf, OL, dev, sect, track, side, cnt);
            if (bf != buf) fastcpy(bf, buf);
        }

        if (ret < 0)
            ret = critic((WORD)ret, dev);
    } while (ret == CRITICAL_RETRY);
    if (ret < 0) return ret;

    buf += ((long)cnt << 9); /* advance DMA pointer */
    recno += cnt; /* bump record number */
    count -= cnt; /* decrement count */
}

return OK; /* success! */
}

```

```
#ifndef DAS_BOOT
```

```

/*
 * Random number generator parameters.
 * (from Knuth, vol II)
 */
#define RAND_A 3141592621L /* multiplier */
#define RAND_C 1 /* incremter */

LONG seed; /* seed (zeroed at powerup) */

/*
 * Return a 24-bit random number.
 * If the seed is zero (uninitialized)
 * then use the frame clock, slightly

```

```

    * munged, as a starting value.
    */
LONG rand()
{
    extern LONG hz_200;                /* raw 200-hz system timer counter */

    if (!seed) seed = hz_200 ; (hz_200 << 16);
    seed = (RAND_A * seed + RAND_C);
    return (seed >> 8) & 0xffffffff;
}
#endif

#define BOOT_MAGIC      0x1234          /* magic boot-sector checksum */

/*
 * Error returns:
 */
#define NO_DRIVE        1                /* no floppy attached */
#define COULDNT_LOAD    2                /* couldn't read boot sector */
#define UNREADABLE      3                /* unreadable boot sector */
#define NOT_VALID_BS    4                /* boot sector not executable */

/*
 * Boot from floppy or hard disk.
 * Returns OK if diskbuf[] contains an executable
 * boot sector.
 */
boot()
{
    extern WORD _hinit();
    extern WORD bootdev;
    extern LONG floprd();
    register WORD err;

    /*
     * Initialize disk system:
     */
    hinit();

    /*
     * Attempt to load boot sector from floppy "bootdev":
     */
    err = nflops ? NO_DRIVE : COULDNT_LOAD;
    if (nflops && (bootdev < 2))
    {
        if (!floprd(diskbuf, 0L, bootdev, 1, 0, 0, 1))
            err = OK;
        else if (!wpstatus[0]) return UNREADABLE;
    }
    if (err != OK) return err;

    /*

```

```

    * Successfully loaded boot sector from somewhere,
    * check it out:
    */
    return (checksum(diskbuf, 0x100) == BOOT_MAGIC) ? OK : NOT_VALID_BS;
}

```

```

#ifndef DAS_BOOT

```

```

/*
 * Prototype BPBs for floppies;
 * used to construct boot sectors.
 */
char proto_tab[] =
{
    /* 40 tracks single sided */
    0x00, 0x02, 0x01, 0x01, 0x00, 0x02, 0x40, 0x00, 0x68, 0x01,
    0xfc, 0x02, 0x00, 0x09, 0x00, 0x01, 0x00, 0x00, 0x00,

    /* 40 tracks double sided */
    0x00, 0x02, 0x02, 0x01, 0x00, 0x02, 0x70, 0x00, 0xd0, 0x02,
    0xfd, 0x02, 0x00, 0x09, 0x00, 0x02, 0x00, 0x00, 0x00,

    /* 80 tracks single sided */
    0x00, 0x02, 0x02, 0x01, 0x00, 0x02, 0x70, 0x00, 0xd0, 0x02,
    0xf8, 0x05, 0x00, 0x09, 0x00, 0x01, 0x00, 0x00, 0x00,

    /* 80 tracks double sided */
    0x00, 0x02, 0x02, 0x01, 0x00, 0x02, 0x70, 0x00, 0xa0, 0x05,
    0xf9, 0x05, 0x00, 0x09, 0x00, 0x02, 0x00, 0x00, 0x00
};

```

```

/*
 * Prototype a boot sector. (this is a strange function...)
 *
 * 'serial' is the disk's volume ID (or -1 not to initialize).
 * If serial > 0xffffffff, it is replaced by a different, random serial number
 *
 * 'dsktyp' is the disk size (0, 1, 2, 3), or -1 not to initialize.
 *
 * If 'execflg' is 1, the boot sector is made executable (bootable);
 * If 'execflg' is 0, the boot sector is g'teed NOT to be executable;
 * If 'execflg' is -1, keep the boot sector the way it was passed
 * (it will stay executable or non-executable, no matter what other
 * changes were made to it).
 */

```

```

WORD proto_bt(buf, serial, dsksiz, execflg)
char *buf;
LONG serial;
WORD dsksiz, execflg;
{
    long rand();
    register int i, j;

```

```

register char *s;
WORD *p, w;

/*
 * If execflg < 0, determine if boot sector is already executable.
 * Whatever the case, make sure the sector /stays/ the way it
 * came to us.
 */
if (execflg < 0)
    execflg = (checksum(buf, 0x100) == BOOT_MAGIC);

/*
 * Install volume ID
 */
if (serial >= 0)
{
    if (serial > 0x00ffffff)
        serial = rand();
    for (i = 0; i < 3; ++i)
    {
        buf[VOL_SERIAL + i] = serial & 0xff;
        serial >>= 8;
    }
}

/*
 * Install BPB
 */
if (dsksize >= 0)
{
    j = dsksize * 19;
    for (i = 0; i < 19; ++i)
        buf[IBM_BPS + i] = proto_tab[j++];
}

/*
 * Make the sector executable or non-executable.
 */
w = 0;
for (p = buf; p < (buf + 0x1fe);)
    w += *p++;
*p = BOOT_MAGIC - w;
if (!execflg) ++(*p);
}
#endif

/*
 * Compute checksum of a number of 16-bit words.
 */
WORD checksum(p, cnt)
WORD *p;

```

```
int cnt;
{
    register WORD i;

    for (i = 0; cnt--;)
        i += *p++;
    return i;
}
```

```
/*
 * Convert an 8086-flavored integer
 * to a 68000 integer.
 */
int u2i(loc)
char *loc;
{
    return (low8bits(*(loc+1)) << 8) | low8bits(*loc);
}
```

```

das_boot      equ      0
*-----*
*
*      130-ST / 520-ST
*      Floppy Disk Driver
*      (C)1985 Atari Corp.
*
* 22-Feb-1985 lmd      Added write-protect and motor-on monitoring.
* 22-Feb-1985 lmd      Substituted format-track for format-disk.
* 23-Feb-1985 lmd      Multiple-sector DMA in _floprd.
* 25-Feb-1985 lmd      _flopwr understands "ccount" (but cannot do
*                       multi-sector DMA -- a hardware constraint).
* 25-Feb-1985 lmd      Added "virgin" parameter to _flopfmt
* 27-Feb-1985 lmd      _flopwr() can write an entire track in one
*                       revolution of the disk....
* 28-Feb-1985 lmd      _floprd() doesn't do reseek on seek error
*                       (it takes too long)
* 4-Mar-1985 lmd      Added "bad sector" return to _flopfmt
* 7-Mar-1985 lmd      Fixed bug in _flopfmt bad sector return
* 8-Mar-1985 lmd      Fixed "floplock" and "flopulok" to save and
*                       restore C registers.
* 10-Mar-1985 lmd     Added "disk flip" code (hook to _critic)
* 13-Mar-1985 lmd     If single-floppy system, copy drive 0's write-
*                       protect transitions to drive 1.
* 13-Mar-1985 lmd     Set _wplatch after disk flip
* 13-Mar-1985 lmd     Return reasonable error numbers
* 17-Mar-1985 lmd     Added _flopver()
* 21-Mar-1985 lmd     dasBoot assembly switches, default seek rate
* 22-Mar-1985 lmd     format_track sets media change mode to CHANGED
* 22-Mar-1985 lmd     a write to the boot sector sets the media
*                       change mode to UNSURE.
* 28-Mar-1985 lmd     Force write-protect to "real time" mode
*                       on any exit from the driver.
* 1-Apr-1985 lmd      Moved floppy DSBs to here.
* 1-Apr-1985 lmd      Based variables off of zero-page
* 8-Apr-1985 lmd      Moved flock out of here to public basepage
* 30-Apr-1985 lmd     Disk errors set media-change mode to UNSURE
* 1-May-1985 lmd      Bug in _flopini; mis-use of args on stack
* 6-May-1985 lmd      Set _motoron nonzero on any floppy command.
*                       Added _acctim[] timer variables.
*-----*
text

*----- Tunable values (subject to tweaking):
retries      equ      2          ; default # of retries - 1
midretry     equ      1          ; "middle" retry (when to reseek)
timeout      equ      $40000     ; short timeout (motor already on)
ltimeout     equ      $60000     ; long timeout (to startup motor)

*----- Exports:
.globl _flopini          ; init floppy          func
.globl _floprd          ; read sector          func
.globl _flopvbl        ; vertical blank monitor      func

```

```

ifeq das_boot
    .globl _flopwr           ; write sector           func
    .globl _flopfmt         ; format drive/track    func
    .globl _flopver         ; verify sectors        func
endc

    .globl _wpstatus        ; write-protect state (2 drives)
    .globl _wplatch        ; write-protect latch (2 drives)
    .globl _motoron        ; motor-on status (1 byte, both drives)
    .globl _acctim         ; time (200 hz tick) of last access

```

\*----- Imports:

```

.globl flock                ; floppy/FIFO lock variable
.globl _frclock            ; vbl-frame-counter
.globl _nflops             ; number of floppy drives attached
.globl _curflop            ; currently inserted floppy
.globl _critic             ; critical error handler
.globl seekrate            ; default floppy seek rate
.globl _diskmode           ; disk change mode
.globl _hz_200             ; 200 hz timer ticker

```

\*----- media change modes:

```

m_changed    equ    2      ; "CHANGED" media
m_ensure     equ    1      ; "UNSURE" about media change

```

\*----- Error returns

```

e_error      equ    -1     ; general catchall
e_nready     equ    -2     ; drive-not-ready
e_crc        equ    -4     ; CRC error
e_seek       equ    -6     ; seek error
e_rnf        equ    -8     ; record (sector) not found
e_write      equ    -10    ; generic write error
e_read       equ    -11    ; generic read error
e_wp         equ    -13    ; write on write-protected media
e_badsects   equ    -16    ; bad sectors on format-track
e_insert     equ    -17    ; insert_a_disk

```

\*----- Floppy state variables in DSB:

```

recal        equ    $fff0  ; recalibrate flag (in dcurtrack)
dcurtrack    equ    0      ; current track#
dseekrt      equ    dcurtrack+2 ; floppy's seek-rate
dsbsiz       equ    dseekrt+2 ; (size of a DSB)

```

\*--- DMA chip:

```

diskctl      equ    $ffff8604 ; disk controller data access
fifo         equ    $ffff8606 ; DMA mode control / status
dmahigh      equ    $ffff8609 ; DMA base high
dmamid       equ    $ffff860b ; DMA base medium

```

```

dmalow          equ      $ffff860d      ; DMA base low

*--- 1770 select values:
cmdreg          equ      $80            ; select command register
trkreg          equ      $82            ; select track register
secreg          equ      $84            ; select sector register
datareg         equ      $86            ; select data register

*--- GI ("psg") sound chip:
giselect        equ      $ffff8800     ; (W) sound chip register select
giread          equ      $ffff8800     ; (R) sound chip read-data
giwrite         equ      $ffff8802     ; (W) sound chip write-data
giporta         equ      $e            ; GI register# for I/O port A

*--- 68901 ("mfp") sticky chip:
mfp             equ      $fffffa00     ; mfp base
gpip            equ      mfp+1         ; general purpose I/O

```

```

**
*
* SYNOPSIS (synopsisi?):
*
* _flopini(dsb, OL, devno)
* _floprd(dsb, buf, devno, sectno, trackno, sideno, count)
* _flopwr(dsb, buf, devno, sectno, trackno, sideno, count)
* _flopfmt(dsb, buf, devno, spt, trackno, sideno, interlv, magicno, virgin)
* _flopvbl()
* _flopver(dsb, buf, devno, sectno, trackno, sideno, count)
*
* An "EQ" return means success. Zero is returned in DO.W.
* An "NE" return means failure. Some negative error number is return in DO.W.
*
* Parameter types (in general):
*     LONG dsb, buf;
*     WORD devno, sectno, trackno, count;
*     WORD spt, interlv, virgin;
*     LONG magicno;
*
*--

```

```

**
* flopini - initialize floppies
* Passed (on the stack):
*     $c(sp) devno
*     $8(sp) ->DSB
*     $4(sp) ->buffer (unused)
*     $0(sp) return address
*

```

```
* Returns:      EQ if initialization succeeded (drive attached).
*              NE if initialization failed (no drive attached).
*-
```

```
_flopini:
    lea    dsb0,a1          ; get ptr to correct DSB
    tst.w  $c(sp)
    beq    fi_1
    lea    dsb1,a1

fi_1:   move.w  seekrate,dseekrt(a1) ; setup default seek rate
        moveq  #e_error,d0        ; (default error)
        clr.w  dcurtrack(a1)      ; fake clean drive
        bsr   floplock           ; setup parameters
        bsr   select             ; select drive and side
        move.w #recal,dcurtrack(a1) ; default = recal drive (it's dirty)

        bsr   restore           ; attempt restore
        beq   fi_ok             ; (quick exit if that won)
        moveq #10,d7            ; attempt seek to track 10
        bsr   hseek1            ; (hard seek to 'd7')
        bne   fi_nok            ; (failed: drive unusable)
        bsr   restore           ; attempt restore after seek
fi_ok:  beq   flop              ; return OK (on win)
fi_nok: bra   flopfail          ; return failure
```

```
**
* floprd - read sector from floppy
* Passed (on the stack):
*   $14(sp) count
*   $12(sp) sideno
*   $10(sp) trackno
*   $e(sp) sectno
*   $c(sp) devno
*   $8(sp) ->DSB
*   $4(sp) ->buffer
*   $0(sp) return address
*
```

```
* Returns:      EQ, the read won (on all sectors),
*              NE, the read failed (on some sector).
*-
```

```
_floprd:
    bsr   change              ; test for disk change
    moveq #e_read,d0         ; set default error#
    bsr   floplock           ; lock floppies, setup parameters
frd1:  bsr   select           ; select drive, setup registers
        bsr   go2track       ; seek appropriate track
        bne   frde           ; retry on seek failure

        move.w #e_error,curr_err ; set general error#
        move.w #$090,(a6)        ; toggle DMA data direction,
        move.w #$190,(a6)        ; leave hardware in READ state
        move.w #$090,(a6)
        move.w ccount(a5),diskctl ; set sector count register
        move.w #$080,(a6)        ; startup 1770 "read sector" command
```

```

    move.w  #90,d7                ; (read multiple)
    bsr     wdiskctl
    move.l  #timeout,d7          ; set timeout count
    move.l  edma(a5),a2          ; a2 -> target DMA address

*--- Wait for read completion:
frd2:     btst.b  #5,gpip          ; 1770 done yet?
          beq     frd4             ; (yes)
          subq.l  #1,d7           ; decrement timeout counter
          beq     frd3             ; (punt on timeout)
          move.b  dmahigh,tmpdma+1(a5) ; get hardware DMA pointer
          move.b  dmamid,tmpdma+2(a5) ; (most significant bytes FIRST)
          move.b  dmalow,tmpdma+3(a5)
          cmp.l   tmpdma(a5),a2    ; if(tmpdma < edma) continue;
          bgt     frd2

          bsr     reset1770        ; we're done -- interrupt controller
          bra     frd4             ; see if the read won

*--- timeout: reset the controller and retry:
frd3:     move.w  #e_nready,curr_err(a5) ; set "timeout" error
          bsr     reset1770        ; (clobber 1770)
          bra     frde             ; (go retry)

*--- check status after read:
frd4:     move.w  #090,(a6)        ; examine DMA status register
          move.w  (a6),d0
          btst   #0,d0            ; bit zero indicates DMA error
          beq    frde             ; (when its zero -- retry)

          move.w  #080,(a6)        ; examine 1770 status register
          bsr     rdiskctl
          and.b   #18,d0           ; check for RNF, checksum, lost-data
          beq    flopok           ; return OK if no errors
          bsr     err_bits         ; set error# from 1770 bits
frde:     cmp.w   #midretry,retrycnt(a5) ; are we on the "middlemost" retry?
          bne    frd5
frde1:    bsr     reseek           ; yes, home and reseek the head
frd5:     subq.w  #1,retrycnt(a5)  ; drop retry count
          bpl    frd1             ; (continue if any retries left)
          bra    flopfail         ; fail when we run out of patience

*+
* err_bits - set "curr_err" according to 1770 error status
* Passed:    d0 = 1770 status
*
* Returns:   curr_err, containing current error number
*
* Uses:     d1
*-
err_bits:
          moveq   #e_wp,d1         ; write protect?
          btst   #6,d0
          bne.s  ebl

```

```

        moveq    #e_rnf,d1          ; record-not-found?
        btst    #4,d0
        bne.s   ebl
        moveq    #e_crc,d1          ; CRC error?
        btst    #3,d0
        beq     ebl
ebl:    move     def_error(a5),d1    ; use default error#
        move.w  d1,curr_err(a5)    ; set current error number & return
        rts

```

```

ifeq das_boot
**
* flopwr - write sector to floppy
* Passed (on the stack):
*   $14(sp) count
*   $12(sp) sideno
*   $10(sp) trackno
*   $e(sp) sectno
*   $c(sp) devno
*   $8(sp) ->DSB
*   $4(sp) ->buffer (unused)
*   $0(sp) return address
*
* Returns:      EQ, the write won (on all sectors),
*              NE, the write failed (on some sector).
*-

```

```

_flopwr:
        bsr     change              ; check for disk swap
        moveq   #e_write,d0        ; set default error number
        bsr     floplock           ; lock floppies

```

```

**
* If the boot sector is written to,
* set the media change mode to "unsure".
* (Kludge, kludge, kludge....)
*-

```

```

        move.w  csect(a5),d0        ; sector 1
        subq   #1,d0
        or.w   ctrack(a5),d0       ; track 0
        or.w   cside(a5),d0        ; side 0
        bne   fwr1                  ; if not boot sector, then OK
        moveq  #m_changed,d0       ; set media change mode to unsure
        bsr   setdmode              ; (boy, is this /ugly/)

fwr1:   bsr     select              ; select drive
        bsr     go2track            ; seek
        bne   fwr1                  ; (retry on seek failure)
fwr1a:  move.w  #e_error,curr_err(a5) ; set general error#
        move.w  #$190,(a6)          ; toggle DMA chip to clear status
        move.w  #$090,(a6)
        move.w  #$190,(a6)          ; leave in WRITE mode
        move.w  #1,d7               ; load sector-count register
        bsr   wdiskctl

```

```

        move.w  #180,(a6)           ; load "WRITE SECTOR" command
        move.w  #a0,d7             ; into 1770 cmdreg
        bsr     wdiskctl           ;
        move.l  #timeout,d7       ; d7 = timeout count

fwr2:   btst.b  #5,gpip            ; done yet?
        beq     fwr4               ; (yes, check status)
        subq.l  #1,d7              ; decrement timeout count
        bne     fwr2               ; (still tickin')
        bsr     reset1770          ; timed out -- reset 1770
        bra     fwr               ; and retry

fwr4:   move.w  #180,(a6)          ; get 1770 status
        bsr     rdiskctl           ;
        bsr     err_bits           ; compute 1770 error bits
        btst   #6,d0              ; if write protected, don't retry
        bne     flopfail          ; (can't write, so punt)
        and.b  #5c,d0             ; check WriteProt+RecNtFnd+CHKSUM+LostD
        bne     fwr               ; retry on error

        addq.w  #1,csect(a5)       ; bump sector number
        add.l  #200,cdma(a5)       ; and DMA pointer for next sector
        subq.w  #1,ccount(a5)     ; if(!--count) return OK;
        beq     flopok            ;
        bsr     select1           ; setup sector#, DMA pointer
        bra     fwr1a            ; write next (no seek)

fwr5:   cmp.w   #midretry,retrycnt(a5) ; re-seek head in "middle" retry
        bne     fwr5              ; (not middle retry)
fwr1:   bsr     reseek            ; home head and seek
fwr5:   subq.w  #1,retrycnt(a5)    ; decrement retry count
        bpl     fwr1              ; loop if there's still hope
        bra     flopfail          ; otherwise return error status

```

\*\*

```

* _flopfmt - format a track
* Passed (on the stack):
*   $1a(sp) initial sector data
*   $16(sp) magic number
*   $14(sp) interleave
*   $12(sp) side
*   $10(sp) track
*   $e(sp) spt
*   $c(sp) drive
*   $8(sp) pointer to state block
*   $4(sp) dma address
*   $0(sp) [return]
*

```

```

* Returns:   EQ: track successfully written. Zero.W-terminated list of
*            bad sectors left in buffer (they might /all/ be bad.)
*
*            NE: could not write track (write-protected, drive failure,
*            or something catastrophic happened).

```

\*-

\_flopfmt:

```

cmp.l    #$87654321,$16(sp)    ; check for magic# on stack
bne      flopfail              ; no magic, so we just saved the world
bsr      change                 ; check for disk flip
moveq    #e_error,d0           ; set default error number
bsr      flopflock              ; lock floppies, setup parms
bsr      select                 ; select drive and side
move.w   #e(sp),spt(a5)        ; save sectors-per-track
move.w   $14(sp),interlv(a5)   ; save interleave factor
move.w   $1a(sp),virgin(a5)    ; save initial sector data

*--- put drive into "changed" mode
moveq    #m_changed,d0         ; d0 = "CHANGED"
bsr      setdmode              ; set media change mode

*--- seek to track (hard seek):
bsr      hseek                  ; hard seek to 'ctrack'
bne      flopfail              ; (return error on seek failure)
move.w   ctrack(a5),dcurtrack(a1) ; record current track#

*--- format track, then verify it:
move.w   #e_error,curr_err(a5) ; vanilla error mode
bsr      fmtrack                ; format track
bne      flopfail              ; (return error on seek failure)
move.w   spt(a5),ccount(a5)    ; set number of sectors to verify
move.w   #1,csect(a5)          ; starting sector# = 1
bsr      verify1               ; verify sectors

*--- if there are any bad sectors, return /that/ error...
move.l   cdma(a5),a2           ; a2 -> bad sector list
tst.w   (a2)                   ; any bad sectors?
beq      flopok                 ; no -- return OK
move.w   #e_badsects,curr_err(a5) ; set error number
bra      flopfail              ; return error

**
* fmtrack - format a track
* Passed:      variables setup by _flopfmt
* Returns:     NE on failure, EQ on success
* Uses:        almost everything
* Called-by:   _flopfmt
*
*-
fmtrack:
move.w   #e_write,def_error(a5) ; set default error number
move.w   #1,d3                  ; start with sector 1, first pass
move.l   cdma(a5),a2            ; a2 -> prototyping area
move.w   #60-1,d1               ; 60 x $4e (track leadin)
move.b   #$4e,d0
bsr      wmult

*--- address mark
ot3:     move.w   d3,d4           ; d4 = starting sector (this pass)
ot1:     move.w   #12-1,d1       ; 12 x $00
clr.b    d0
bsr      wmult

```

```

    move.w #3-1,d1 ; 3 x $f5
    move.b #$f5,d0
    bsr wmult
    move.b #$fe,(a2)+ ; $fe -- address mark intro
    move.b ctrack+1,(a2)+ ; track#
    move.b cside+1,(a2)+ ; side#
    move.b d4,(a2)+ ; sector#
    move.b #$02,(a2)+ ; sector size (512)
    move.b #$f7,(a2)+ ; write checksum

*--- gap between AM and data:
    move.w #22-1,d1 ; 22 x $4e
    move.b #$4e,d0
    bsr wmult
    move.w #12-1,d1 ; 12 x $00
    clr.b d0
    bsr wmult
    move.w #3-1,d1 ; 3 x $f5
    move.b #$f5,d0
    bsr wmult

*--- data block:
    move.b #$fb,(a2)+ ; $fb -- data intro
    move.w #256-1,d1 ; 256 x virgin.W (initial sector data)
ot2:  move.b virgin(a5),(a2)+ ; copy high byte
    move.b virgin+1(a5),(a2)+ ; copy low byte
    dbra d1,ot2 ; fill 512 bytes
    move.b #$f7,(a2)+ ; $f7 -- write checksum
    move.w #40-1,d1 ; 40 x $4e
    move.b #$4e,d0
    bsr wmult

    add.w interlv(a5),d4 ; bump sector#
    cmp.w spt(a5),d4 ; if(d4 <= spt) then_continue;
    ble ot1 ; proto more sectors this pass
    add.w #1,d3 ; bump pass start count
    cmp.w interlv(a5),d3 ; if(d3 <= interlv) then_continue;
    ble ot3

*--- end-of-track
    move.w #1400,d1 ; 1401 x $4e -- end of track trailer
    move.b #$4e,d0
    bsr wmult

*--- setup to write the track:
    move.b cdma+3(a5),dmalow ; load dma pointer
    move.b cdma+2(a5),dmamid
    move.b cdma+1(a5),dmahigh
    move.w #$190,(a6) ; toggle R/W flag and
    move.w #$090,(a6) ; select sector-count register
    move.w #$190,(a6) ; (absurd sector count)
    move.w #$1f,d7
    bsr wdiskctl
    move.w #$180,(a6) ; select 1770 cmd register
    move.w #$f0,d7 ; write format_track command
    bsr wdiskctl

```

```

        move.l  #timeout,d7                ; d7 = timeout value

*--- wait for 1770 to complete:
otw1:   btst.b  #5,gpip                    ; is 1770 done?
        beq    otw2                        ; (yes)
        subq.l #1,d7                       ; if(--d7) continue;
        bne   otw1
        bsr   reset1770                    ; timed out -- reset 1770
oterr:  moveq  #1,d7                       ; return NE (error status)
        rts

*--- see if the write-track won:
otw2:   move.w  #$190,(a6)                 ; check DMA status bit
        move.w  (a6),d0
        btst   #0,d0                       ; if its zero, there was a DMA error
        beq    oterr                       ; (so return NE)
        move.w  #$180,(a6)                 ; get 1770 status
        bsr   rdiskctl
        bsr   err_bits                     ; set 1770 error bits
        and.b  #$44,d0                     ; check for writeProtect & lostData
        rts                                ; return NE on 1770 error

*----- write 'D1+1' copies of DO.B into A2, A2+1, ...
wmult:  move.b  d0,(a2)+                   ; record byte in proto buffer
        dbra   d1,wmult                    ; (do it again)
        rts

**
* _flopver - verify sectors on a track
*   $14(sp) count
*   $12(sp) sideno
*   $10(sp) trackno
*   $e(sp) sectno
*   $c(sp) devno
*   $8(sp) -->DSB
*   $4(sp) -->buffer (at least 1K long)
*   $0(sp) return address
*
* Returns:  NULL.W-terminated list of bad sectors in the buffer if DO == 0,
*           OR some kind of error (DO < 0).
*
*-
_flopver:
        bsr   change                       ; hack disk change
        moveq #e_read,d0                   ; set default error#
        bsr   flopload                      ; lock floppies, setup parameters
        bsr   select                        ; select floppy
        bsr   go2track                      ; go to track
        bne   flopfail                      ; (punt if that fails)
        bsr   verify1                       ; verify some sectors
        bra   flopok                        ; return "OK"

```

\*\*

```

* verify1 - verify sectors on a single track
* Passed:      csect = starting sector#
*              ccount = number of sectors to verify
*              cdma -> 1K buffer (at least)
*
* Returns:     NULL, W-terminated list of bad sectors (in the buffer)
*              (buffer+$200..buffer+$3ff used as DMA buffer)
*
* Environment: Head seeked to the correct track;
*              Drive and side already selected;
*              Motor should be spinning (go2track and fmtrack do this).
*
* Uses:        Almost everything.
*
* Called-by:   _flopfmt, _flopver
*
*-

```

```

verify1:
    move.w    #e_read, def_error(a5)    ; set default error number
    move.l    cdma(a5), a2              ; a2 -> start of bad sector list
    add.l     #$200, cdma(a5)           ; bump buffer up 512 bytes

*--- setup for (next) sector
tvr1p:      move.w    #retries, retrycnt(a5) ; init sector-retry count
            move.w    #secreg, (a6)        ; load 1770 sector register
            move.w    csect(a5), d7       ; with 'csect'
            bsr      wdiskctl

*--- setup for sector read
tvr1:       move.b    cdma+3(a5), dmalow    ; load dma pointer
            move.b    cdma+2(a5), dmamid
            move.b    cdma+1(a5), dmahigh
            move.w    #$090, (a6)          ; toggle R/W (leave in W state)
            move.w    #$190, (a6)
            move.w    #$090, (a6)
            move.w    #1, d7              ; set DMA sector count to 1
            bsr      wdiskctl
            move.w    #$080, (a6)        ; load 1770 command register
            move.w    #$80, d7           ; with ReadSector command
            bsr      wdiskctl
            move.l    #timeout, d7       ; set timeout value

*--- wait for command completion
tvr2:       btst.b    #5, gpip            ; test for 1770 done
            beq      tvr4                ; (yes, it completed)
            subq.l    #1, d7              ; decrement timeout count
            bne      tvr2                ; (still counting down)
            bsr      reset1770           ; reset controller and return error
            bra      tvre

*--- got "done" interrupt, check DMA status:
tvr4:       move.w    #$090, (a6)        ; read DMA error status
            move.w    (a6), d0
            btst     #0, d0              ; if DMA_ERROR is zero, then retry
            beq      tvre

```

```

*--- check 1770 completion status (see if it's happy):
    move.w  #$080,(a6)           ; read 1770 status register
    bsr    rdiskctl
    bsr    err_bits             ; set error# from 1770 register
    and.b  #$1c,d0              ; check for record-not-found, crc-err,
    bne    tvre                 ; and lost data; return on error

```

```

*--- read next sector (or return if done)
tvr6:  addq.w  #1,csect(a5)      ; bump sector count
       subq.w  #1,ccount(a5)    ; while(--count) read_another;
       bne    tvrlp
       sub.l   #$200,cdma(a5)   ; readjust DMA pointer
       clr.w   (a2)            ; terminate bad sector list
       rts                    ; and return EQ

```

```

*--- read failure: retry or record bad sector
tvre:  cmp.w   #midretry,retrycnt(a5) ; re-seek head?
       bne    tvr5             ; (no)
       bsr    reseek           ; yes: back to home and then back
tvr5:  subq.w  #1,retrycnt(a5)    ; to the current track...
       bpl    tvr1
       move.w  csect(a5),(a2)+   ; record bad sector
       bra.s  tvr6             ; do next sector

endc

```

```

**
* _flopvbl - floppy vblank handler
* Deselects floppies after the motor stops.
*-

```

```

_flopvbl:
    clr.l   a5                 ; a5 -> zeropage base
    lea    fifo,a6            ; a6 -> fifo
    st.b   _motoron(a5)       ; assume motor is on
    tst.w  flock(a5)          ; floppies locked?
    bne    fvblr              ; (yes, so don't touch them)

```

```

*----- write-protect monitor:
    move.l  _frclock,d0        ; check a drive every 8 jiffies
    move.b  d0,d1              ; (save jiffy count)
    and.b   #7,d1              ; time yet?
    bne    fvbl1              ; (no)
    move.w  #cmdreg,(a6)      ; select 1770 command/status register

```

```

*--- select drive, record it's WP status:
    lsr.b   #3,d0              ; use bit 4 as drive# to check
    and.w   #1,d0              ; (keep only bit 0)
    lea    _wpstatus(a5),a0    ; a0 -> write-protect status table
    add.w   d0,a0              ; a0 -> WP-status table entry

    cmp.w   _nflops,d0         ; if(d0 == _nflops == 1)
    bne    fvbl2              ; d0 = 0;
    clr.w   d0
fvbl2:  addq.b  #1,d0           ; turn into drive-select bits
    lsl.b   #1,d0              ; (magic shift left)
    eor.b   #7,d0              ; invert select bits, select side 0

```

```

        bsr      setporta          ; set port A (d2 = old bits)
        move.w   diskctl,d0        ; get 1770 status
        btst    #6,d0             ; test Write-Protect status bit
        sne.b    (a0)              ; set WP status to $00 or $FF
        move.b   d2,d0            ; restore old drive-select bits
        bsr      setporta

fvb11:  move.w   _wpstatus(a5),d0   ; or _wpstatus into _wplatch
        or.w    d0,_wplatch(a5)    ; (catch any WP transitions)

*----- floppy deselect test:
        tst.w   deselflg(a5)       ; floppies already deselected?
        bne     fvb1r1             ; (yes, so don't do it again)

        bsr     rdiskctl           ; read 1770 status register
        btst    #7,d0             ; is the motor still on?
        bne     fvb1r             ; (yes, so don't deselect)
        move.b  #7,d0             ; deselect both drives
        bsr     setporta           ; (set bits 0..3 in portA of PSG)
        move.w  #1,deselflg(a5)    ; indicate floppies deselected
fvb1r1: clr.w   _motoron(a5)       ; indicate motor is OFF
fvb1r:  rts                       ; back to vbl

```

```

*+
* floplock - lock floppies and setup floppy parameters
*
* Passed (on the stack):
*   $18(sp) - count.W (sector count)
*   $16(sp) - side.W (side#)
*   $14(sp) - track.W (track#)
*   $12(sp) - sect.W (sector#)
*   $10(sp) - dev.W (device#)
*   $c(sp)  - obsolete.L
*   8(sp)   - dma.L (dma pointer)
*   4(sp)   - ret1.L (caller's return address)
*   0(sp)   - ret.L (floplock's return address)
*
* Passed:   D0.W = default error number
*-

```

```

floplock:
        movem.l d3-d7/a3-a6,regsave ; save C registers

        clr.l   a5                 ; a5 -> zeropage base
        lea    fifo,a6             ; a6 -> fifo
        st     _motoron            ; kludge motor state = ON
        move.w d0,def_error(a5)    ; set default error number
        move.w d0,curr_err(a5)     ; set current error number
        move.w #1,flock(a5)        ; tell vbl not to touch floppies
        move.l 8(sp),cdma(a5)       ; cdma -> /even/ DMA address
        move.w $10(sp),cdev(a5)     ; save device# (0..1)
        move.w $12(sp),csect(a5)    ; save sector# (1..9, usually)
        move.w $14(sp),ctrack(a5)   ; save track# (0..39..79)
        move.w $16(sp),cside(a5)    ; save side# (0..1)

```

```

        move.w  $18(sp),ccount(a5)      ; save sector count (1..spt)
        move.w  #retries,retrycnt(a5)  ; setup retry count

*--- pick a DSB:
        lea     dsb0(a5),a1
        tst.w   cdev(a5)
        beq     flock2
        lea     dsb1(a5),a1

*--- compute ending DMA address from count parameter:
flock2: moveq   #0,d7
        move.w  ccount(a5),d7          ; edma = cdma + (ccount * 512)
        lsl.w   #8,d7
        lsl.w   #1,d7
        move.l  cdma(a5),a0
        add.l   d7,a0
        move.l  a0,edma(a5)

*--- recalibrate drive (if it needs it)
        tst.w   dcurtrack(a1)          ; if (curtrack < 0) recalibrate()
        bpl     flockr

        bsr     select                 ; select drive & side
        clr.w   dcurtrack(a1)          ; we're optimistic -- assume winnage
        bsr     restore                ; attempt restore
        beq     flockr                 ; (it won)
        moveq   #10,d7                 ; attempt seek to track 10
        bsr     hseek1
        bne     flock1                 ; (failed)
        bsr     restore                ; attempt restore again
        beq     flockr                 ; (it won)
flock1: move.w  #recal,dcurtrack(a1)    ; complete failure (what can we do?)
flockr: rts

*+
* flopfail - unlock floppies and return error.
*
*-
flopfail:
        moveq   #m_ensure,d0           ; disk change mode = UNSURE
        bsr     setdmode
        move.w  curr_err(a5),d0        ; get current error number
        ext.l   d0
        bra.s   unlok1                 ; clobber floppy lock & return

*+
* flopok - unlock floppies and return success status:
*
*-
flopok: clr.l   d0                     ; return 0 (success)
unlok1: move.l  d0,-(sp)                ; (save return value)
        move.w  #datareg,(a6)          ; force WP to real-time mode
        move.w  dcurtrack(a1),d7       ; dest-track = current track
        bsr     wdiskctl
        move.w  #$10,d6                 ; cmd = seek w/o verify

```

```

        bsr      flopcmds          ; do it

        move.w   cdev, d0          ; set last-access time for 'cdev'
        lsl.w   #2, d0
        lea     _acctim, a0
        move.l   _hz_200(a5), (a0, d0.w)
        cmp.w   #1, _nflops       ; if (nflops == 1) set other time, too
        bne     unlock2
        move.l   _hz_200(a5), 4(a0) ; set last-accessed time for floppy 1

unlock2: move.l   (sp)+, d0        ; restore return value
        movem.l regsave, d3-d7/a3-a6 ; restore C registers
        clr.w   flock            ; unlock floppies
        rts

```

++

```

* hseek - seek to 'ctrack' without verify
* hseek1 - seek to 'd7' without verify
* hseek2 - seek to 'd7' without verify, keep current error number

```

```

*
* Returns:      NE on seek failure ("cannot happen"?)
*              EQ if seek wins

```

```

*
* Uses:        d7, d6, ...
* Jumps-to:    flopcmds
* Called-by:   _flopfmt, _flopini

```

\*

```

*-
hseek:  move.w   ctrack, d7          ; dest track = 'ctrack'
hseek1: move.w   #e_seek, curr_err  ; possible error = "seek error"
hseek2: move.w   #datareg, (a6)     ; write destination track# to data reg
        bsr      wdiskctl
        move.w   #$10, d6           ; execute "seek" command
        bra     flopcmds           ; (without verify...)

```

++

```

* reseek - home head, then reseek track
* Returns:      EQ/NE on success/failure
* Falls-into:   go2track

```

\*

\*-

```

reseek:
        move.w   #e_seek, curr_err  ; set "seek error"
        bsr      restore           ; restore head
        bne     go2trr            ; (punt if home fails)

        clr.w   dcurtrack(a1)      ; current track = 0
        move.w   #trkreg, (a6)     ; set "current track" reg on 1770
        clr.w   d7
        bsr      wdiskctl

        move.w   #datareg, (a6)    ; seek out to track five
        move.w   #5, d7

```

```

    bsr    wdiskctl          ; dest track = 5
    move.w #$10,d6
    bsr    flopcmds         ; seek
    bne    go2trr          ; return error on seek failure
    move.w #5,dcurtrack(a1) ; set current track#

```

\*+

```

* go2track - seek proper track
* Passed:    Current floppy parameters (ctrack, et al.)
* Returns:   EQ/NE on success/failure
* Calls:     flopcmds

```

\*-

```

go2track:
    move.w #e_seek,curr_err ; set "seek error"
    move.w #datareg,(a6)    ; set destination track# in
    move.w ctrack(a5),d7    ; 1770's data register
    bsr    wdiskctl        ; (write track#)
    moveq  #$14,d6         ; execute 1770 "seek_with_verify"
    bsr    flopcmds        ; (include seek-rate bits)
    bne    go2trr          ; return error on seek failure
    move.w ctrack(a5),dcurtrack(a1) ; update current track number
    and.b  #$18,d7        ; check for RNF, CRC_error, lost_data
go2trr:  rts              ; return EQ/NE on succes/failure

```

\*+

```

* restore - home head
* Passed:    nothing
* Returns:   EQ/NE on success/failure
* Falls-into: flopcmds

```

\*-

```

restore:
    clr.w  d6              ; $00 = 1770 "restore" command
    bsr    flopcmds       ; do restore
    bne    res_r          ; punt on timeout
    btst   #2,d7          ; test TRK00 bit
    eor    #$04,ccr       ; flip Z bit (return NE if bit is zero)
    bne    res_r          ; punt if didn't win
    clr.w  dcurtrack(a1)  ; set current track#
res_r:   rts

```

\*+

```

* flopcmds - floppy command (or-in seek speed bits from database)
* Passed:    d6.w = 1770 command
* Sets-up:   seek bits (bits 0 and 1) in d6.w
* Falls-into: flopcmd
* Returns:   EQ/NE on success/failure

```

\*-

```

flopcmds:
    move.w dseekrt(a1),d0 ; get floppy's seek rate bits
    and.b  #3,d0          ; OR into command
    or.b   d0,d6

```

```

**
* flopcmd - execute 1770 command (with timeout)
* Passed:      d6.w = 1770 command
*
* Returns:     EQ/NE on success/failure
*              d7 = 1770 status bits
*
*-
flopcmd:
    move.l  #timeout, d7          ; setup timeout count (assume short)
    move.w  #cmdreg, (a6)        ; select 1770 command register
    bsr    rdiskctl              ; read it to clobber READY status
    btst   #7, d0                ; is motor on?
    bne    flopcm                ; (yes, keep short timeout)
flopcm:   bsr    wdiskct6        ; write command (in d6)

flopci:   subq.l #1, d7          ; timeout?
    beq    flopcto              ; (yes, reset and return failure)
    btst.b #5, gpip             ; 1770 completion?
    bne    flopci              ; (not yet, so wait some more)
    bsr    rdiskct7            ; return EQ + 1770 status in d7
    clr.w  d6
    rts

flopcto:  bsr    reset1770       ; bash controller
    moveq  #1, d6              ; and return NE
    rts

```

```

**
* reset1770 - reset disk controller after a catastrophe
* Passed:    nothing
* Returns:   nothing
* Uses:     d7
*
*-
reset1770:
    move.w  #cmdreg, (a6)        ; execute 1770 "reset" command
    move.w  #$d0, d7
    bsr    wdiskctl
    move.w  #15, d7              ; wait for 1770 to stop convulsing
r1770:    dbra  d7, r1770        ; (short delay loop)
    bsr    rdiskct7            ; return 1770 status in d7
    rts

```

```

**
* select - setup drive select, 1770 and DMA registers
* Passed:   cside, cdev
* Returns:  appropriate drive and side selected
*
*-
select:
    clr.w  deselflg(a5)         ; floppies NOT deselected
    move.w  cdev(a5), d0        ; get device number
    addq.b  #1, d0              ; add and shift to get select bits
    lsl.b  #1, d0              ; into bits 1 and 2

```

```

or.w    cside(a5),d0      ; or-in side number (bit 0)
eor.b   #7,d0            ; negate bits for funky hardware select
and.b   #7,d0            ; strip anything else out there
bsr     setporta         ; do drive select

move.w  #trkreg,(a6)     ; setup 1770 track register
move.w  dcurtrack(a1),d7 ;      from current track number
bsr     wdiskctl         ;
clr.b   tmpdma(a5)      ; zero bits 24..32 of target DMA addr

```

\*--- alternate entry point: setup R/W parameters on 1770

select1:

```

move.w  #secreg,(a6)     ; setup requested sector_number from
move.w  csect(a5),d7    ;      caller's parameters
bsr     wdiskctl
move.b  cdma+3(a5),dmalow ; setup DMA chip's DMA pointer
move.b  cdma+2(a5),dmamid
move.b  cdma+1(a5),dmahigh
rts

```

\*+

\* setporta - set floppy select bits in PORT A on the sound chip

```

* Passed:    d0.b (low three bits)
* Returns:   d1 = value written to port A
*           d2 = old value read from port A
*
* Uses:      d1

```

\*-

setporta:

```

move    sr,-(sp)        ; save our IPL
or      #$0700,sr      ; start critical section
move.b  #giporta,giselect ; select port on GI chip
move.b  giread,d1      ; get current bits
move.b  d1,d2          ; save old bits for caller
and.b   #$ff-7,d1     ; strip low three bits there
or.b    d0,d1          ; or-in our new bits
move.b  d1,giwrite     ; and write 'em back out there
move    (sp)+,sr       ; restore IPL to terminate CS, return
rts

```

\*+

\* Primitives to read/write 1770 controller chip (DISKCTL register).

```

*
* The 1770 can't keep up with full-tilt CPU accesses, so
* we have to surround reads and writes with delay loops.
* This is not really as slow as it sounds.

```

\*-

```

wdiskctl6:    * write d6 to diskctl
              ;
              bsr    rwdelay    ;      delay
              move.w d6,diskctl ;      write it
              bra    rwdelay    ;      delay and return

```

```

wdiskctl1:   * write d7 to diskctl
              ;
              bsr    rwdelay    ;      delay

```

```

        move.w  d7,diskctl      ; write it
        bra     rwdelay        ; delay and return

rdiskct7:      * read diskctl into d7
        bsr     rwdelay        ; delay
        move.w  diskctl,d7     ; read it
        bra     rwdelay        ; delay and return

rdiskctl:     * read diskctl into d0
        bsr     rwdelay        ; delay
        move.w  diskctl,d0     ; read it

rwdelay:
        move    sr,-(sp)       ; save flags
        move.w  d7,-(sp)       ; save counter register
        move.w  #$20,d7        ; 0x20 seems about right...
rdly1:        dbra   d7,rwdly1  ; busy-loop: give 1770 time to settle
        move.w  (sp)+,d7       ; restore register, flags, and return
        move    (sp)+,sr
        rts

**
* change - check to see if the "right" floppy has been inserted
* On the stack:
*   $10(sp) - dev.W (device#)
*   $c(sp) - dsb.L (pointer to Device State Block)
*   8(sp) - dma.L (dma pointer)
*   4(sp) - ret1.L (caller's return address)
*   0(sp) - ret.L (change's return address)
*
* Returns:      both media "might have changed" condition
*
* Uses:         C registers
*
*--
change:
        cmp.w   #1,_nflops     ; if there are zero or two floppies
        bne    ch_r            ; then do nothing (return OK)
        move.w  $10(sp),d0     ; if cdev == _curflop
        cmp.w   _curflop,d0    ; (...current disk == current drive?)
        beq    ch_ok1         ; then return OK (but use drive #0)

*--- ask the user to stick in the other floppy (via critical error handler)
        move.w  d0,-(sp)       ; push disk# we want inserted
        move.w  #e_insert,-(sp) ; push "INSERT_A_DISK" error number
        bsr     _critic        ; use critical error handler and
        add.w   #4,sp          ; hope somebody handles it
        move.w  #$ffff,_wplatch ; set "might have changed" on both drvs
        move.w  $10(sp),_curflop ; set current disk#
ch_ok1:  clr.w   $10(sp)       ; use drive 0
ch_r:    rts

**
* setdmode - set drive-change mode

```

```
* Passed:      d0.b = mode to put current drive in (0, 1, 2)
* Uses:        a0
*
*--
```

```
setdmode:
    lea    _diskmode,a0          ; a0 -> disk mode table
    move.b d0,-(sp)             ; (save mode)
    move.w cdev(a5),d0          ; d0.w = drive# (index into table)
    move.b (sp)+,(a0,d0.w)      ; set drive's mode
    rts
```

```
__dskf: dc.b %10101110
        dc.b %11010110
        dc.b %10001100
        dc.b %00010111
        dc.b %11111011
        dc.b %10000000
        dc.b %01101010
        dc.b %00101011
        dc.b %10100110
        even
```

\*----- Floppy RAM usage:

```
        bss
retrycnt: ds.w    1          ; retry counter          (used)
_wpstatus: ds.b    2          ; WP status (2 drives)  status
_wplatch:  ds.b    2          ; WP latch (2 drives)   status
_acctim:   ds.l    2          ; last access counter
_motoron:  ds.w    1          ; motor-on-P (both drives) status
deselflg:  ds.w    1          ; deselect flag          state

cdev:      ds.w    1          ; device #               parm
ctrack:    ds.w    1          ; track number           parm
csect:     ds.w    1          ; sector number          parm
cside:     ds.w    1          ; side number            parm
ccount:    ds.w    1          ; sector count           parm
cdma:      ds.l    1          ; DMA address            parm
edma:      ds.l    1          ; ending DMA address     computed

spt:       ds.w    1          ; #sectors_per_track    flopfmt parm
interlv:   ds.w    1          ; interleave factor      flopfmt parm
virgin:    ds.w    1          ; fill data for sectors  flopfmt parm

tmpdma:    ds.l    1          ; temp for hardware DMA  image
def_error: ds.w    1          ; default error number
curr_err:  ds.w    1          ; current error number

regsave:   ds.l    9          ; save area for C registers
dsb0:      ds.b    dsbsiz    ; floppy 0's DSB
dsb1:      ds.b    dsbsiz    ; floppy 1's DSB
```

```
*****
*
*           ST SERIES BIOS SOURCE REV. A
*           THIS PORTION BY D. GETREU
*
*           copyright 1984,1985 atari corporation
*           all rights reserved
*
*****
```

```
**+
* rbios.s - character I/O routines
*
* Oct-Feb 84/85 dbg      Backed it up
* 13-Mar-1985 lmd       Ripped out 'conout' (now in escape.s)
* may 7,1985 dbg        conditional assembly added for country of origin
*                        (USA, UK/ITALY, GERMANY, FRANCE)
*
*--
```

```
**+ (lmd)
* Imports:
*
*--
```

```
    .globl  _timr_ms      ;timer C calibration
    .globl  etv_timer     ;system timer handoff vector
    .globl  _hz_200      ;timer c raw tick
    .globl  conterm       ;console configuration byte
    .globl  _dumpflg     ;flag to signal a screen dump(alt-HELP)
```

```
**+ (dbg)
* Exports:
*
*--
```

```
    .globl  kbshift
    .globl  pconfig
```

```
USA      equ      0
UK        equ      1
GERMANY  equ      2
FRANCE   equ      3
```

```
COUNTRY equ      USA      ;set country of origin to USA
*COUNTRY equ      UK       ;set country of origin to UK
*COUNTRY equ      GERMANY  ;set country of origin to GERMANY
*COUNTRY equ      FRANCE   ;set country of origin to FRANCE
```

```
*****
*
*           general equates for the rbp system rom
*
*****
```

```
*****
*
*          acia register commands
*
*****
```

```
rsetacia      equ      %00000011      ;reset acia
div64         equ      %00000010      ;set to clock line to /64
div16         equ      %00000001      ;set to clock line to /16
```

\* note the keyboard and midi units expect 8 bits/1 stop bit/no parity!!

```
protocol      equ      %00010100      ;set to 8 bit/1 stop/no parity
```

\* note the keyboard and midi units may allow for transmitting interrupts  
\* therefore we define all possible states here. we will  
\* assume that it is init'ed as bar/rtts=low, disabled.

```
rtsl         equ      %00000000      ;rts=low, interrupt disabled
rtsle        equ      %00100000      ;rts=low, interrupt enabled
rtshd        equ      %01000000      ;rts=high, interrupt disabled
rtsbrk       equ      %01100000      ;rts=low, interrupt disabled, break
```

\* note the keyboard and midi units may be allowed to  
\* send interrupts to the host

```
intron        equ      %10000000      ;interrupts enabled
introff       equ      %00000000      ;interrupts disabled
```

```
*****
*          acia status definitions
*****
```

```
rdrf          equ      %00000001
tdre          equ      %00000010
dcd           equ      %00000100
cts           equ      %00001000
fe            equ      %00010000
ovrn          equ      %00100000
pe            equ      %01000000
irq           equ      %10000000
```

\* control register "or" mask settings

```
c19200 equ 1
c9600  equ 1
c4800  equ 1
c3600  equ 1
c2400  equ 1
c2000  equ 1
c1800  equ 1
c1200  equ 1
c600   equ 1
c300   equ 1
```

```

c200 equ 1
c150 equ 1
c134 equ 1
c110 equ 1
c75 equ 2
c50 equ 2

```

\* timer data register settings

```

d19200 equ 1
d9600 equ 2
d4800 equ 4
d3600 equ 5 ;3840 baud -- % error of 6.66
d2400 equ 8
d2000 equ 10 ;1920 baud -- % error of 4.00
d1800 equ 11 ;1745 baud -- % error of 2.50
d1200 equ 16
d600 equ 32
d300 equ 64
d200 equ 96
d150 equ 128
d134 equ 143 ;134.26 baud -- % error of 0.19
d110 equ 175 ;109.71 baud -- % error of 0.26
d75 equ 64
d50 equ 96

```

```

*****
*
* g.i. sound chip ay-3-8910 definitions and init code
*
*****

```

gibase equ \$ffff8800

\* gi chip register offsets

```

giselect equ gibase+0 ;write data register word
rddata equ gibase+0 ;byte of register word
wrdata equ gibase+2 ;byte of register word

```

\* gi register select offset numbers

```

toneaf equ 0
toneac equ 1
tonebf equ 2
tonebc equ 3
tonecf equ 4
tonecc equ 5
noise equ 6
mixer equ 7
aamplt equ 8
bamplt equ 9
camplt equ 10
fienvlp equ 11
crenvlp equ 12
shenvlp equ 13

```

```

porta    equ      14
*
*        port a - outputs all!
*
*        d0 - side select
*        d1 - drive select 0
*        d2 - drive select 1
*        d3 - rts for rs-232
*        d4 - dtr for rs-232
*        d5 - centronics strobe
*        d6 - general purpose output
*        d7 - unassigned output
*

```

```

portb    equ      15      ;parallel i/o port

```

```

*****
*
*        68901 multifunction peripheral chip equates
*        (interrupt controller, timers, serial i/o)
*
*****

```

```

*        register and base addresses

```

```

mfp      equ      $fffffa01      ;base address, +1 offset !!!!!!!

```

```

*        system interrupt register offsets

```

```

gpip     equ      0      ;general purpose i/o
aer      equ      2      ;active edge register
ddr      equ      4      ;data direction register
iera     equ      6      ;interrupt enable register a
ierb     equ      8      ;interrupt enable register b
ipra     equ      10     ;interrupt pending register a
iprb     equ      12     ;interrupt pending register b
isra     equ      14     ;interrupt in-service register a
isrb     equ      16     ;interrupt in-service register b
imra     equ      18     ;interrupt mask register a
imrb     equ      20     ;interrupt mask register b
vr       equ      22     ;vector register

```

```

*        system timer registers offsets

```

```

tacr     equ      24     ;timer a control register
tbcr     equ      26     ;timer b control register
tcdr     equ      28     ;timer c and d control register
tadr     equ      30     ;timer a data register
tbdrr    equ      32     ;timer b data register
tcdr     equ      34     ;timer c data register
tddr     equ      36     ;timer d data register

```

```

*        rs232/rs422/async/sync serial i/o registers offsets

```

```

scr      equ      38     ;sync character register

```

```

ucr      equ      40          ;user's control register
rsr      equ      42          ;receiver status register
tsr      equ      44          ;transmitter status register
udr      equ      46          ;user data register
    
```

\* non-memory oriented equates for the ps282 port and timers

```

ctrls    equ      $13        ;control s
ctrlq    equ      $11        ;control q
xoff     equ      $13
xon      equ      $11
xonoff   equ      1          ;used to indicate xon/xoff protocol
    
```

\* timer relative locations

```

atimer   equ      0
btimer   equ      1
ctimer   equ      2
dtimer   equ      3
    
```

```

*****
*
*      last modified   9/17/84
*      created 9/04/84
*      by      david b. getreu
*
*      the following is the acia definitions for the keyboard
*      and midi interfacing.  the baud rate for the keyboard acia is
*      an amazing 7812.5, a new exciting industrial standard.
*      anyways, the appropriate chip setting for this acia is /64,
*      while that of the midi interface is /16.  it's baud rate is an
*      amazing 31250, another new exciting industrial standard.  the
*      500 khz signal to the acia comes off of the glue chip to both
*      the keyboard and midi acia tx/rx clocks.
*
*
*****
    
```

```

keyboard    equ      $ffffffc00    ;keyboard acia address base
midi        equ      $ffffffc04    ;midi acia address base
    
```

\* register offsets for acias'

```

comstat    equ      0          ;command/status registers
iodata     equ      2          ;keyboard data register
    
```

```

*****
*      ascii character definitions
*
*****
    
```

```

nul      equ      $00
soh      equ      $01
stx      equ      $02
    
```

```

etx      equ      $03
eot      equ      $04
enq      equ      $05
ack      equ      $06
bel      equ      $07
bs       equ      $08
ht       equ      $09
lf       equ      $0a
vt       equ      $0b
ff       equ      $0c
cr       equ      $0d
so       equ      $0e
si       equ      $0f
dle      equ      $10
dc1      equ      $11
dc2      equ      $12
dc3      equ      $13
dc4      equ      $14
nak      equ      $15
syn      equ      $16
etb      equ      $17
can      equ      $18
em       equ      $19
eof      equ      $1a      ;really 'sub' in ANSI ascii
esc      equ      $1b
fs       equ      $1c
gs       equ      $1d
rs       equ      $1e
us       equ      $1f
spc      equ      $20
del      equ      $7f

```

```

*****
*      exception vector assignment table equates and functions      *
*****

```

```

evsetsp  equ      $00      ;power-on reset supervisor stack pointer
evsetpc  equ      $04      ;power-on reset initial program counter
buserr   equ      $08      ;bus error
adrerr   equ      $0C      ;address error
illins   equ      $10      ;illegal instruction
zerodiv  equ      $14      ;zero divide
chkinst  equ      $18      ;chk instruction
trapvf   equ      $1C      ;trap on overflow
privldg  equ      $20      ;privileged instruction
trace    equ      $24      ;trace mode
lin1010  equ      $28      ;line 1010 emulator
lin1111  equ      $2C      ;line 1111 emulator
uninit   equ      $3C      ;uninitialized interrupt vector
spurint  equ      $60      ;spurious interrupt
hblank   equ      $68      ;horizontal blank interrupt
vblank   equ      $70      ;vertical blank interrupt
trap0    equ      $80      ;trap instruction 0
trap1    equ      $84      ;trap instruction 1
trap2    equ      $88      ;trap instruction 2
trap3    equ      $8C      ;trap instruction 3

```

```

trap4   equ    $90    ;trap instruction 4
trap5   equ    $94    ;trap instruction 5
trap6   equ    $98    ;trap instruction 7
trap7   equ    $9C    ;trap instruction 7
trap8   equ    $A0    ;trap instruction 8
trap9   equ    $A4    ;trap instruction 9
trap10  equ    $AB    ;trap instruction 10
trap11  equ    $AC    ;trap instruction 11
trap12  equ    $B0    ;trap instruction 12
trap13  equ    $B4    ;trap instruction 13
trap14  equ    $B8    ;trap instruction 14
trap15  equ    $BC    ;trap instruction 15
    
```

```

*****
*      interrupt priority table      *
*****
*                                     *
*      priority      vector          *
*      -----      - - - - -      *
*      0  low        00_0100 *      centronics busy          i0      *
*      1              00_0104 *      data carrier detect      i1      *
*      2              00_0108 *      clear-to-send          i2      *
*      3              00_010c *      gpu blt done           i3      *
*      4              00_0110 *      baud rate generator    (d)     *
*      5              00_0114 *      system timer          (c)     *
*      6              00_0118 *      midi/keyboard acia    i4      *
*      7              00_011c *      disk dma              i5      *
*      8              00_0120 *      horizontal blank counter (b) *
*      9              00_0124 *      tx error              *
*      10             00_0128 *      tx buffer empty      *
*      11             00_012c *      receive error        *
*      12             00_0130 *      receive buffer full  *
*      13             00_0134 *      user/application timer (a) *
*      14             00_0138 *      ringer indicator     i6      *
*      15 high       00_013c *      monochrome detect    i7      *
*****
    
```

```

prtint  equ    $100    ;centronics busy          (i0)
dcd232  equ    $104    ;dcd rs-232 interrupt vector (i1)
cts232  equ    $108    ;cts rs-232 interrupt vector (i2)
bltdon  equ    $10C    ;graphics blt done interrupt (i3)
baudrg  equ    $110    ;baud rate generator interrupt timer d
unused  equ    $114    ;system clock interrupt    timer c
midkey  equ    $118    ;midi/keyboard interrupt   (i4)
dskdma  equ    $11C    ;disk dma interrupt        (i5)
hblnkc  equ    $120    ;horizontal blank counter   timer b
txderr  equ    $124    ;transmitter error interrupt
txbufe  equ    $128    ;transmitter buffer empty interrupt
rxderr  equ    $12C    ;receiver error interrupt
rxbufe  equ    $130    ;receiver buffer full interrupt
sysclk  equ    $134    ;free...free...free...     timer a
rng232  equ    $138    ;ringer indicator rs-232    (i6)
monitr  equ    $13C    ;monochrome monitor detect  (i7)
    
```

```
*****
*           operating system memory space           *
*****
```

```
*
*           rs-232/midi/keyboard offset equates for their i/o buffer records
*
```

```
ibufptr      equ      0      ;input buffer location pointer
ibufsiz      equ      4      ;maximum size of this buffer
ibufhead     equ      6      ;relative pointer to next byte to be taken from
*            ;this buffer
ibuftail     equ      8      ;relative pointer to next location available to
*            ;insert a new byte
ibuflow      equ      10     ;amount of space in buffer before an "xon" may
*            ;be sent to restore normal use of buffer.
ibufhigh     equ      12     ;amount of space used in buffer that trigger's
*            ;the sending of a "xoff" signal to the host
obufptr      equ      14     ;buffer location pointer
obufsiz      equ      18     ;maximum size of this buffer
obufhead     equ      20     ;relative pointer to next byte to be taken from
*            ;this buffer
obuftail     equ      22     ;relative pointer to next location available to
*            ;insert a new byte
obuflow      equ      24     ;amount of space in buffer before an "xon" may
*            ;be sent to restore normal use of buffer.
obufhigh     equ      26     ;amount of space used in buffer that trigger's
*            ;the sending of a "xoff" signal to the host
status       equ      28     ;copy of midi acia status
rsrbyte      equ      28     ;copy of rs-232 receiver status byte
tsrbyte      equ      29     ;copy of rs-232 transmitter status byte
rxoff        equ      30     ;rs-232 receiver xoff flag
txoff        equ      31     ;rs-232 transmitter xoff flag
rsmode       equ      32     ;rs-232 control mode
```

.bss

```
rinsize      equ      $100   ;these are size equates, not location
routsize     equ      $100   ;these are size equates, not location

ribuffer     ds.b    rinsize  ;rs-232 input buffer
robuffer     ds.b    routsize ;rs-232 output buffer

kinsize      equ      $80
kibuffer     ds.b    kinsize  ;keyboard input buffer

minsize      equ      $80
mibuffer     ds.b    minsize  ;midi input buffer
```

```
*
*           mfp rs232 port routines variable space
*
```

```
ribufptr     ds.l    1
```

```

ribufsiz      ds.w      1
ribufhead     ds.w      1
ribuftail     ds.w      1
ribufflow     ds.w      1
ribufhigh     ds.w      1
robufptr      ds.l      1
robufsiz      ds.w      1
robufhead     ds.w      1
robuftail     ds.w      1
robufflow     ds.w      1
robufhigh     ds.w      1
rrsrbyte      ds.b      1
rtsrbyte      ds.b      1
rrxoff        ds.b      1
rtxoff        ds.b      1
rrsmode       ds.b      2
rbufrec       equ       ribufptr

```

```

*
*      keyboard rs232 port routines variable space
*

```

```

kibufptr      ds.l      1
kibufsiz      ds.w      1
kibufhead     ds.w      1
kibuftail     ds.w      1
kibufflow     ds.w      1
kibufhigh     ds.w      1
kbufrec       equ       kibufptr

```

```

*
*      midi rs232 port routines variable space
*

```

```

mibufptr      ds.l      1
mibufsiz      ds.w      1
mibufhead     ds.w      1
mibuftail     ds.w      1
mibufflow     ds.w      1
mibufhigh     ds.w      1
mbufrec       equ       mibufptr

```

```

*      Acia error handler vectors -- init'ed to point to 'rte' unless
*      changed subsequent to boot-up

```

```

midivec       ds.l      1      ;midi interrupt handler vector
vkbderr       ds.l      1      ;keyboard error handler address
vmiderr       ds.l      1      ;midi error handler address
statintvec    ds.l      1      ;general ikbd status record interrupt vector
msintvec      ds.l      1      ;mouse interrupt vector
clkintvec     ds.l      1      ;ikbd real-time clock interrupt vector
joyintvec     ds.l      1      ;general joystick interrupt vector

```

```

*
*      real-time clock command equates
*
settod equ    $1b
gettod equ    $1c

*
*      kstate (ikbd's general state variable) values
*
normal equ    0
stats equ    1
amouse equ    2
rmouse equ    3
clock equ    4
joyall equ    5
joy0 equ     6
joy1 equ     7

*
*      array lengths for ikbd subsystem records
*

statdex equ    7
amdex equ     5
rmdex equ     3
clkdex equ     6
joydex equ     2
joydex equ     1

kstate        ds.b    1      ; present state of ikbd reception routine
kindex        ds.b    1      ; index used to count down bytes left to
*             ; receive for current state's record
statrec       ds.b    statdex
amrec         ds.b    amdex
mousebuf      ds.b    rmdex
clkrec        ds.b    clkdex
joyrec        ds.b    joydex

datetime      ds.l    1      ; jdos variable
newtime       ds.l    1      ; jdos variable
oclkrec       ds.b    clkdex ; used to assemble and send a new t.o.d. record
*             ; to the ikbd

on            equ    1
off           equ    0

kmbuf         ds.b    3      ; key-emulating mouse buffer

* bit assignments in kbshift

KBRSH EQU     0      * right shift
KBLSH EQU     1      * left shift
KBCTL EQU     2      * control key
KBALT EQU     3      * alternate key
KBCL EQU      4      * caps lock

```

```

KBMRB EQU 5 * right mouse button (clr/home)
KBMLB EQU 6 * left mouse button (insert)

kbshift ds.b 1

initsize equ kbshift-kstate-1 ; area to be inited to zero!

skeytran ds.l 1 ; contains address for unshifted key translation
skeyshif ds.l 1 ; contains address for shifted key translation
skeycl ds.l 1 ; contains address for caps-lock key translation

* mouse init transfer string buffer

transbuf ds.b 17 ; temporary string buffer for mouse init's

* keyrepeat variables

timerate equ 200 ; timer c rate in Hz.

keyrep ds.b 1
kdelay1 ds.b 1 ; must start on word boundary
kdelay2 ds.b 1
cdelay1 ds.b 1 ; must start on word boundary
cdelay2 ds.b 1
tdelay1 equ 15 ; delay before key repeat engages
tdelay2 equ 2 ; delay before key repeats after
* ; key repeat is activated

* parallel timeout counter

prt_to ds.l 1

tc_rot ds.w 1 ; divisor byte for timer c interrupt

*
* Dave Staugas' Sound Driver variables
*
cursnd ds.l 1
timer ds.b 1
auxd ds.b 1

*
* printer configuration word
*
* bits 6-15 not defined
*
* bit 5 - printer uses (_FORMFEED/SINGLE SHEET)
* bit 4 - port to send output to (_ATARI/EPSON)
* bit 3 - style of output (_DRAFT/FINAL)
* bit 2 - type of printer (_DOT MATRIX/DAISY WHEEL)
* bit 1 - type of ink (_MONOCHROME/COLOR)
* bit 0 - manufacturer (_ATARI/EPSON COMPATIBLE)
*
* note all underscored settings are the default and are represented
* by their corresponding bit set to "0"

```

pconfig ds.w 1

\* console and terminal enable flags
\* bit 0 - keyclick enabled
\* bit 1 - repeat key function enabled
\* bit 2 - keyboard "^g" bell feature enabled

\*conterm ds.b 1 ;now in landon's equates

newtod ds.b 1 ;handshaking flag for get time of day function

page
even
text

\*\*\*\*\*
\* cp/m-68k atari rbp bios
\* basic input/output subsystem
\* copyright 1984, atari corporation
\* all rights reserved.
\* atari confidential
\*
\*\*\*\*\*

\*\*\*\*\*
\* convert ikbd real-time clock format to jdos format
\*
\*\*\*\*\*

jdostime

lea \$0, a5 ;address pointer to address base
lea clkrec(a5), a0
bsr bcdbin
subi.b #80, d0 ;adjust so that 1980 => 0 for time base
move.b d0, d2
asl.l #4, d2

bsr bcdbin
add.b d0, d2
asl.l #5, d2

bsr bcdbin
add.b d0, d2
asl.l #5, d2

bsr bcdbin
add.b d0, d2
asl.l #6, d2

bsr bcdbin
add.b d0, d2
asl.l #5, d2

```

    bsr      bcdbin
    lsr.b   d0          ;adjust to provide two second increments...
    add.b   d0,d2      ;...another @!#%@$% kludge, thank you !
    move.l  d2,datetime(a5)
    move.b  #$0,newtod(a5) ;clear handshaking flag
    rts

```

```

*****
*
*           get time of day
*
*   entry:
*
*   long    gettime()
*
*****

```

.globl gettime

```

gettime
    move.b  #0,newtod(a5) ;set handshaking flag
    move.b  #gettod,d1    ;send get time of day command
    bsr     ikbdput
gtod1
    tst.b   newtod(a5)    ;see if the new time of day is in yet.
    bne.b   gtod1
    move.l  datetime(a5),d0
    rts

```

```

*****
*
*           set time of day
*
*   entry:
*
*   void    settime(newtime)
*   long    newtime
*
*****

```

.globl settime

```

settime
    move.l  4(sp),newtime(a5)

```

```

*****
*
*   convert jdos format to ikbd real-time clock format
*
*****

```

.globl ikbdtime

```

ikbdtime
    lea    oclkrec+clkdex,a0 ;point to end of output clock buffer
    move.l newtime(a5),d2    ;get time to convert
    move.b d2,d0             ;make a copy for conversion routine

```

```

andi.b    #%00011111,d0    ;mask off for pertinent information
asl.b     d0                ;correct for the two second kludge
bsr.b     binbcd           ;convert
lsr.l     #5,d2            ;shift to next information field

move.b    d2,d0            ;make a copy for conversion routine
andi.b    #%00111111,d0    ;mask off for pertinent information
bsr.b     binbcd           ;convert
lsr.l     #6,d2            ;shift to next information field

move.b    d2,d0            ;make a copy for conversion routine
andi.b    #%00011111,d0    ;mask off for pertinent information
bsr.b     binbcd           ;convert
lsr.l     #5,d2            ;shift to next information field

move.b    d2,d0            ;make a copy for conversion routine
andi.b    #%00011111,d0    ;mask off for pertinent information
bsr.b     binbcd           ;convert
lsr.l     #5,d2            ;shift to next information field

move.b    d2,d0            ;make a copy for conversion routine
andi.b    #%00001111,d0    ;mask off for pertinent information
bsr.b     binbcd           ;convert
lsr.l     #4,d2            ;shift to next information field

move.b    d2,d0            ;make a copy for conversion routine
andi.b    #%01111111,d0    ;mask off for pertinent information
bsr.b     binbcd           ;convert
addi.b    #$80,(a0)        ;re-correct for ikbd format from jdos kludge

move.b    #settod,d1       ;send set time-of-day command to ikbd
bsr       ikbdput          ;use "inner circle" entry point!
moveq     #clkdex-1,d3     ;prepare to send new parameters
lea       oclkrec,a2       ;point to parameter list to be sent
bsr       ikbdstr          ;again, use an "inner circle" entry point!
move.b    #gettod,d1       ;send get time-of-day command to ikbd
bsr       ikbdput          ;use "inner circle" entry point!
rts

```

```

*****
*
*           convert a byte from binary to bcd format
*
*   entry:  d0.l  - value
*
*****

```

```

.globl binbcd

binbcd
moveq     #0,d1
moveq     #10,d3
bin2
sub.b     d3,d0
bmi.b     bin1
addq.b    #1,d1
bra.b     bin2

```

```

bin1    addi.b  #10,d0
        asl.b   #4,d1
        add.b   d1,d0
        move.b  d0,-(a0)    ;transfer to output clock buffer
        rts
    
```

```

*****
*
*          convert a byte from bcd format to binary
*
*  entry:  a0.l  - pointer to byte
*
*****
    
```

.globl bcdbin

```

bcdbin
    moveq    #$0,d0
    move.b   (a0),d0    ;get bcd byte
    lsr.b    #4,d0      ;dump low nibble
    lsl.b    d0         ;generate (y1 shl 1)
    move.b   d0,d1     ;copy (y1 shl 1)
    asl.b    #2,d0     ;generate (y1 shl 3)
    add.b    d1,d0     ;generate (y1 shl 3) + (y1 shl 1)
    move.b   (a0)+,d1  ;grab bcd again for low nibble
    andi.w   #$f,d1    ;mask off for low nibble
    add.w    d1,d0     ;generate completed binary version of bcd byte
    rts
    
```

```

*****
*
*          midi output status
*
*  entry:
*
*  word    midiost()
*
*  returns true/okay to send = -1,  false/not ready = 0
*
*****
    
```

.globl midiost

```

midiost
    moveq    #-$1,d0    ;pre-set to true
    move.b   comstat+midi,d2 ;grab midi status
    btst.l   #1,d2
    bne.b    midiox    ;status okay to send
    moveq    #$0,d0    ;status not okay
midiox    rts
    
```

```

*****
*
*          write char to midi port
*
*  entry:
*
*****
    
```

```

*
*      void      midiwc(chr)
*      word      chr
*
*****

```

```

        .globl  midiwc

```

```

midiwc  move.w   6(sp),d1
midiput lea     midi,a1      ;point to midi register base
midput1 move.b  comstat(a1),d2 ;grab midi status
        btst.l  #$1,d2
        beq.b  midput1
        move.b  d1,iodata(a1)
        rts                    ;done for now

```

```

*****
*
*      put string to midi routine
*
*      entry:
*
*      void      midiws(size,ptr)
*      word      size
*      long      ptr
*
*****

```

```

        .globl  midiws

```

```

midiws  moveq    #$0,d3
        move.w  4(sp),d3      ;get size of string buffer - 1
        move.l  6(sp),a2      ;get string address
midp1   move.b  (a2)+,d1
        bsr.b  midiput
        dbra   d3,midp1
        rts

```

```

*****
*
*      get midi receiver buffer status
*
*      entry:
*
*      word      midstat()
*
*      -1 signifies true/okay  0 - signifies false/no characters
*
*****

```

```

        .globl  midstat

```

```

midstat lea     mbufrec(a5),a0 ;point to midi i/o bufrec
        lea     midi,a1      ;point to midi register base
        moveq   #-1,d0       ;set result to true

```

```

    lea    ibufhead(a0),a2
    lea    ibuftail(a0),a3
    cmpm.w (a3)+,(a2)+    ;atomic buffer empty test
    bne.b  midist1        ;branch if not, assume d0 is "clr.w" 'ed
    moveq  #$0,d0         ;set result to false
midist1 rts

```

```

*****
*
*           getchar routine for midi port
*
*   this routine transfers characters from a input queue that is
*   filled by an automatic interrupt routine.  the interrupt
*   routine handles the actual transfer of the character from the
*   i/o port.
*
*   entry:
*
*   long   midin()
*
*   long data returned represents upper three bytes of time stamp
*   and least significant byte as data
*
*****

```

.globl midin

midin

```

*   assume that a0/a1 are inited by the midstat call for the rest of
*   this routine.

    bsr.b  midstat        ;see if key pressed
    tst.w  d0
    beq.b  midin          ;wait until byte comes in
    move   sr,-(sp)       ;protect this upcoming test
    ori    #$700,sr
    move.w ibufhead(a0),d1 ;get current head pointer offset from buffer
    cmp.w  ibuftail(a0),d1 ;head=tail?
    beq.b  mwi2           ;yes

*   check for wrap of pointer

    addq.w #1,d1          ;i=h+1
    cmp.w  ibufsiz(a0),d1 ;? i>= current bufsiz?
    bcs.b  mwil           ;no...
    moveq  #$0,d1         ;wrap pointer
mwil    move.l ibufptr(a0),a1 ;get base address of buffer
        move.b 0(a1,d1),d0    ;get character
        move.w  d1,ibufhead(a0) ;store new head pointer to buffer record
mwi2    move   (sp)+,sr
        rts

```

```

*****
*

```

```

*           parallel i/o port service routine
*
*   this set of routines is for general parallel i/o
*
*   entry to listout
*
*   entry to listin
*
*   exit from listin
*
*****

```

```

.globl _lstout

```

```

_lstout

```

```

move.l _hz_200(a5),d2 ; d2 = hz_200 - prt_to
sub.l  prt_to(a5),d2 ; (compute time since last timeout)
cmpi.l #5*200,d2    ; do "fake" timeout if we timed out within
bcs.b  lperr        ; the last five seconds

```

```

pt0    move.l _hz_200(a5),d2 ; d2 = starting time for this char
      bsr.b  _lstostat      ; go get parallel port status
      tst.w  d0             ; ...and check for high (busy)
      bne.b  pt1           ; port is ready -- print the char

```

```

move.l _hz_200(a5),d3 ; d3 = hz_200 - d2
sub.l  d2,d3
cmpi.l #30*200,d3     ; check for 30 second delta
blt.b  pt0            ; continue if no timeout

```

```

lperr  moveq  #$0,d0      ; return value of 0 indicates timeout
      move.l _hz_200(a5),prt_to(a5) ; record time of last timeout
      rts

```

```

pt1    move.w  sr,d3      ; save status register
      ori.w  #$700,sr     ; protect upcoming switching of the port setting
      moveq  #mixer,d1    ; get current io enable register contents
      bsr    gientry
      ori.b  #$80,d0      ; set port b for output
      moveq  #mixer+$80,d1 ; set to write to io enable
      bsr    gientry
      move.w d3,sr        ; restore status register

```

```

move.w 6(sp),d0          ; retrieve byte to be sent and...
moveq  #portb+$80,d1    ; write out byte to parallel port
bsr    gientry

```

```

bsr.b  strobeon
bsr.b  strobeoff
moveq  #-$1,d0          ; set d0=-1 for good transfer status
lexit  rts

```

```

strobeoff
moveq  #%00100000,d2    ; set strobe off
bra    onbit            ; go set it!!

```

```

strobeon
    moveq    #%11011111,d2    ;set strobe on
    bra     offbit            ;set strobe now...

    .globl  _lstin

_lstin
    moveq    #mixer,d1        ;get current io enable register contents
    bsr     gientry
    andi.b   #$7f,d0          ;set port b for input
    moveq    #mixer+$80,d1    ;set to write to io enable
    bsr     gientry

    bsr.b   strobeoff        ;busy off!

lstibusy
    bsr.b   _lstostat        ;go get parallel port status
    tst.w   d0                ;...and check for high (busy)
    bne.b   lstibusy         ;loop till high...
    bsr.b   strobeon
    moveq    #portb,d1        ;init to use gientry routine to read
    bra     gientry          ;now get the byte from the parallel port
*
*                               ;d0.l contains the byte of data from the port
*
*                               the 'bra' is implied rts from this routine

*****
*
*                               parallel port status routine
*
*****
    .globl  _lstostat

_lstostat
    lea     mfp,a0            ;point to mfp register base
    moveq   #-$1,d0          ;pre-init to true (parallel port ready)
    btst.b  #$0,gpip(a0)
    beq.b   lst1
    moveq   #$0,d0           ;parallel port busy

lst1
    rts

*****
*
*                               auxillary port input status routine
*
*****
    .globl  auxistat

auxistat
    lea     rbufrec(a5),a0    ;point to rs-232 buffer record
    moveq   #-$1,d0          ;set result to true
    lea     ibufhead(a0),a2
    lea     ibuftail(a0),a3
    cmpm.w  (a3)+,(a2)+      ;atomic buffer empty test
    bne.b   auxist1
    moveq   #$0,d0          ;set result to false
    
```

auxist1 rts

```
*****
*
*          auxillary input routine
*
*****
```

.globl auxin

```
auxin  bsr.b   auxistat    ;see if key pressed
       tst.w   d0
       beq.b   auxin      ;wait until key pressed
       bsr    rs232get
       andi.w  #$ff,d0    ;clear out the high byte
       rts
```

```
*****
*
*          auxillary port output status routine
*
*****
```

.globl \_auxostat

\_auxostat

```
       lea    rbufrec(a5),a0 ;point to rs-232 buffer record
       moveq  #%-1,d0        ;set result to true
       move.w obuftail(a0),d2 ;get current tail pointer offset from buffer
       bsr    wrapout       ;check for wrap of pointer
       cmp.w  obufhead(a0),d2 ;head=tail?
       bne.b  auxost1      ;no...there is buffer space left!
       moveq  #$0,d0        ;set result to false
```

auxost1 rts

```
*****
*
*          auxillary output routine
*
*****
```

.globl \_auxout

```
_auxout move.w 6(sp),d1    ;get data
        bsr    rs232put   ;exit via rs-232 output routine
        bcs.b  _auxout
        rts
```

```
*****
*
*          ikbd output status
*
*          entry:
*
*          word   ikbdost()
*
*****
```

```
* returns true/okay to send = -1, false/not ready = 0 *
*
*****
```

```
.globl ikbdost
```

```
ikbdost
    moveq    #-1,d0          ;pre-set to true
    move.b   comstat+keyboard,d2 ;grab ikbd status
    btst.l   #$1,d2
    bne.b    ikbdox         ;status okay to send
    moveq    #$0,d0          ;status not okay
ikbdox    rts
```

```
*****
*
*           write char to ikbd port
*
* entry:
*
* void      ikbdwc(chr)
* word      chr
*
*
*****
```

```
.globl ikbdwc
```

```
ikbdwc  move.w  6(sp),d1
ikbdput lea    keyboard,a1    ;point to ikbd register base
ikput1  move.b  comstat(a1),d2 ;grab keyboard status
        btst.l  #$1,d2
        beq.b  ikput1
        move.b  d1,iodata(a1)
        rts          ;done for now
```

```
*****
*
*           put string to ikbd routine
*
* entry:
*
* void      ikbdws(size,ptr)
* word      size
* long      ptr
*
*****
```

```
.globl ikbdws
```

```
ikbdws  moveq    #$0,d3
        move.w   4(sp),d3
        move.l   6(sp),a2
ikbdstr move.b   (a2)+,d1
        bsr.b    ikbdput
```

```

    dbra    d3, ikbdstr
    rts

    .globl  constat

constat
    lea    kbufrec(a5), a0    ;point to ikbd buffer record
    moveq  #-1, d0           ;set result to true
    lea    ibufhead(a0), a2
    lea    ibuftail(a0), a3
    cmpm.w (a3)+, (a2)+      ;atomic buffer empty test
    bne.b  const1           ;branch if not, assume d0 is "clr.w"ed
    moveq  #$0, d0          ;set result to false
const1   rts

    .globl  conin

conin    bsr.b  constat      ;see if key pressed
         tst.w  d0
         beq.b  conin        ;wait until key pressed
         move   sr, -(sp)     ;protect this upcoming test
         ori    #$700, sr
         move.w ibufhead(a0), d1 ;get current head pointer offset from buffer
         cmp.w  ibuftail(a0), d1 ;head=tail?
         beq.b  cwi2         ;yes

*        check for wrap of pointer

         addq.w #2, d1        ;i=h+2
         cmp.w  ibufsiz(a0), d1 ;? i>= current bufsiz?
         bcs.b  cwil         ;no...
         moveq  #$0, d1      ;wrap pointer
cwil     move.l ibufptr(a0), a1 ;get base address of buffer
         moveq  #$0, d0      ;clear out for jdos format
         move.w 0(a1, d1), d0 ;get character
         move.w d1, ibufhead(a0) ;store new head pointer to buffer record
         lsl.l  #$8, d0      ;shift the scancode only to the low byte
         lsr.w  #$8, d0      ;high word location for jdos
cwi2     move   (sp)+, sr
         rts

    .globl  conoutst

conoutst
    moveq  #-1, d0
    rts    ;jdos requirement

    .globl  ringbel

ringbel
    btst.b  #$2, conterm(a5)
    beq.b  rgbel
    move.l  #bellsnd, cursnd(a5)
    move.b  #0, timer(a5)
rgbel    rts

```

```

*****
*
*   end of gemdos bios portion
*
*   device driver and auxillary routines follow
*
*****

```

ifeq COUNTRY-USA

keytran:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', '-', '=', $0B, $09
dc. b 'q', 'w', 'e', 'r', 't', 'y', 'u', 'i'
dc. b 'o', 'p', '[', ']', $0D, $00, 'a', 's'
dc. b 'd', 'f', 'g', 'h', 'j', 'k', 'l', ';'
dc. b $27, '\', $00, '\', 'z', 'x', 'c', 'v'
dc. b 'b', 'n', 'm', ',', '.', '/', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keyshif:

```

dc. b $00, $1b, '!', '@', '#', '$', '%', '^'
dc. b '&', '*', '(', ')', '/', '+', $0B, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', '{', '}', $0D, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', ';'
dc. b '"', '~', $00, '|', 'Z', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', '<', '>', '?', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $37
dc. b $38, $00, '-', $34, $00, $36, '+', $00
dc. b $32, $00, $30, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keycl:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', '-', '=', $0B, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', '[', ']', $0D, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', ';'

```

```

dc. b $27, '\', $00, '\', 'Z', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', ',', ', ', ' ', ' ', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', ' ', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

. endc

ifeq COUNTRY-UK

keytran:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', '-', '=', $08, $09
dc. b 'q', 'w', 'e', 'r', 't', 'y', 'u', 'i'
dc. b 'o', 'p', '[', ']', $0D, $00, 'a', 's'
dc. b 'd', 'f', 'g', 'h', 'j', 'k', 'l', ';'
dc. b $27, '\', $00, '#', 'z', 'x', 'c', 'v'
dc. b 'b', 'n', 'm', ',', ', ', ' ', ' ', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

```

```

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '\', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', ' ', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keyshif:

```

dc. b $00, $1b, '!', '"', $9c, '$', '%', '^'
dc. b '&', '*', '(', ')', '_', '+', $08, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', '{', '}', $0D, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', ':'
dc. b '@', $ff, $00, '~', 'Z', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', '<', '>', '?', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

```

```

dc. b $00, $00, $00, $00, $00, $00, $00, $37
dc. b $38, $00, '-', $34, $00, $36, '+', $00
dc. b $32, $00, $30, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '!', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', ' ', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keycl:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', '-', '=', $08, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', '[', ']', $0d, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', ';'
dc. b $27, '^', $00, '#', 'Z', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', ',', '.', ':', '/', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '\', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

. endc

ifeq COUNTRY-GERMANY

keytran:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', $9e, $27, $08, $09
dc. b 'q', 'w', 'e', 'r', 't', 'z', 'u', 'i'
dc. b 'o', 'p', $81, '+', $0D, $00, 'a', 's'
dc. b 'd', 'f', 'g', 'h', 'j', 'k', 'l', $94
dc. b $84, '#', $00, '~', 'y', 'x', 'c', 'v'
dc. b 'b', 'n', 'm', ',', '.', ':', '-', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '<', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keyshif:

```

dc. b $00, $1b, '!', '"', $dd, '$', '%', '&'
dc. b '/', '(', ')', '=', '?', '^', $08, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Z', 'U', 'I'
dc. b 'O', 'P', $9a, '*', $0D, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', $99
dc. b $8e, '^', $00, '!', 'Y', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', ',', '.', ':', '-', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $37
dc. b $38, $00, '-', $34, $00, $36, '+', $00

```

```

dc. b $32, $00, $30, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '>', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', '$0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keycl:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', $9e, $27, $08, $09
dc. b 'Q', 'W', 'E', 'R', 'T', 'Z', 'U', 'I'
dc. b 'O', 'P', $9a, '+', $0D, $00, 'A', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', $99
dc. b $8e, '#', $00, '^', 'Y', 'X', 'C', 'V'
dc. b 'B', 'N', 'M', ',', '.', '-', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

```

```

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '<', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', '$0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

. endc

ifeq COUNTRY-FRANCE

keytran:

```

dc. b $00, $1b, '&', $82, '"', $27, '(', $dd
dc. b $8a, '!', $80, $85, ')', '-', $08, $09
dc. b 'a', 'z', 'e', 'r', 't', 'y', 'u', 'i'
dc. b 'o', 'p', '^', '$', $0D, $00, 'q', 's'
dc. b 'd', 'f', 'g', 'h', 'j', 'k', 'l', 'm'
dc. b $97, '^', $00, '#', 'w', 'x', 'c', 'v'
dc. b 'b', 'n', ',', ';', ':', '=', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

```

```

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '<', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', '$0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00

```

keyshif:

```

dc. b $00, $1b, '1', '2', '3', '4', '5', '6'
dc. b '7', '8', '9', '0', $f8, $ff, $08, $09
dc. b 'A', 'Z', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', $b9, '*', $0D, $00, 'Q', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', 'M'

```

```

dc. b '%', $9c, $00, '!', 'W', 'X', 'C', 'V'
dc. b 'B', 'N', '?', ' ', '/', '+', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $37
dc. b $38, $00, '-', $34, $00, $36, '+', $00
dc. b $32, $00, $30, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '>', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
    
```

keycl:

```

dc. b $00, $1b, '&', $82, '"', $27, '(', $dd
dc. b $8a, '!', $80, $85, ')', '-', $08, $09
dc. b 'A', 'Z', 'E', 'R', 'T', 'Y', 'U', 'I'
dc. b 'O', 'P', '^', '$', $0D, $00, 'Q', 'S'
dc. b 'D', 'F', 'G', 'H', 'J', 'K', 'L', 'M'
dc. b $97, '\', $00, '#', 'W', 'X', 'C', 'V'
dc. b 'B', 'N', ' ', ';', ':', '=', $00, $00
dc. b $00, $20, $00, $00, $00, $00, $00, $00

dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b $00, $00, '-', $00, $00, $00, '+', $00
dc. b $00, $00, $00, $7f, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
dc. b '<', $00, $00, '(', ')', '/', '*', '7'
dc. b '8', '9', '4', '5', '6', '1', '2', '3'
dc. b '0', '.', $0D, $00, $00, $00, $00, $00
dc. b $00, $00, $00, $00, $00, $00, $00, $00
    
```

. endc

. even  
. page  
. text

```

*****
*
* routine to set up the general interrupt port registers
* (gpip, are, ddr)
*
* algorithm to set up the port
*
* 1. mask off all interrupts via the imrx registers;
* 2. clear all enable and pending bits in the ierx and iprx
* registers;
* 3. check the interrupt in-service registers and loop till
* clear;
* 4. init the aer register bits as desired (default = 11111111);
* 5. init the ddr register bits as desired (default = 10000000);
* 6. clear the gpip register;
* 7. enable all desired interrupt enable bits;
* 8. mask on all desired interrupt mask bits;
*
*
    
```

```

*
*****
        .globl  initmfp

initmfp
        lea    mfp,a0           ;init mfp address pointer

        moveq  #$0,d0           ;init to zero for clearing mfp
        movep.l d0,gpip(a0)     ;clear gpip thru iera
        movep.l d0,ierb(a0)     ;clear ierb thru isrb
        movep.l d0,isrb(a0)     ;clear isrb thru vr

*
        move.b #$48,vr(a0)      ;set mfp autovector and s-bit
*
        move.b #$4,aer(a0)      ;set cts to low to high transition

*
        init the "c" timer

        move.w #$1111,tc_rot(a5) ;setup bitstream for /4 on timer c interr
        move.w #20,_timr_ms(a5)  ;set timer calibration value

        moveq  #ctimer,d0       ;set to timer C
        moveq  #$50,d1           ;set to /64 for 200 hz tick
        move.w #192,d2          ;set to 192
        bsr    setimer          ;setup timer and init interrupt vector.....

        lea    timercint,a2      ;point to the timer C interrupt routine...
        moveq  #$5,d0           ;point to the timer C interrupt number
        bsr    initint

*
        init the "d" timer

        moveq  #dtimer,d0       ;select the d timer
        moveq  #c9600,d1         ;init for /4 for 9600 baud
        moveq  #d9600,d2         ;init for 9600 baud
*
        moveq  #c1200,d1         ;init for /4 for 9600 baud
*
        moveq  #d1200,d2         ;init for 9600 baud
        bsr    setimer          ;branch to our timer initialier...

*
        now init the 3 rs232 chip registers

        move.l #$00980101,d0
        movep.l d0,scr(a0)       ;inits scr,ucr,rsr,tsr

*
        initialize the default rs-232 control line settings

        bsr    dtron
        bsr    rtson

*
        initialize the rs-232 buffer record structure

        lea    rbufrec(a5),a0
        lea    rs232init,a1
        moveq  #rssize,d0
        bsr    lbmove           ;do block move and return

```

```

*      initialize the midi buffer record structure

      lea      mbufrec(a5),a0
      lea      minit,a1
      moveq    #mssize,d0
      bsr      lbmove          ;do block move and return

      move.l   #aciaexit,d0      ;init to ikbd and midi error handler address
      move.l   d0,vkbderr(a5)    ;init keyboard error handler address
      move.l   d0,vmiderr(a5)    ;init midi error handler address
      move.l   #sysmidi,midivec(a5) ;point to system midi interrupt vector

*      init the midi acia next

      move.b   #rsetacia,comstat+midi ;init the acia via master reset

*      init the acia to divide by 16x clock, 8 bit data, 1 stop bit, no parity,
*      rts low, transmitting interrupt disabled, receiving interrupt enabled

      move.b   #div16+protocol+rtsld+intron,comstat+midi

*      initialize the keyboard acia interrupt vector exception address

      move.b   #%00000111,conterm(a5) ;enable keyclick,repeat key,bell functions

      move.l   #jdostime,clkintvec(a5)
      move.l   #genrts,d0          ;generalized rts for ikbd subsystems
      move.l   d0,statintvec(a5)
      move.l   d0,msintvec(a5)    ;init user mouse interrupt adr to rts
      move.l   d0,joyintvec(a5)

*
*      Sound routine initialization - uses the pre-init'ed d0.l=0000 !!
*
*initsnd:
      moveq    #$0,d0              ;init 'd0' to clear sound variables
      move.l   d0,cursnd(a5)       ;clear sound ptr
      move.b   d0,timer(a5)        ;clear delay timer
      move.b   d0,auxd(a5)         ;clear temp value
      move.l   d0,prt_to(a5)       ;init printer timeout to 0

      bsr      strobeoff           ;init strobe to off (line high!)
      move.b   #tdelay1,cdelay1(a5) ;init system default key repeat values
      move.b   #tdelay2,cdelay2(a5)

*      within the mouse relative routine

*      initialize the ikbd buffer record structure

      lea      kbufrec(a5),a0
      lea      kinit,a1
      moveq    #kssize,d0
      bsr.b    lbmove              ;do block move and return

      bsr      bioskeys            ;point key translation address to
*                                     ;the rom based translation tables

```

```

*      init the acia next

      move.b  #rsetacia,comstat+keyboard      ;init the acia via master re

* now that the vector is initialized, we can allow interrupts to occur!
* init the acia to divide by 64 clock, 8 bit data, 1 stop bit, no parity,
* rts low, transmitting interrupt disabled, receiving interrupt enabled

      move.b  #div64+protocol+rtsld+intron,comstat+keyboard

      move.l  #mfpvectr,a3      ;point to initializing array of exception vec's
      moveq   ##3,d1            ;init branch counter/index
sti    move.l  d1,d2
      move.l  d1,d0            ;load in interrupt # to setup
      addi.b  ##9,d0           ;add constant to point to proper mfp interrupt
      asl.l   #2,d2
      move.l  0(a3,d2),a2
      bsr    initint          ;go to service routine
      dbra   d1,sti
      lea    midikey(a5),a2
      moveq  ##6,d0           ;load in interrupt # to setup
      bsr    initint          ;go to service routine

      lea    ctsint(a5),a2    ;point to the CTS interrupt routine...
      moveq  ##2,d0           ;point to the CTS interrupt number
      bsr    initint

*
*      ;initializing code which sets the enable
*      ;and mask bits...

      movea.l #setikbd,a2
      moveq   #sizeikbd,d3
      bsr    ikbdstr          ;init ikbd from 'setikbd' data

genrts  rts

lbmove  move.b  (a1)+,(a0)+
      dbra   d0,lbmove
      rts                    ;and return home

setikbd dc.b  $80,$01,$12,$1a ;reset keyboard,disable mouse,disable joysticks
sizeikbd equ   *-setikbd-1

kinit
      dc.l   kibuffer
      dc.w   kinsize
      dc.w   0
      dc.w   0
      dc.w   kinsize/4
      dc.w   kinsize*3/4

kssize  equ   *-kinit-1

minit
      dc.l   mibuffer
      dc.w   minsize

```

```
dc.w 0
dc.w 0
dc.w minsize/4
dc.w minsize*3/4
```

```
mssize equ *-minit-1
```

```
.even
```

rs232init

```
dc.l ribuffer ;ibufptr
dc.w rinsize ;ibufsiz
dc.w 0 ;ibufhead
dc.w 0 ;ibuftail
dc.w rinsize/4 ;ibuflow
dc.w rinsize*3/4 ;ibufhigh
```

```
dc.l robuffer ;obufptr
dc.w routsize ;obufsiz
dc.w 0 ;obufhead
dc.w 0 ;obuftail
dc.w routsize/4 ;obuflow
dc.w routsize*3/4 ;obufhigh
```

```
dc.b 0 ;rsrbyte
dc.b 0 ;tsrbyte
dc.b 0 ;rxoff
dc.b 0 ;txoff
```

```
* dc.b 1 ;rsmode -- xon/xoff mode
* dc.b 2 ;rsmode -- CTS/RTS/DTR mode
dc.b 0 ;rsmode filler
```

```
rssize equ *-rs232init-1
```

```
.even
```

mfpvectr

```
* array of exception vector addresses for the above interrupts, including
* dummy vectors that point to "rte's".
```

```
dc.l txerror
dc.l txrint
dc.l rxerror
dc.l rcvrint
```

```
.page
.text
```

```
*****
*
* routine to setup a timer
*
* algorithm to init a timer
*
* 1. determine which timer and set d0.b = to timer's index value *
```

```

*      as shown below:
*
*      2. disable the associated interrupt;
*      3. disable the timer itself via it's timer control register;
*      4. initialize the timer's data register
*      5. repeat step #4 until the data register's contents are
*         verified, per the errata sheet to the 68901 description;
*      6. turn on the timer by using the value that you previously
*         stored in d1;
*
*
*      note:   the interrupt vector for the associated timer
*              is not set in this routine, so it is the user's
*              responsibility to set it if so desired!
*
*
*      registers used:      d0-d3/a0-a3
*      registers saved:    d0-d3/a0-a3
*      entry:
*
*          d0.l - timer to be set
*                  0 - timer a
*                  1 - timer b
*                  2 - timer c
*                  3 - timer d
*
*          d1.b - timer's new control setting
*          d2.b - timer's data register data
*
*      exit:   no values to pass
*
*
*          d3   - used and abused by call to mskreg routine
*          a0.l - set to mfp register base
*          a1.l - temporary location for a3
*          a2.l - used to pass table address to mskreg routine
*          a3.l - used to pass table address to mskreg routine
*
*
* *****

```

```

.globl setimer

```

```

setimer:

```

```

movem.l d0-d4/a0-a3, -(sp)      ;save all registers to be messed with!!
move.l  #mfp, a0                ;set mfp chip address pointer

move.l  #imrt, a3               ;mask off the timer's interrupt maskable bit
move.l  #imrmt, a2
bsr.b   mskreg

move.l  #iert, a3              ;mask off the timer's interrupt enable bit
move.l  #iermt, a2
bsr.b   mskreg

move.l  #iprt, a3              ;mask off the timer's interrupt pending bit
move.l  #iprmt, a2
bsr.b   mskreg

move.l  #isrt, a3              ;mask off the timer's interrupt inservice bit
move.l  #isrmt, a2
bsr.b   mskreg

```

```

move.l #tcrtab,a3 ;mask off the timer's control bits
move.l #tcrmsk,a2
bsr.b mskreg

exg a3,a1 ;save address pointer for restoring control

lea tdrtab,a3 ;initialize the timer data register
moveq #0,d3 ;to prevent false effective address generation
move.b 0(a3,d0),d3
verify move.b d2,0(a0,d3)
cmp.b 0(a0,d3),d2
bne.b verify

exg a3,a1 ;grab that register address back
or.b d1,(a3) ;mask the timer control register value

movem.l (sp)+,d0-d4/a0-a3 ;restore all registers that were saved
rts

```

```

*****
*
* generalize mask register bit(s) routine *
*
* entry *
* static d0 - contains the timer # *
* static d3 - used and abused *
* static d4 - used and abused *
* static a0 - mfp register base *
* static a3 - points to table of similar timer registers *
* static a2 - points to table of similar timer data values *
*****

```

mskreg

```

bsr.b getmask
move.b (a2),d3 ;grab mask now
and.b d3,(a3) ;and have masked off the desired bit(s)
rts

getmask moveq #0,d3 ;to prevent false effective address generation
adda d0,a3 ;have got pointer to mfp register now
move.b (a3),d3 ;now have the address offset to mfp
add.l a0,d3
movea.l d3,a3 ;now have address pointing to desired mfp reg.
* ;now we get the mask to turn off interrupt
adda d0,a2 ;have got pointer to mask now
rts

iert dc.b $6,$6,$8,$8
iprt dc.b $A,$A,$C,$C
isrt dc.b $E,$E,$10,$10
imrt dc.b $12,$12,$14,$14

iermt dc.b $df,$fe,$df,$ef
imrmt equ iermt
iprmt equ iermt
isrmt equ iermt

```

```
tcrtab dc.b $18,$1a,$1c,$1c
tcrmsk dc.b $0,$0,$8f,$f8
tdrtab dc.b $1e,$20,$22,$24
```

.even

```
*****
*
* initialize mfp interrupt via GEMDOS
*
* entry
*
* void mfpint(numint, intvec)
* word numint
* long intvec
*
*
*****
```

.globl mfpint

mfpint

```
move.w 4(sp),d0
move.l 6(sp),a0
andi.l #$f,d0 ;to ensure masking of 0-$f
```

```
*****
*
* routine to init an mfp associated interrupt vector
*
* algorithm
*
* 1. block the interrupt via it's mask bit;
* 2. disable the interrupt's enable and pending bits;
* 3. check the interrupt's in-service register and loop till
* clear;
* 4. init the interrupt's associated vector;
* 5. set the interrupt's enable bit;
* 6. set the interrupt's mask bit;
*
* entry
*
* d0 - contains interrupt # to affect
* a2 - contains new vector address
*
*****
```

initint

```
movem.l d0-d2/a0-a2,-(sp) ;save affected registers
bsr.b disint ;disable the interrupts
move.l d0,d2 ;get a copy so as to determine where to...
asl #2,d2 ;place the a2 address into the int. vector
addi.l #$100,d2 ;interrupt vector addr = (4 * int) + $000100
move.l d2,a1 ;transfer the calculated address to a register
move.l a2,(a1) ;...that can act upon it thus!<--vector init'ed
bsr.b enabint ;enable interrupts
movem.l (sp)+,d0-d2/a0-a2 ;restore affected registers
```

rts

```
*****
*
*          disable an mfp interrupt via GEMDOS
*
*      entry
*
*      void      jdisint(numint)
*      word      numint
*
*****
```

.globl jdisint

```
jdisint move.w 4(sp),d0
        andi.l #$f,d0          ;to ensure masking of 0-$f
```

```
*****
*          interrupt disable routine
*
*****
```

disint

```
movem.l d0-d1/a0-a1,-(sp)      ;save affected registers
lea     mfp,a0                 ;set mfp chip address pointer
lea     imra(a0),a1            ;set a1 for the mskoff routine
bsr.b   bselect                ;generate the appropriate bit to clear
bclr    d1,(a1)                ;and clear the bit...
lea     iera(a0),a1           ;set a1 for another mskoff call
bsr.b   bselect                ;generate the appropriate bit to clear
bclr    d1,(a1)                ;and clear the bit...
lea     ipra(a0),a1           ;set a1 for another mskoff call
bsr.b   bselect                ;generate the appropriate bit to clear
bclr    d1,(a1)                ;and clear the bit...
lea     isra(a0),a1           ;now set up to check for interrupts in progress
bsr.b   bselect                ;get proper a/b version...
bclr    d1,(a1)                ;and clear the bit...
movem.l (sp)+,d0-d1/a0-a1     ;restore affected registers
rts
```

```
*****
*
*          enable/re-enable an mfp interrupt via GEMDOS
*
*      entry
*
*      void      jenabint(numint)
*      word      numint
*
*****
```

.globl jenabint

```
jenabint
        move.w 4(sp),d0
        andi.l #$f,d0          ;to ensure masking of 0-$f
```

```
*****
*          enable interrupt routine          *
*****
enabint
```

```
    movem.l d0-d1/a0-a1,-(sp)      ;save affected registers
    lea    mfp,a0                  ;set mfp chip address pointer
    lea    iera(a0),a1             ;set up to enable the interrupt enable bit
    bsr.b  bselect
    bset   d1,(a1)                 ;and set the bit...
    lea    imra(a0),a1             ;set up to enable the interrupt enable bit
    bsr.b  bselect
    bset   d1,(a1)                 ;and set the bit...
    movem.l (sp)+,d0-d1/a0-a1      ;restore affected registers
    rts
```

```
*****
*
*          the following routine generates the appropriate bset/bclr #
*          for the interrupt # specified in d0.      valid interrupt #'s are
*          0 --> 15 as shown in the 68901 chip specification.  It also
*          selects between the ixra and the ixrb version of the register
*          as is appropriate.
*
*          entry    d0 - contains the interrupt number
*                   a1 - contains the pointer to the "ixra" version of
*                   the interrupt byte to mask
*          exit      d0 - same as upon entry
*                   d1 - contains the number of the bit
*****
```

```
bselect
```

```
    move.b  d0,d1                  ;copy d0 to d1 for scratch work
    cmpi.b  #$8,d0                 ;see if desired int # >= 8...
    blt.b   skip0                  ;...and branch if it ain't...
    subq    #$8,d1                 ;adjust for using ixrb instead
skip0    cmpi.b  #$8,d0                 ;see if desired int # >= 8...
    bge.b   skip1                  ;...and branch if it is...
    addq    #$2,a1                 ;adjust for using ixrb instead
skip1    rts
```

```
.page
.text
```

```
rs232ptr
```

```
    lea    rbufrec,a0              ;point to current output buffer record
    lea    mfp,a1
    rts
```

```
rs232ibuf
```

```
    move.w  ibuftail(a0),d2
    move.w  ibufhead(a0),d3
    cmp.w   d3,d2                  ;is head-pointer > tail-pointer
    bhi.b   rb1                    ;no...
    add.w   ibufsiz(a0),d2         ;yes...buffer used=bufsiz+tail-head
rb1       sub.w  d3,d2              ;obtain tail-head value
```

rts

```

rtschk  btst.b  #1, rsmode(a0) ; check if we're using control lines
        beq.b  rtsexit      ; no... no need to assert rts on
        bsr   rtson        ; yes... turn on rts signal
rtsexit rts
    
```

```

*****
*           putchar routine for rs-232 port           *
*
*   this routine transfers characters to a output queue that is
*   emptied by an automatic interrupt routine.  the interrupt
*   routine handles the actual transfer of the character to the i/o
*   port.
*
*   entry
*       d1 - contains character to transfer
*   exit
*       d0 - contains "0" for successful transfer, "xoff"
*           for full buffer and no transfer
*       carry bit clear - good transfer
*       carry bit set - error condition
*
*****
    
```

rs232put

```

        move   sr, -(sp)      ; save sr
        ori   #700, sr
        bsr.b rs232ptr      ; point to current output buffer record

        btst.b #0, rsmode(a0) ; are we using xon/xoff flow control?
        beq.b rp0           ; no...

        tst.b  txoff(a0)     ; if non-zero then xon is in effect!
        bne.b rp1           ; whether we're full or not, it's all the same!!

rp0     btst.b #7, tsr(a1)   ; buffer is full so keep char in circular buffr
        beq.b rp1

        move.w obufhead(a0), d2
        cmp.w  obuftail(a0), d2 ; head=tail?
        bne.b rp1           ; yes...

        move.b d1, udr(a1)   ; write a byte to transmit
        bra.b rp3

rp1     move.w obuftail(a0), d2 ; get current tail pointer offset from buffer
        bsr   wrapout       ; check for wrap of pointer
        cmp.w obufhead(a0), d2 ; head=tail?
        beq.b rp2           ; yes... no buffer space left
        move.l obufptr(a0), a1 ; get current available buffer storage location
        move.b d1, 0(a1, d2)  ; store char to the buffer
        move.w d2, obuftail(a0) ; store new tail pointer to buffer record

rp3     bsr   rtschk        ; do we turn on RTS signal line?
        move (sp)+, sr
    
```

```

andi.b  $$fe, ccr      ; indicate carry clear/good transfer
rts                                           ; done for now

rp2     bsr           rtschk      ; do we turn on RTS signal line?
        move        (sp)+, sr
        ori.b       $$1, ccr
        rts                                           ; done for now

```

```

*****
*           getchar routine for rs-232 port           *
*
*   this routine transfers characters from a input queue that is
*   filled by an automatic interrupt routine.  the interrupt
*   routine handles the actual transfer of the character from the
*   i/o port.
*
*   entry
*       a0 - contains pointer to device buffer record
*   exit
*       d0 - contains character if carry bit clear
*           if carry bit set then error condition
*
*****

```

rs232get

```

move     sr, -(a7)      ; protect this upcoming test
ori      $$700, sr

bsr     rs232ptr      ; point to current output buffer record

move.w  ibufhead(a0), d1 ; get current head pointer offset from buffer
cmp.w   ibuftail(a0), d1 ; head=tail?
beq.b   rg5           ; yes
bsr     wrapin        ; check for wrap of pointer
move.l  ibufptr(a0), a1 ; get base address of buffer
moveq   $$0, d0       ; clear out 'd0'!
move.b  0(a1, d1), d0  ; get character
move.w  d1, ibufhead(a0) ; store new head pointer to buffer record

move    (a7)+, sr
andi.b  %%11111110, ccr ; clear carry flag for normal return
bra.b   rg4

```

rg5

```

move    (a7)+, sr
ori.b   $$01, ccr      ; set carry for error condition just in case...

```

```

*   check rxoff flag and if set, see if low water mark is reached
*   if low watermark is reached, turn off rxoff flag and send a ctrl-q

```

rg4

```

btst.b  $$0, rsmode(a0) ; are we using xon/xoff flow control?
beq.b   rg1             ; no...

tst.b   rxoff(a0)      ; check for a current receiver xon situation
beq.b   rg1             ; xon so continue...

```

\* now check for lowwater mark triggering of flow-control

```

bsr      rs232ibuf      ;get amount of input buffer used
cmp.w    ibuflow(a0),d2 ;is amount consumed = lowmark?
bne.b    rg1            ;no...

move.b   #ctrlq,d1      ;setup rs232put/txrint to send a ctrl-q
bsr      rs232put
clr.b    rxoff(a0)      ;turn off rxoff flag byte
    
```

rg1 rts

```

*****
*
*           receiver buffer full interrupt routine
*
*           grabs data from the rs-232 receiver port
*
*****
    
```

rcvrint

```

movem.l  d0-d3/a0-a2,-(sp) ;save affected registers
bsr      rs232ptr          ;point to current output buffer record

move.b   rsr(a1),rsrbyte(a0) ;do the required rsr read before
*                               ;the udr read!
btst.b   #7,rsrbyte(a0) ;do rcvr buffer full flag test
beq      ri8               ;branch should never be taken! means that the
*                               ;wrong interrupt was called...should have been
*                               ;the rcvr error interrupt procedure!
btst.b   #$1,rsmode(a0) ;check for currently using rts/cts/dtr
beq.b    ri1               ;no...not currently in use
bsr      rtsoff            ;yes...so clear rts to indicate we're busy
ri1      move.b   udr(a1),d0 ;get incoming data byte
    
```

\* now we do xon/xoff protocol check in case the byte we just got is  
 \* a ^s/^q. we also check to see which mode we're in so that if we're in  
 \* binary or bypass mode (where the calling program handles the  
 \* handshaking!) we let the character into the buffer. if we get either  
 \* character and are in xon/xoff protocol mode, we do not pass the  
 \* character along. instead, we do the following

\* if we get a ^s xoff, then we set the txoff flag byte to 1 to signal  
 \* to the txrint routine to stop transmitting. the putchar routine to  
 \* the transmit buffer also checks the txoff byte and returns the carry  
 \* set if the byte may not be sent into the buffer. see that routine for  
 \* a better explanation of how it handles txoff=1.

\* if we get a ^q xon, then we reset the txoff flag byte to 1 to signal  
 \* to the txrint and the putchar routines to resume normal operation.

```

btst.b   #$1,rsmode(a0) ;check for currently using rts/cts/dtr
bne.b    ri3             ;yes, so bypass xon/xoff flow control code...

btst.b   #$0,rsmode(a0) ;is the rs232 mode xon/xoff?
beq.b    ri3             ;no...so process normally
    
```

```

    cmpi.b  #xon,d0      ;is the data an "xon" signal?
    bne.b   ri2          ;no...now check for xoff
    move.b  #$00,txoff(a0) ;set to normal transmission status
    bra.b   ri8          ;abnormal exit condition!!

ri2    cmpi.b  #xoff,d0    ;check for xoff (^s) condition from host
    bne.b   ri3          ;neither xon/xoff value, must be normal data...
    move.b  #$ff,txoff(a0) ;set to halted transmission to host
    bra.b   ri8          ;abnormal exit condition!!

ri3    move.w  ibuftail(a0),d1 ;get current tail pointer offset
    bsr     wrapin       ;do wrap of input pointer if needed
    cmp.w   ibufhead(a0),d1 ;head=tail?
    beq.b   ri8          ;yes...exit...

    move.l  ibufptr(a0),a2 ;get buffer pointer
    move.b  d0,0(a2,d1)    ;store the data
    move.w  d1,ibuftail(a0) ;store the new buftail pointer

```

\* now check for highwater mark triggering of flow-control

```

    bsr     rs232ibuf     ;obtain amount of input buffer used
    cmp.w   ibufhigh(a0),d2 ;is amount consumed = highmark?
    bne.b   ri6          ;no...

```

\* yes... send xoff to outside world

\* set rxoff flag for the getchar and rcvrint routines

```

    btst.b  #$1,rsmode(a0) ;check for currently using rts/cts/dtr
    bne.b   ri8          ;yes...exit without re-enabling DTR signal

```

```

    btst.b  #$0,rsmode(a0) ;are we using xon/xoff flow control?
    beq.b   ri6          ;no...

```

```

    tst.b   rxoff(a0)      ;has a ctrl-s been sent yet?
    bne.b   ri6          ;yes...so don't send another
    move.b  #$ff,rxoff(a0) ;means a ctrl-s has been sent to halt input
    move.b  #ctrls,d1      ;halt input from host
    bsr     rs232put

```

```

ri6    btst.b  #$1,rsmode(a0) ;check for currently using rts/cts/dtr
    beq.b   ri8          ;no...not currently in use
    bsr     rtson        ;we're ready now for more data...yum! yum!

```

```

ri8    bclr.b  #$4,isra(a1)
    movem.l (sp)+,d0-d3/a0-a2 ;restore affected registers
    rte

```

```

*****
*
*   transmit buffer empty interrupt routine
*
*****

```

txrint

```

movem.l d2/a0-a2, -(sp) ; save affected registers
bsr     rs232ptr         ; point to current output buffer record

btst.b  #$1, rsmode(a0) ; are we using CTS/RTS flow control?
bne.b   ti6             ; yes... get out of this routine and use CTSINT

btst.b  #$0, rsmode(a0) ; are we using xon/xoff flow control?
beq.b   ti0             ; no...
tst.b   txoff(a0)       ; if non-zero then xon is in effect!
bne.b   ti6             ; whether we're full or not, it's all the same!!
    
```

ti0

```

move.b  tsr(a1), tsrbyte(a0)
move.w  obufhead(a0), d2
cmp.w   obuftail(a0), d2 ; head=tail?
beq.b   ti6             ; yes... abnormal exit...
bsr     wrapout         ; do wrap of input pointer if needed
move.l  obufptr(a0), a2 ; get current buffer pointer
move.b  0(a2, d2), udr(a1) ; write a byte to transmit
move.w  d2, obufhead(a0) ; store new head pointer
    
```

ti6

```

bclr.b  #$2, isra(a1) ; turn off interrupt
movem.l (sp)+, d2/a0-a2 ; restore affected registers
rte
    
```

```

*****
*
*           Clear-To-Send interrupt routine
*
*
*****
    
```

ctsint

```

movem.l d2/a0-a2, -(sp) ; save affected registers
bsr     rs232ptr         ; point to current output buffer record

btst.b  #$1, rsmode(a0) ; are we using CTS/RTS flow control?
beq.b   ctsexit         ; no...
    
```

cts0

```

move.b  tsr(a1), tsrbyte(a0)
btst.b  #$7, tsrbyte(a0) ; is the transmit buffer empty yet?
beq.b   cts0            ; no... continue looping

move.w  obufhead(a0), d2
cmp.w   obuftail(a0), d2 ; head=tail?
beq.b   ctsempy        ; yes... abnormal exit... empty output buffer
bsr     wrapout         ; do wrap of input pointer if needed
move.l  obufptr(a0), a2 ; get current buffer pointer
move.b  0(a2, d2), udr(a1) ; write a byte to transmit
move.w  d2, obufhead(a0) ; store new head pointer
    
```

ctsexit

```

bclr.b  #$2, isrb(a1) ; turn off interrupt
movem.l (sp)+, d2/a0-a2 ; restore affected registers
rte
    
```

ctsempy

bra.b ctsexit ;exit via "ctsexit"

\*\*\*\*\*  
 \* routines to handle tx or rx errors \*  
 \*\*\*\*\*

rxerror

```

movem.l d0/a0-a1, -(sp) ;save all registers
bsr rs232ptr ;point to current output buffer record

move.b rsr(a1), rsrbyte(a0) ;receiver status register
move.b udr(a1), d0 ;dummy read of data register
bclr #$3, isra(a1)
movem.l (sp)+, d0/a0-a1 ;restore all registers
rte
  
```

txerror

```

movem.l a0-a1, -(sp) ;save all registers
bsr rs232ptr ;point to current output buffer record

move.b tsr(a1), tsrbyte(a0) ;transmitter status register
bclr #$1, isra(a1)
movem.l (sp)+, a0-a1 ;restore all registers
rte
  
```

\*\*\*\*\*

```

*
* get device buffer record
*
* entry:
*
* long iorec(device)
* word device
*
* returns pointer to the device's buffer record table
*
* device - buffer identification number
* 0 - rs232
* 1 - ikbd
* 2 - midi
* 3 - parallel
*
* device table structure:
*
* input buffer address long
* input buffer size word
* input buffer head word
* input buffer tail word
* input buffer low-water mark word
* input buffer high-water mark word
*
* output buffer address long
* output buffer size word
* output buffer head word
* output buffer tail word
* output buffer low-water mark word
*
  
```

```
*          output buffer high-water mark    word          *
*                                                                 *
*****
```

```
.globl iorec
```

```
iorec
```

```
moveq    #0, d1
move.w   4(sp), d1
move.w   sr, -(sp)           ;save sr for now
ori.w    #$700, sr          ;no interrupts for now
lea      devtab, a2
asl.l    #2, d1              ;x4=index into devtab space
move.l   0(a2, d1.l), d0    ;get device bufrec pointer
move.w   (sp)+, sr          ;save sr for now
rts
```

```
devtab
```

```
dc.l     rbufrec
dc.l     kbufrec
dc.l     mbufrec
*        dc.l     pbufrec          ;future consideration?
```

```
*****
```

```
*          configure rs-232 port of MFP          *
```

```
entry:
```

```
void     rsconf(baudrate, flow, ucr, rsr, tsr, scr)
*
* word    baudrate - baud rate setting (value for timer D control
*                and data registers)
*                xxxxxxxx/xxxxxCCC/xxxxxxxx/DDDDDDDD
* word    flow - flow control:   xxxxxxhs
*                h - cts/rts/dtr
*                s - software xon/xoff
*                1 - on, 0 - off
* word    ucr - MFP ucr register setting
* word    rsr - MFP rsr register setting
* word    tsr - MFP tsr register setting
* word    scr - MFP scr register setting
*
```

```
*****
```

```
.globl rsconf
```

```
rsconf
```

```
*        move.w   sr, -(sp)           ;save sr for now
*        ori.w    #$700, sr          ;no interrupts for now
*
*        bsr      rs232ptr
*
*        first, we grab the old ucr, rsr, tsr, scr contents
*
```

```

movepl ucr(a1),d7

*
*
*
next, we disable the receiver and transmitter enable bits
*
moveq    #$0,d0           ;pre-init to zero
move.b   d0,rsr(a1)       ;disable the receiver
move.b   d0,tsr(a1)       ;disable the transmitter

*
*
*
set flow control mode(s)
*
*
tst.w    $6(sp)           ;if -1 then don't change
bmi.b    auxc1
move.b   $7(sp),rsmode(a0)

*
set timer baud rate
*
auxc1    moveq    #0,d0
         moveq    #0,d2
         tst.w    $4(sp)           ;if -1 then don't change
         bmi.b    auxc2
         move.w   $4(sp),d1
         lea     baudctrl,a2       ;point to baudrate control register settings
         move.b   0(a2,d1.w),d0    ;get control mask
         lea     bauddata,a2       ;point to baudrate data register settings
         move.b   0(a2,d1.w),d2    ;get data reg value
         move.l   d0,d1           ;re-assign for "setimer" routine protocol
         moveq    #dtimer,d0      ;point to timer D
         bsr     setimer          ;set timer D to new baud rate

*
set rs-232 registers
*
auxc2    tst.w    $8(sp)           ;if -1 then don't change
         bmi.b    auxc3
         move.b   $9(sp),ucr(a1)
auxc3    tst.w    $a(sp)           ;if -1 then don't change
         bmi.b    auxc4
         move.b   $b(sp),rsr(a1)
auxc4    tst.w    $c(sp)           ;if -1 then don't change
         bmi.b    auxc5
         move.b   $d(sp),tsr(a1)
auxc5    tst.w    $e(sp)           ;if -1 then don't change
         bmi.b    auxc6
         move.b   $f(sp),scr(a1)
auxc6
*
*
*
finally we re-enable the receiver and transmitter enable bits
*
moveq    #$1,d0           ;pre-init to one
move.b   d0,rsr(a1)       ;enable the receiver
move.b   d0,tsr(a1)       ;enable the transmitter

move.l   d7,d0           ;move old contents of rs-232 registers to d0.l

```

```
*      move.w  (sp)+,sr      ;restore sr for now
      rts
```

```
*      baudrate table - control register setting
```

```
baudctrl
```

```
dc.b    c19200,c9600,c4800,c3600
dc.b    c2400,c2000,c1800,c1200
dc.b    c600,c300,c200,c150
dc.b    c134,c110,c75,c50
```

```
*      baudrate table - data register setting
```

```
bauddata
```

```
dc.b    d19200,d9600,d4800,d3600
dc.b    d2400,d2000,d1800,d1200
dc.b    d600,d300,d200,d150
dc.b    d134,d110,d75,d50
```

```
.page
.text
```

```
wrapin
```

```
addq.w  #1,d1      ;i=h+1
cmp.w   ibufsiz(a0),d1 ;? i>= current bufsiz?
bcs.b   w1l        ;no...
moveq   #$0,d1     ;wrap pointer
```

```
w1l
```

```
rts
```

```
wrapout
```

```
addq.w  #1,d2      ;i=t+1
cmp.w   obufsiz(a0),d2 ;? i>= current bufsiz?
bcs.b   w1l        ;no...
moveq   #$0,d2     ;wrap pointer
```

```
w1l
```

```
rts
```

```
.page
.text
```

```
*****
*      this code handles the midi/keyboard interrupt exception      *
*****
```

```
.globl  midikey
```

```
midikey
```

```
movem.l d0-d7/a0-a6,-(sp) ;save all registers
lea     $0,a5              ;address pointer to variable base
keymidi lea     mbufrec(a5),a0 ;point to midi buffer record
lea     midi,a1            ;point to midi register base
movea.l vmiderr(a5),a2    ;load in the jump vector
bsr.b   astatus           ;goto general acia status check routine
lea     kbufrec(a5),a0    ;point to ikbd buffer record
lea     keyboard,a1       ;point to keyboard register base
movea.l vkbderr(a5),a2   ;load in the jump vector
bsr.b   astatus           ;goto general acia status check routine
```

```

btst.b  #$4, gpip+mfp    ;check for pending interrupt occurrence
beq.b   keymidi         ;repeat this interrupt processing
bclr.b  #$6, isrb+mfp   ;clear in-service bit
movem.l (sp)+, d0-d7/a0--a6 ;restore all registers
rte                                           ;go back to what was happening!

```

astatus

```

move.b  comstat(a1), d2 ;grab device status
btst.l  #7, d2          ;make sure it was an interrupt request
beq.b   aciaexit       ;nope...it's empty
btst.l  #0, d2          ;see if receiver buffer is full
beq.b   mk1            ;nope...it's empty
movem.l d2/a0-a2, -(sp)
bsr.b   arcvrint       ;yes...get byte
movem.l (sp)+, d2/a0-a2

```

mk1

```

andi.b  #X00100000, d2 ;mask off bits already tested
beq.b   aciaexit       ;see if any other status bits are on...
move.b  iodata(a1), d0 ;grab data byte from acia data register
jmp     (a2)           ;yes so branch to pre-initiated error subroutine

```

aciaexit

```

rts

```

```

*****
*
*          acia receiver buffer full interrupt routine
*
*****

```

.globl arcvrint

arcvrint

```

move.b  iodata(a1), d0 ;grab data byte from acia data register
cmpa.l  #kbufrec, a0
bne     midibyte       ;don't treat midi acia data as anything other
*                                           ;than as pure data...

```

```

tst.b   kstate(a5)
bne.b   ML3

```

```

cmpi.b  #$f6, d0
bcs     itsakey        ;branch early if it is not a ikbd header!
subi.b  #$f6, d0       ;generate true index into tables now
andi.l  #$ff, d0       ;clear high 3 bytes for indexing
lea     ikbdev, a3     ;point to ikbd device state codes
move.b  0(a3, d0), kstate(a5) ;set ikbd state
lea     ikbdlen, a3    ;point to ikbd device buffer length table
move.b  0(a3, d0), kindex(a5) ;set ikbd device index counter
addi.w  #$f6, d0       ;re-constitute original value

```

MLB

```

cmpi.b  #$f8, d0
blt.b   MLB
cmpi.b  #$fb, d0
bgt.b   MLB
move.b  d0, mousebuf(a5)
rts

```

ikbdev

```

dc.b   statks, amouse, rmouse, rmouse, rmouse, rmouse
dc.b   clock, joyall, joy0, joy1

```

```
ikbdlen dc.b   statdex, amdex, rmdex-1, rmdex-1, rmdex-1, rmdex-1
         dc.b   clkdex, joyadex, joydex, joydex
```

ML3

```

cmpi.b  #joy0, kstate(a5)
bcc     ML35 ; a joystick 0/1 record byte, not both!
lea     ikbdparams, a2 ; point to ikbd subsystem parameters table
moveq   #0, d2
move.b  kstate(a5), d2 ; load to generate longword offset
subq.b  #1, d2 ; kstate(a5)=1 to 5/ table index is 0 to 4
asl     d2 ; x2
add.b   kstate(a5), d2 ; +1
subq.b  #1, d2 ; kstate(a5)=1 to 5/ table index is 0 to 4
asl     #2, d2 ; x4

movea.l 0(a2, d2), a0 ; load in subsystem's record pointer
movea.l 4(a2, d2), a1 ; load in subsystem's index base+record pointer
movea.l 8(a2, d2), a2 ; load in subsystem's pointer variable that
* ; contains the pointer to the subsystem's
* ; interrupt routine...

movea.l (a2), a2
moveq   #0, d2 ; clear out 'd2' for address manipulation
move.b  kindex(a5), d2
suba.l  d2, a1
move.b  d0, (a1)
sub.b   #1, kindex(a5)
tst.b   kindex(a5)
bne.b   ML1

ikserve move.l  a0, -(sp) ; stuff buffer pointer to stack
         jsr     (a2) ; go service the subsystem interrupt routine
         addq   #4, sp ; re-adjust stack
         clr.b  kstate(a5) ; reset ikbd state
ML1      rts

```

ikbdparams

```

dc.l    statrec
dc.l    statdex+statrec
dc.l    statintvec

dc.l    amrec
dc.l    amdex+amrec
dc.l    msintvec

dc.l    mousebuf
dc.l    rmdex+mousebuf
dc.l    msintvec

dc.l    clkrec
dc.l    clkdex+clkrec
dc.l    clkintvec

dc.l    joyrec
dc.l    joyadex+joyrec
dc.l    joyintvec

```

ML35

```

move.l #joyrec+1,d1
add.b kstate(a5),d1 ;kstate(a5) reflects joy0 or joy1 state
subi.b #joy0,d1
move.l d1,a2 ;create index to joyrec table for record byte
move.b d0,(a2)
movea.l joyintvec(a5),a2 ;get user's joystick interrupt routine adr
lea joyrec(a5),a0 ;send along address of joystick data
bra.b ikserve

```

itsakey

```

* check the special keys
move.b kbshift(a5),d1 ;load in kbshift(a5) for manipulation...
cmpi.b #$2A,d0 ;left shift?
bne.b ari2
bset #KBLSH,d1
bra.b ari10
ari2 cmpi.b #$AA,d0
bne.b ari3
bclr #KBLSH,d1
bra.b ari10
ari3 cmpi.b #$36,d0 ;right shift
bne.b ari4
bset #KBRSH,d1
bra.b ari10
ari4 cmpi.b #$B6,d0
bne.b ari5
bclr #KBRSH,d1
bra.b ari10
ari5 cmpi.b #$1D,d0 ;CTRL
bne.b ari6
bset #KBCTL,d1
bra.b ari10
ari6 cmpi.b #$9D,d0
bne.b ari7
bclr #KBCTL,d1
bra.b ari10
ari7 cmpi.b #$3B,d0 ;ALT
bne.b ari8
bset #KBALT,d1
bra.b ari10
ari8 cmpi.b #$B8,d0
bne.b ari9
bclr #KBALT,d1
bra.b ari10
ari9 cmpi.b #$3A,d0 ;CAPS LOCK
bne.b ari11
btst.b #0,conterm(a5)
beq.b ari9a ;no click please!
move.l #keyclk,cursnd(a5)
move.b #0,timer(a5)
ari9a bchg #KBCL,d1 ;toggle CAPS LOCK state
ari10 move.b d1,kbshift(a5) ;restore new kbshift(a5) value
rts ;ignore CAPS LOCK break
ari11 btst.l #7,d0 ;is it a break code?
bne.b ari12 ;no... a break code!
tst.b keyrep(a5) ;yes

```

```

    bne. b    ari15
    move. b   d0, keyrep(a5)    ; save for repeat purpose
    move. b   cdelay1, kdelay1(a5)
    move. b   cdelay2, kdelay2(a5)
    bra. b    ari16
ari15  move. b   #0, kdelay1(a5)
    move. b   #0, kdelay2(a5)
    bra. b    ari16
ari12  tst. b    keyrep(a5)
    beq. b    ari18
    moveq    #0, d1
    move. b   d1, keyrep(a5)
    move. b   d1, kdelay1(a5)
    move. b   d1, kdelay2(a5)

ari18  cmpi. b   #$c7, d0        ; is it a "home" break-code?
    beq. b    ari18a           ; yes... allow it to pass
    cmpi. b   #$d2, d0        ; is it a "insert" break-code?
    bne      ari14           ; no... regular break junk...
ari18a btst. b   #KBALT, kbshift(a5) ; early "ALT" test to prevent double "nulls"
    beq      ari14           ; no ALT... so exit now...

ari16  btst. b   #0, conterm(a5)
    beq. b    ari16a           ; no click please!
    move. l   #keyclk, cursnd(a5)
    move. b   #0, timer(a5)

ari16a move. l   a0, -(sp)      ; store kbufrec pointer

    moveq    #$0, d1
    move. b   d0, d1

    movea. l  skeytran(a5), a0
    andi. w   #$7F, d0
    btst. b   #KBCL, kbshift(a5)
    beq. b    conin21
    movea. l  skeycl(a5), a0
conin21 btst. b   #KBRSH, kbshift(a5)
    bne. b    conin22
    btst. b   #KBLSH, kbshift(a5)
    beq. b    conin23
conin22 cmpi. b   #$3b, d0        ; see if a possible function key
    bcs. b    conin22a        ; unsigned less than lowest function scancode
    cmpi. b   #$44, d0        ; see if a possible function key
    bhi. b    conin22a        ; unsigned greater than highest function scan
    addi. w   #$19, d1        ; add to change to GSX standard
    moveq    #$0, d0        ; change to GSX standard
    bra      conin25
conin22a
conin23 movea. l  skeyshif(a5), a0
    move. b   (a0, d0. w), d0
    btst. b   #KBCTL, kbshift(a5)    ; is the control key down?
    beq. b    conin24a
    cmpi. b   #cr, d0           ; is it a carriage return?
    bne. b    conin23a
    moveq    #lf, d0           ; change to a linefeed according to GSX spec...

```

```

    beq. b    conin24
conin23a  cmpi. b    #$47, d1      ;convert CONTROL-home to gsx standard
    bne. b    conin23b      ;by adding #$30...
    addi. w    #$30, d1
    bra       conin25
conin23b  cmpi. b    #$4b, d1      ;convert CONTROL-left arrow to gsx standard
    bne. b    conin23c
    moveq     #$73, d1      ;change according to gsx spec
    moveq     #$0, d0
    bra       conin25
conin23c  cmpi. b    #$4d, d1      ;convert CONTROL-right arrow to gsx standard
    bne. b    conin24
    moveq     #$74, d1      ;change according to gsx spec
    moveq     #$0, d0
    bra       conin25
conin24   andi. w    #$01F, d0   ;yep, so CTRLize the key
    bra       conin25
conin24a  btst. b    #KBALT, kbshift(a5) ;is the alt key down?
    beq       conin25

    ifeq     COUNTRY-GERMANY

    cmpi. b    #$1a, d1      ;is it a ALT-umlaut?
    bne. b    altger1       ;no...
    move. b    #$40, d0      ;put in '@', then check the shift keys
    move. b    kbshift(a5), d2 ;grab current setting
    andi. b    #$3, d2      ;KBRSH+KBLSH bits
    beq       conin25       ;process it as unshifted
    move. b    #$5c, d0      ;put in '\', instead...it's a alt-shift umlaut!
    bra       conin25       ;process it
altger1   cmpi. b    #$27, d1 ;is it a ALT-
    bne. b    altger2       ;no...
    move. b    #$5b, d0      ;put in '[', then check the shift keys
    move. b    kbshift(a5), d2 ;grab current setting
    andi. b    #$3, d2      ;KBRSH+KBLSH bits
    beq       conin25       ;process it as unshifted
    move. b    #$7b, d0      ;put in '{', instead...it's a alt-shift umlaut!
    bra       conin25       ;process it
altger2   cmpi. b    #$28, d1 ;is it a ALT-
    bne. b    outside       ;no...
    move. b    #$5d, d0      ;put in ']', then check the shift keys
    move. b    kbshift(a5), d2 ;grab current setting
    andi. b    #$3, d2      ;KBRSH+KBLSH bits
    beq       conin25       ;process it as unshifted
    move. b    #$7d, d0      ;put in '}', instead...it's a alt-shift umlaut!
    bra       conin25       ;process it

    endc

    ifeq     COUNTRY-FRANCE

```

```

    cmpi.b  #1a,d1      ;is it a ALT-^?
    bne.b   altfrr1    ;no...
    move.b  #5b,d0      ;put in '[' , then check the shift keys
    move.b  kbshift(a5),d2 ;grab current setting
    andi.b  #3,d2       ;KBRSH+KBLSH bits
    beq     conin25     ;process it as unshifted
    move.b  #7b,d0      ;put in '{', instead...it's a alt-shift ^
    bra     conin25     ;process it
altfrr1   cmpi.b  #1b,d1      ;is it a ALT-$?
    bne.b   altfrr2    ;no...
    move.b  #5d,d0      ;put in ']', then check the shift keys
    move.b  kbshift(a5),d2 ;grab current setting
    andi.b  #3,d2       ;KBRSH+KBLSH bits
    beq     conin25     ;process it as unshifted
    move.b  #7d,d0      ;put in '}', instead...it's a alt-shift $
    bra     conin25     ;process it
altfrr2   cmpi.b  #28,d1     ;is it a ALT-
    bne.b   altfrr3    ;no...
    move.b  #5c,d0      ;put in '\', then check the shift keys
    move.b  kbshift(a5),d2 ;grab current setting
    andi.b  #3,d2       ;KBRSH+KBLSH bits
    beq     conin25     ;process it as unshifted
    move.b  #00,d0      ;put in 'NUL',instead...it's a alt-shift
    bra     conin25     ;process it
altfrr3   cmpi.b  #2b,d1     ;is it a ALT-#?
    bne.b   outside    ;no...
    move.b  #40,d0      ;put in '@', then check the shift keys
    move.b  kbshift(a5),d2 ;grab current setting
    andi.b  #3,d2       ;KBRSH+KBLSH bits
    beq     conin25     ;process it as unshifted
    move.b  #7e,d0      ;put in '|', instead...it's a alt-shift #
    bra     conin25     ;process it

    endc

outside   cmpi.b  #62,d1     ;is it an "alt help" signal to dump the screen?
    bne.b   alt15a     ;no...
    addq.w  #1,_dumpflg(a5) ;yes...switch the signal flag on!...
    movea.l (sp)+,a0    ;restore kbufrec pointer
    bra     ar14       ;...and exit

*
*   check the alt-insert/alt-home key make/break combinations, first
*
alt15a    lea     mauskey1,a2 ;get pointer to first alt. mouse scancode table
    moveq   #3,d2        ;create countdown
mkloop1   cmp.b   0(a2,d2),d1 ;is table's scancode value = current value?
    beq     keymaus1     ;yes...go preprocess it...
    dbra   d2,mkloop1    ;no...loop back to check next table value

    cmpi.b  #48,d1      ;is it an up arrow?
    bne.b   alt11
    move.b  #0,d1       ;x value for up arrow
    move.b  #-8,d2      ;y value for up arrow
    move.b  kbshift(a5),d0 ;grab current setting
    andi.b  #3,d0       ;KBRSH+KBLSH bits

```

```

    beq      keymaus
    move.b  #0, d2      ; y value for up arrow
    bra     keymaus
alt11     cmpi.b  #4b, d1      ; is it an left arrow?
    bne.b  alt12
    move.b  #0, d2      ; y value for left arrow
    move.b  #-8, d1     ; x value for left arrow
    move.b  kbshift(a5), d0 ; grab current setting
    andi.b  #3, d0     ; KBRSH+KBLSH bits
    beq     keymaus
    move.b  #-1, d1     ; x value for left arrow
    bra     keymaus
alt12     cmpi.b  #4d, d1      ; is it an right arrow?
    bne.b  alt13
    move.b  #8, d1      ; x value for right arrow
    move.b  #0, d2      ; y value for right arrow
    move.b  kbshift(a5), d0 ; grab current setting
    andi.b  #3, d0     ; KBRSH+KBLSH bits
    beq     keymaus
    move.b  #1, d1     ; x value for right arrow
    bra     keymaus
alt13     cmpi.b  #50, d1     ; is it an down arrow?
    bne.b  alt14
    move.b  #0, d1     ; x value for down arrow
    move.b  #8, d2     ; y value for down arrow
    move.b  kbshift(a5), d0 ; grab current setting
    andi.b  #3, d0     ; KBRSH+KBLSH bits
    beq     keymaus
    move.b  #1, d2     ; y value for down arrow
    bra     keymaus
alt14     cmpi.b  #2, d1
    bcs.b  alt1      ; not >= the '1' key scancode
    cmpi.b  #d, d1
    bhi.b  alt1      ; not <= the '=' key scancode
    addi.b  #76, d1   ; scancode is a key between '1' key and '=' key
    bra.b  alt2
alt1      cmpi.b  #41, d0     ; is the key an ascii 'A' or greater?
    bcs.b  alt3      ; no... skip to check if 'a'-'z'...
    cmpi.b  #5a, d0   ; is the key an ascii 'Z' or less?
    bhi.b  alt3      ; no... skip to check if 'a'-'z'...
alt2      moveq   #0, d0
    bra.b  conin25
alt3      cmpi.b  #61, d0     ; is the key an ascii 'a' or greater?
    bcs.b  conin25   ; no... skip to finish normal processing
    cmpi.b  #7a, d0   ; is the key an ascii 'z' or less?
    bhi.b  conin25   ; no... skip to finish normal processing
    bra.b  alt2
conin25   and.w   #7f, d1
    asl.w  #8, d1    ; shift the scan code to the word's high byte
    add.w  d1, d0    ; form the outgoing word

    movea.l (sp)+, a0 ; restore kbufrec pointer

    move.w  ibuftail(a0), d1 ; get current tail pointer offset
    addq   #2, d1      ; index = tail + 2
    cmp.w  ibufsiz(a0), d1 ; check to see if buffer should wrap

```

```

        bcs. b    ari13          ;no...
        moveq   #$0, d1         ;wrap pointer
ari13   cmp. w    ibufhead(a0), d1 ;head=tail?
        beq. b    ari14          ;yes
        move. l  ibufptr(a0), a2 ;get buffer pointer
        move. w  d0, 0(a2, d1)   ;store the data
        move. w  d1, ibuftail(a0) ;store the new buftail pointer
ari14   rts

midibyte
        movea. l midivec(a5), a2 ;get contents of midivec for indirect branch
        jmp     (a2)           ;jump to midi interrupt handler

sysmidi move. w  ibuftail(a0), d1 ;get current tail pointer offset
        addq   #1, d1          ;index = tail + 1
        cmp. w  ibufsiz(a0), d1 ;check to see if buffer should wrap
        bcs. b  mi13           ;no...
        moveq   #$0, d1         ;wrap pointer
mi13    cmp. w   ibufhead(a0), d1 ;head=tail?
        beq. b  mi14           ;yes
        move. l  ibufptr(a0), a2 ;get buffer pointer
        move. b  d0, 0(a2, d1)   ;store the data
        move. w  d1, ibuftail(a0) ;store the new buftail pointer
mi14    rts

keymausi
        moveq   #KBMRB, d3      ;pre-init to "keyboard" right mouse button
        btst   #4, d1           ;see if it is a left or right button...
        beq. b  kym1           ;it's a right button ($47/$c7)
        moveq   #KBMLB, d3      ;it's a left button ($52/$d2)
kym1    btst   #7, d1           ;see if it is a make or break action
        beq. b  kym2           ;it's a set button action (make code)
        bclr   d3, kbshift(a5) ;it's a clear button action (break code)
        bra. b  kym3           ;go to further pre-init action...
kym2    bset   d3, kbshift(a5) ;it's a set button action (set code)
kym3    moveq   #$0, d1
        moveq   #$0, d2

*
*      finish up at the actual pseudo mouse routine
*

keymaus
        lea    kmbuf(a5), a0     ;point to key-emulating mouse buffer
        movea. l msintvec(a5), a2 ;grab mouse interrupt vector
        clr. l  d0
        move. b  kbshift(a5), d0 ;get current button status
        lsr. b  #KBMRB, d0       ;shift right button bit to 'd0'
        addi. b  #$f8, d0        ;add relative mouse header
        move. b  d0, 0(a0)       ;store in first byte of record buffer
        move. b  d1, 1(a0)       ;store x value in second byte of record buffer
        move. b  d2, 2(a0)       ;store y value in third byte of record buffer
        jsr    (a2)
        movea. l (sp)+, a0       ;restore kbufrec pointer
        rts

mauskey1

```

```
dc.b    $47
dc.b    $c7
dc.b    $52
dc.b    $d2
```

```
.page
.text
```

```
*****
*
* protocol for accessing a gi sound chip register
*
* this bios call must be accessed in supervisor state
* because it affects the 'sr' register
*
* entry
*
* void    giaccess(data,register)
* word    data,register
*
* data -- data register read/write data
*
* register -- chip register to select
* d1 = #$0000 ;selects read operation of the register
* d1 = #$80 .or .xx ;selects write xx to register
* example write to portb - $80 .or. $0f = $8f
*
* exit
* read operations
* d0.b -- data register contains byte of date
* write operations
* d0.b -- data register contains a verification of written data
*
*
*****
```

```
.globl giaccess
```

```
giaccess
```

```
move.w 4(sp),d0
move.w 6(sp),d1
```

```
gientry
```

```
move    sr,-(a7)
ori     #$0700,sr
movem.l d1-d2/a0,-(a7) ;save affected registers
lea     giselect,a0    ;init desired gi register addr
move.b  d1,d2          ;make a copy to test for read or write
andi.b  #$f,d1        ;turn off any extraneous bits
move.b  d1,(a0)       ;select register
asl.b   #1,d2         ;shift once for carry bit detection
bcc.b   giread        ;carry clear, so do a read operation
giwrit  move.b  d0,2(a0) ;init the memory location
giread  moveq   #$0,d0  ;clear out register
        move.b  (a0),d0 ;grab the data from the gi register
        movem.l (a7)+,d1-d2/a0 ;restore affected registers
        move   (a7)+,sr
```

rts ;return with data in d0

```
*****
*          routine to turn off the rts signal          *
*****
        .globl  rtsoff
```

```
rtsoff
        moveq   #%00001000, d2
        bra.b   onbit
```

```
*****
*          routine to turn on the rts signal          *
*****
        .globl  rtson
```

```
rtson
        moveq   #%11110111, d2
        bra.b   offbit
```

```
*****
*          routine to turn off the dtr signal        *
*****
        .globl  dtroff
```

```
dtroff
        moveq   #%00010000, d2
        bra.b   onbit
```

```
*****
*          routine to turn on the dtr signal        *
*****
        .globl  dtron
```

```
dtron
        moveq   #%11101111, d2
        bra.b   offbit
```

```
*****
*
*          routine to set any bit in the gi port a area
*
*          entry
*
*          void    ongibit(bitnum)
*          word    bitnum
*
*          bitnum - byte size bit mask with desired bit set to "1"
*
*****
```

```
        .globl  ongibit
```

```
ongibit
        moveq   #$0, d2
        move.w  4(sp), d2
onbit   movem.l d0-d2, -(a7)
```

```

move    sr, -(a7)
ori     #$0700, sr
moveq   #porta, d1      ;get ready to read in the port a contents
move.l  d2, -(a7)
bsr.b   gientry         ;go get it...
move.l  (a7)+, d2
or.b    d2, d0          ;set bit(s) on
moveq   #porta+$80, d1  ;setup to write to port a
bsr.b   gientry         ;go set it and return
move    (a7)+, sr
movem.l (a7)+, d0-d2
rts

```

```

*****
*
*   routine to clear any bit in the gi port a area
*
*   entry
*
*   void    offgibit(bitnum)
*   word    bitnum
*
*           bitnum - byte size bit mask with desired bit set to "0"
*
*****

```

```
.globl offgibit
```

```

offgibit
moveq   #$0, d2
move.w  4(sp), d2
offbit  movem.l d0-d2, -(a7)
move    sr, -(a7)
ori     #$0700, sr
moveq   #porta, d1      ;get ready to read in the port a contents
move.l  d2, -(a7)
bsr.b   gientry         ;go get it...
move.l  (a7)+, d2
and.b   d2, d0          ;turn bit(s) off
moveq   #porta+$80, d1  ;setup to write to port a
bsr.b   gientry         ;go set it and return
move    (a7)+, sr
movem.l (a7)+, d0-d2
rts

```

```
.page
.text
```

```

*****
*
*   EXTENDED RBP BIOS MOUSE INIT CALL
*
*   entry:
*
*   void    initmous(type, param, intvec)
*   word    type
*
*****

```

```

*      long      param,intvec      *
*
*      type - key/abs/rel/off  mouse function requested      *
*              4/ 2/ 1/ 0  value      *
*      param - address of parameter block      *
*      intvec - mouse interrupt vector      *
*
*
*      parameter block definition:
*
*      byte 0 - y=0 at top/bottom; if non-zero then y=0 at bottom
*              otherwise y=0 at top
*      byte 1 - parameter for set mouse buttons command
*      byte 2 - x threshold/scale/delta parameter
*      byte 3 - y threshold/scale/delta parameter
*
*      the following bytes are required for the absolute mouse only
*
*      byte 4 - xmsb for absolute mouse maximum position
*      byte 5 - xlsb for absolute mouse maximum position
*      byte 6 - ymsb for absolute mouse maximum position
*      byte 7 - ylsb for absolute mouse maximum position
*      byte 8 - xmsb for absolute mouse initial position
*      byte 9 - xlsb for absolute mouse initial position
*      byte a - ymsb for absolute mouse initial position
*      byte b - ylsb for absolute mouse initial position
*
*****

```

```

.global  initmouse

```

```

initmouse

```

```

*      first we determine if the init is for a absolute, relative, or keycode
*      mouse action.

```

```

      tst.w    $4(sp)          ;turn mouse off?
      beq.b   im1             ;yes...disable mouse
      move.l  $a(sp),msintvec(a5) ;init the mouse interrupt vector
      move.l  $6(sp),a3
      cmpi.w  ##1,$4(sp)      ;relative mouse request?
      beq.b   im2             ;yes...
      cmpi.w  ##2,$4(sp)      ;absolute mouse request?
      beq.b   im3             ;yes...
      cmpi.w  ##4,$4(sp)      ;keycode mouse request?
      beq.b   im4             ;yes...
      moveq   ##0,d0          ;error condition returned -- improper request
      rts
im1     moveq   ##12,d1        ;disable mouse
      bsr    ikbput
      move.l  #xbtexit,msintvec(a5) ;re-init the mouse interrupt vector
      bra.b  imexit
im2     lea    transbuf(a5),a2 ;set transfer buffer pointer
      move.b  ##8,(a2)+       ;set to relative mouse
      move.b  ##b,(a2)+       ;set relative mouse threshold x,y
      bsr.b  setmouse

```

```

    moveq    #7-1,d3          ;set length of string -1 to transfer
    lea     transbuf(a5),a2  ;set transfer buffer pointer
    bsr     ikbdstr          ;do transfer to ikbd
    bra.b   imexit

im3
    lea     transbuf(a5),a2  ;set transfer buffer pointer
    move.b  #$9,(a2)+        ;set to absolute mouse
    move.b  4(a3),(a2)+      ;set xmsb max
    move.b  5(a3),(a2)+      ;set xlsb max
    move.b  6(a3),(a2)+      ;set ymsb max
    move.b  7(a3),(a2)+      ;set ylsb max
    move.b  #$c,(a2)+        ;set absolute mouse scale
    bsr.b   setmouse
    move.b  #$e,(a2)+        ;load initial absolute mouse position
    move.b  #$0,(a2)+        ;filler load
    move.b  8(a3),(a2)+      ;initial xmsb absolute mouse position
    move.b  9(a3),(a2)+      ;initial xlsb absolute mouse position
    move.b  $a(a3),(a2)+     ;initial ymsb absolute mouse position
    move.b  $b(a3),(a2)+     ;initial ylsb absolute mouse position
    moveq   #17-1,d3         ;set length of string -1 to transfer
    lea     transbuf(a5),a2  ;set transfer buffer pointer
    bsr     ikbdstr          ;do transfer to ikbd
    bra.b   imexit

im4
    lea     transbuf(a5),a2  ;set transfer buffer pointer
    move.b  #$a,(a2)+        ;set to mouse keycode mode
    bsr.b   setmouse
    moveq   #6-1,d3         ;set length of string -1 to transfer
    lea     transbuf(a5),a2  ;set transfer buffer pointer
    bsr     ikbdstr          ;do transfer to ikbd
imexit  moveq   #-$1,d0       ;set to true to indicate good init
        rts

setmouse
    move.b  2(a3),(a2)+      ;set x threshold/scale/delta
    move.b  3(a3),(a2)+      ;set y threshold/scale/delta
    moveq   #$10,d1         ;setup to determine if top/bottom
    sub.b   0(a3),d1        ;set y=0 at ?
    move.b  d1,(a2)+
    move.b  #$7,(a2)+       ;set mouse button action
    move.b  1(a3),(a2)+     ;mouse button parameter
    rts

```

```

*****
*
*           EXTENDED RBP BIOS TIMER INIT CALL
*
*   entry:
*
*   void     xbtimer(id,control,data,intvec)
*   word     id,control,data
*   long     intvec
*
*   intvec - timer interrupt vector
*   control - timer's control setting
*   data - timer's data register setting
*   id - timer id    a-0, b-1, c-2, d-3
*

```

Special Note:

In the interest of preserving as many features for the user in the future, timer A should be reserved for the end-user or independent software vendor's application program. System software or those application needing just a "tick" should constrain themselves to timer C, which is adequate for delay and other timing uses. Future hardware may or may not bring out the timer A input line out...giving software developers another useful aspect of the machine to utilize.

The recommended usage of the timers is as follows:

- Timer A - Reserved for end-users and stand-alone applications.
- Timer B - Reserved for screen graphics, primarily.
- Timer C - Reserved for system timing (GSX, GEM, DESKTOP, ET. AL).
- Timer D - Reserved for baud rate control of RS-232 port, the interrupt vector is available to anyone.

\*\*\*\*\*

.globl xbtimer

xbtimer

```

moveq    #$0, d0
moveq    #$0, d1
moveq    #$0, d2
move.w   $4(sp), d0
move.w   $6(sp), d1
move.w   $8(sp), d2
bsr      setimer          ;setup the timer
tst.l    $a(sp)           ;if >$7fffffff then skip and exit
bmi.b    xbtexit
movea.l  $a(sp), a2       ;setup for initint call
moveq    #$0, d1         ;clear long
lea      xbtim, a1        ;point to timer -> interrupt # translation tab
andi.l   #$ff, d0        ;mask off the highest three bytes in register
move.b   0(a1, d0), d0    ;setup for initint call
bsr      initint

```

xbtexit

rts

xbtim

dc.b \$d, \$8, \$5, \$4

.even

\*\*\*\*\*

KEYBOARD TRANSLATION TABLE CHANGE CALL

entry:

```

long    keytrans(unshift, shift, capslock)
long    unshift, shift, capslock

```

-1 signifies no change to vector

exit:

```

*          d0.l - returns pointer to beginning of
*          key translation address pointers
*          order of pointers is:
*          unshifted, shifted, caps-locked
*          Note:  buffer space for each table should $80!!
*
*****

```

.globl keytrans

keytrans

```

    tst.l  $4(sp)
    bmi.b  kt1
    move.l  $4(sp), skeytran(a5)
kt1      tst.l  $8(sp)
    bmi.b  kt2
    move.l  $8(sp), skeyshif(a5)
kt2      tst.l  $c(sp)
    bmi.b  kt3
    move.l  $c(sp), skeycl(a5)
kt3      move.l  #skeytran, d0
    rts

```

```

*****
*
*          RESTORE BIOS KEYBOARD TRANSLATION TABLE
*
*          entry:
*
*          void    bioskeys()
*
*****

```

.globl bioskeys

bioskeys

```

    move.l  #keytran, skeytran(a5)
    move.l  #keyshif, skeyshif(a5)
    move.l  #keycl, skeycl(a5)
    rts

```

```

*****
*
*          RETURN IKBD SUBSYSTEM INTERRUPT TABLE POINTER
*
*          entry:
*
*          void    dosound(ptr)
*          long    ptr      ;points to start of sound interpreter table
*
*****

```

.globl dosound

dosound

```

        move.l cursnd(a5),d0      ; return current status in D0.L
        move.l 4(sp),d1          ; if new ptr < 0, then just return
        bmi   ds_r              ; (invalid ptr, so return)
        move.l d1,cursnd(a5)     ; setup new sound ptr
        clr.b timer(a5)        ; zap sound timer register
ds_r    rts

```

```

*****
*
*           SET/RETURN PRINTER CONFIGURATION WORD
*
*   entry:
*
*   word   setprt(pconfig)
*   word   pconfig ;sets/gets printer information word
*
*****

```

```

        .globl setprt

setprt
        move.w pconfig(a5),d0    ;get current config word before we change it
        tst.w  4(sp)             ;see if we don't change the word
        bmi.b  nosetp           ;don't set printer word
        move.w 4(sp),pconfig(a5) ;set printer config word
nosetp  rts

```

```

*****
*
*           SET/RETURN KEY REPEAT VALUES
*
*   entry:
*
*   word   kbrate(initial,repeat)
*   word   initial,repeat
*
*   initial determines the number of 50 hz cycles to wait before
*   a keyrepeat is to commence.  repeat determines the interval
*   between keyrepeats after the initial pause.
*
*****

```

```

        .globl kbrate

kbrate
        move.w cdelay1(a5),d0    ;get current initial/repeat values
        tst.w  4(sp)             ;see if we don't change the word
        bmi.b  kbrate1          ;don't set key repeat values
        move.w 4(sp),d1          ;set key repeat values
        move.b d1,cdelay1(a5)    ;set initial delay
        tst.w  6(sp)             ;see if we don't change the word
        bmi.b  kbrate1          ;don't set key repeat values
        move.w 6(sp),d1          ;set key repeat values
        move.b d1,cdelay2(a5)    ;set subsequent delay
kbrate1 rts

```

```

*****
*
*           RETURN POINTER TO IKBD/MIDI INTERRUPT VECTORS
*
*   entry:
*
*   long   ikbdvecs()
*           returns a pointer to the midi interrupt vector and
*           ikbd subsystem interrupt vector table.  the table
*           structure is as follows:
*
*   midivec      ds.l    1      ;midi interrupt handler vector
*   vkbderr      ds.l    1      ;keyboard error handler address
*   vmiderr      ds.l    1      ;midi error handler address
*   statintvec   ds.l    1      ;ikbd status interrupt vector
*   msintvec     ds.l    1      ;mouse interrupt vector
*   clkintvec    ds.l    1      ;realtime clk interrupt vector
*   joyintvec    ds.l    1      ;joystick interrupt vector
*
*   note:  msintvec is modified via the initmouse system function
*           call.  since gem uses this vector, modifying it can be
*           fatal while running under gem.  clkintvec is used by
*           gemdos.  its pre-inited vector must be restored for
*           proper gemdos operation.  Caveat hacker!
*
*****

```

```

        .globl ikbdvecs

ikbdvecs
        move.l #midivec,d0
        rts

```

```

*****
*
*   C Timer interrupt routine to process the PSG sound table
*
*****
**+ (lmd)
*   timercint - timer c interrupt handler
*   divide 200 Hz interrupt frequency to 50 hz, and do:
*       sound handler processing
*       key-repeat processing;
*       control-g bell and keyclick if enabled via sound handler
*       system timer-tick handoff.
*   updates:          tc_rot (every tick)
*
*   imports:          etv_timer (timer handoff vector)
*                    _timr_ms (timer calibration value)
*
*-

```

```
timercint
```

```

add.l    #1,_hz_200      ;increment raw tick counter
rol.w    tc_rot          ;rotate divisor bits
bpl.b    t_punt          ;if not 4th interrupt, then return

movem.l  d0-d7/a0-a6,-(sp)

lea     $0,a5            ;address pointer to variable base

bsr.b    sndirq          ;process sounds...

btst.b   #$1,conterm(a5);check for key repeat enabled
beq.b    krexit          ;not enabled

*        process for repeat key function first because it can affect the sound
*        table if enabled and the user is 'using'...

tst.b    keyrep(a5)
beq.b    krexit
tst.b    kdelay1(a5)
beq.b    kr1
subi.b   #1,kdelay1(a5)
bne.b    krexit
kr1      subi.b   #1,kdelay2(a5)
bne.b    krexit
move.b   cdelay2(a5),kdelay2(a5)
move.b   keyrep(a5),d0
lea      kbufrec(a5),a0
bsr      aril6          ;repeat key stroke and stuff into buffer

krexit
**+ (lmd)
* Call system timer vector
* (first guy in the system daisy-chain)
*
*--

move.w   _timr_ms(a5),-(sp) ;push #ms/tick
move.l   etv_timer(a5),a0   ;get vector
jsr      (a0)                ;call it
addq     #2,sp               ;cleanup stack

tick1    movem.l  (sp)+,d0-d7/a0-a6
t_punt   bclr.b   #5,isrb+mfprte ;clear the interrupt channel
rte

*****
*
* Quick & dirty sound stuff
*
*
* Programmed by Dave Staugas
* 14 Mar 1985
*
*
*
*****

```

```

*
*
*
*
* To start a sound, load the 32-bit address of the
*       byte stream for that sound in 32-bit
*       "cursnd", & zero the 8-bit "timer"
*
*
*
* Sound interrupt routine
* Called from timer C irq
*
sndirq:
    movem.l a0/d0-d1, -(sp)
    move.l cursnd(a5), d0           ;get current sound ptr
    beq    snd1                    ;br to exit if zero, inactive
    movea.l d0, a0                 ;ptr to a0
    move.b timer(a5), d0          ;check delay timer
    beq.b  snd3                    ;br over delay timer update if not on
*
    subq.b #1, d0                  ;tick off delay timer
    move.b d0, timer(a5)          ;save new
    bra.b  snd1                    ;skip sound update this time
snd3:
    move.b (a0)+, d0              ;pick up next sound command
    bmi.b  snd2                    ;if minus, go do special
*
    move.b d0, giselect           ;else, register load command--select this
    cmpi.b #7, d0                 ;reg. 7 selected?
    bne.b  sn1                     ;br if no
*
    move.b (a0)+, d1              ;get data to write to reg 7
    andi.b #$3f, d1               ;always leave i/o port settings alone
    move.b rddata, d0             ;get mixer contents
    andi.b #$c0, d0              ;mask off non-useful info...
    or.b   d1, d0                 ;generate new setting
    move.b d0, wrdata            ;write data
    bra.b  snd3                   ;go for next command
sn1:
    move.b (a0)+, wrdata          ;write next byte as data directly to reg
    bra.b  snd3                   ;go for next command
*
* special case command
*
snd2:
    addq.b #1, d0                 ;was command 255?
    bpl.b  snd5                    ;br if yes--set delay timer
*
    cmpi.b #129, d0              ;was command 128 (before increment)
    bne.b  snd6                    ;br if not
+
+ command 128
+

```

```

move.b (a0)+,auxd(a5)
bra.b  snd3

```

```

;128--set aux data from next byte in stream
;go for next command

```

```
command > 128
```

```
nd6:
```

```

cmpi.b #130,d0
bne.b  snd5

```

```

;command greater than 129
;br if yes--must be set timer

```

```
command 129
```

```

move.b (a0)+,giselect
move.b (a0)+,d0
add.b  d0,auxd(a5)
move.b (a0)+,d0
move.b auxd(a5),wrdata
cmp.b  auxd(a5),d0
beq.b  snd4

```

```

;129--select register
;get increment step (signed)
;add to aux data
;get terminating value
;load reg from data in auxd
;reached end of cycle?
;br if so

```

```
still within loop, reset sound pointer to iterate for next irq
```

```

subq   #4,a0
bra.b  snd4

```

```

;back up sound ptr to repeat this command
;update ptr & exit

```

```
set delay timer
```

```
nd5:
```

```

move.b (a0)+,timer(a5)
bne.b  snd4
movea.w #0,a0

```

```

;set delay timer from next byter in stream
;if non-zero, real delay here
;else, sound terminator--set ptr to null

```

```
nd4:
```

```
move.l a0,cursnd(a5)
```

```
;update sound ptr
```

```
nd1:
```

```

movem.l (sp)+,a0/d0-d1
rts

```

```
;pop stack & exit
```

```
sound data...
```

```
format:
```

sound data usually is found in byte pairs, the first of which is the command and the second is the argument. However, some commands take on more than 1 argument.

| cmd | function  | argument(s) |
|-----|-----------|-------------|
| 00  | load reg0 | data0       |
| 01  | load reg1 | data0       |
| 02  | load reg2 | data0       |
| 03  | load reg3 | data0       |
| 04  | load reg4 | data0       |
| 05  | load reg5 | data0       |
| 06  | load reg6 | data0       |
| 07  | load reg7 | data0       |

note: b7 & b6 forced set for all data to r

```

*      08      load reg8      data0
*      09      load reg9      data0
*      0A      load reg10     data0
*      0B      load reg11     data0
*      0C      load reg12     data0
*      0D      load reg13     data0
*
*
*      80      init temp w/    data0
*
*      81      loop defined    data0 as register to load using temp
*              by 3 args      data1 as increment/decrement (signed) of temp
*                              data2 as loop terminator value of temp
*
*      82-FF   set delay      data0 is # of counts till next update
*              timer          note: if data0 = 0, sound is terminated
*
*
*

```

bellsnd:

```

. dc. b      0, $34
. dc. b      1, 0
. dc. b      2, 0
. dc. b      3, 0
. dc. b      4, 0
. dc. b      5, 0
. dc. b      6, 0
. dc. b      7, $FE
. dc. b      8, $10      ; enable envelope, ch a
. dc. b      9, 0
. dc. b     10, 0
. dc. b     11, 0
. dc. b     12, $10
. dc. b     13, 9        ; envelope single attack
. dc. b     255, 0

```

\*

keyclk:

```

. dc. b      0, $3B
. dc. b      1, 0
. dc. b      2, 0
. dc. b      3, 0
. dc. b      4, 0
. dc. b      5, 0
. dc. b      6, 0
. dc. b      7, $FE
. dc. b      8, $10      ; enable envelope, ch a
. dc. b     13, $3        ; envelope single attack
. dc. b     11, $80
. dc. b     12, 1
. dc. b     255, 0

```

\*

```

*-----*
*
*      Boot sector
*      Loads OS.IMG from the disk and executes it.
*
*      (C)1985 Atari Corp.
*
* 25-Feb-1985 lmd      Hey!  It fits in 512 bytes....
* 2-Apr-1985 lmd      Fixed bugs (it works now)
*-----*

```

text

```

*
* BPB fields:
*
recsiz equ 0 ; size of a sector in bytes
clsiz equ 2 ; number of sectors/cluster
clsizb equ 4 ; size of a cluster in bytes
rdlen equ 6 ; root directory length
fsiz equ 8 ; size of a FAT (in sectors)
fatrec equ 10 ; start of 2nd FAT
datrec equ 12 ; sector# of first data sector
numcl equ 14 ; number of clusters on media
bflags equ 16 ; flags

```

```

*
* OS variables:
*
_membot equ $432 ; pointer to bottom of memory
_cmdload equ $482 ; load-command switch
bootdev equ $446 ; default boot device

```

```

*
* Executable code,
* random garbage,
* and a serial number:
*

```

```

bra.s start ; branch to code
dc.b 'Loader' ; name of the loader
dc.b $00,$00,$00 ; 24-bit serial number

```

```

*
* 80 track, single-sided BPB
* (Identical to "DG-1" BPB)
*

```

```

dc.b $00,$02 ; #bytes/sector
dc.b $02 ; #sectors/cluster
dc.b $01,$00 ; #reserved sectors
dc.b $02 ; #of FATs
dc.b $70,$00 ; #of root directory entries
dc.b $d0,$02 ; #of sectors on media
dc.b $f8 ; media descriptor byte

```

```

dc.b    $05,$00    ; #sectors/FAT
dc.b    $09,$00    ; #sectors/track
dc.b    $01,$00    ; #sides on media
dc.b    $00,$00    ; #hidden sectors

```

even

\*  
\* Boot parameters

```

*
execflg:    dc.w    0    ; copied to _cmdload
ldmode:    dc.w    0    ; 0:load file, 1:load sectors
ssect:    dc.w    0    ; starting sector# to load
nsects:    dc.w    0    ; #sectors to load
ldaddr:    dc.l    $40000 ; load address
fatbuf:    dc.l    $8000 ; good place for FAT/directory buffer
fname:    dc.b    "OS     IMG" ; filename to load (11 chars)
*
                12345678901

```

even

\*+  
\* Neuter Booter

\* Register usage:

```

*   A6 -> FAT buffer
*   A5 -> BPB
*   A4 -> directory/load buffer
*   A3 -> current read address
*   A0..A2 used by traps
*
*   D7 = current cluster number
*   D6 = starting sector/sector number
*   D5 = ending sector
*   D4 = sector count
*   D3 = current sector
*   D0..D2 used by traps

```

\*-  
start:

```

move.w    execflg(pc),_cmdload    ; set command-load flag

```

\*----- Get BPB for boot device:

```

move.w    bootdev,-(sp)    ; d0 = getbpb(bootdev)
move.w    #7,-(sp)
trap     #13
addq     #4,sp
tst.l    d0    ; if(d0 == NULL) return;
beq     _fail    ; (I give up)
move.l    d0,a5    ; a5 -> BPB

```

```

lea     fatbuf(pc),a0    ; if(fatbuf == NULL)
tst.l    (a0)    ; fatbuf = _membot
bne     fbuf1

```

```

fbuf1:  move.l    _membot,(a0)
move.w    fsiz(a5),d0    ; a4 = fatbuf + (a5[fsiz] << 9)
lsl.w    #8,d0
add.l    d0,d0

```

```

    move.w  d0,a4
    add.l   fatbuf(pc),a4           ; a4 -> directory buffer

*----- Which mode?
    move.w  ldmode(pc),d0          ; test mode switch
    beq     ldfile                 ; (load file)

*----- Load and exec sectors:
    move.w  ssect(pc),d6           ; starting sector#
    move.w  nsects(pc),d4          ; #sectors to load
    move.l  ldaddr(pc),a3          ; load-address
    bra     l_done                 ; load sectors, execute 'em

*----- Read FAT and directory sectors into memory:
ldfile: move.w  fatrec(a5),d6       ; start = 2nd FAT
    move.w  fsiz(a5),d4            ; count = a5[fsiz] + a5[rdlen]
    add.w   rdlen(a5),d4
    move.l  fatbuf(pc),a3          ; address = the FAT buffer
    bsr     readmult               ; read sectors
    bne     _fail

*----- Setup to search for the image file:
    move.l  a4,a0                  ; a0 -> directory buffer
    move.w  rdlen(a5),d0
    lsl.w   #8,d0
    lsl.w   #1,d0                  ; a0 += rdlen * 512
    lea    (a0,d0.w),a0            ; a0 -> end of directory buffer
    lea    fname(pc),a1           ; a1 -> file to open

*----- Search directory (backwards):
b_3:   sub.w  #$20,a0              ; backup one directory entry
b_1:   cmp.l  a4,a0               ; if(a0 < a4) then fail
    blt     _fail                 ; (file not found, so punt)
    moveq   #10,d0                ; d0 = dbra length of file name
b_2:   move.b (a0,d0.w),d1         ; compare filename
    cmp.b  (a1,d0.w),d1
    bne    b_3                     ; try next entry on match failure
    dbra   d0,b_2                 ; (try all chars)

*----- Get (byte-reversed) cluster number:
    moveq   #0,d7                  ; get starting cluster number
    move.b  27(a0),d7              ; from byte-reversed entry in
    lsl.w   #8,d7                  ; the directory entry
    move.b  26(a0),d7

*----- Setup for reading the file:
    move.l  fatbuf(pc),a6          ; a6 -> FAT
    move.l  ldaddr(pc),a3          ; a3 -> read address
    clr.l   d4                     ; no sector count

**
* Read the file.
* Read as many sectors as possible at once (try to suck it
* in with one rwabs call...)
*
```

\*-

```

*----- compute sector number from cluster number:
l_1:   cmp.w   #$0ff0,d7           ; end of chain?
       bge    l_done             ; (yes)

       move.w d7,d3              ; d3 = d7 - 2
       subq   #2,d3
       mulu   clsiz(a5),d3        ; d3 *= clsiz
       add.w  datrec(a5),d3       ; d3 += datrec

*----- if "break" in chain of sectors, read some in:
       tst.w  d4                  ; any old sectors?
       beq    l_4                 ; (no)
       cmp.w  d5,d3               ; can this one be appended?
       beq    l_3                 ; (yes)
       bsr    readmult           ; read old sectors
       bne    _fail              ; (punt on read failure)

       lsl.l  #8,d4               ; a3 += count * 512
       lsl.l  #1,d4
       add.l  d4,a3

*----- startup a new chunk of contiguous sectors:
l_4:   move.w  d3,d6               ; start = current sector
       move.w  d3,d5               ; end = current sector
       clr.l  d4                  ; count = 0
l_3:   add.w   clsiz(a5),d4         ; append current sector to
       add.w   clsiz(a5),d5         ; the contiguous chunk

*----- compute next cluster number:
       move.w  d7,d2               ; d2 = (d7 >> 1) + d7
       lsr.w  #1,d2
       add.w  d7,d2
       move.b  1(a6,d2.w),d1        ; get high byte
       lsl.w  #8,d1               ; shift it up
       move.b  (a6,d2.w),d1        ; get low byte (d1 = raw cluster entry)
       btst  #0,d7                ; if(d7 & 1) d1 >>= 4
       beq    l_2
       lsr.w  #4,d1
l_2:   and.w   #$0fff,d1           ; d1 &= $0fff
       move.w  d1,d7               ; d7 = d1
       bra    l_1                 ; read next cluster

*----- read any leftover sectors:
l_done: tst.w  d4                  ; any sectors left?
       beq    ld_ex               ; (nothing more to read)
       bsr    readmult           ; read remainder (usu. entire file)
       bne    _fail              ; (punt on read failure)
ld_ex:  move.l  ldaddr(pc),-(sp)    ; jump to stuff we just loaded
       rts

*----- could not boot: complain
_fail:  clr.l  d0                  ; error = 0

```

rts

\*+

```

* Read sectors from boot device
* Passed:      d6 = logical sector number
*              d4 = count
*              a3 -> address

```

```

* Returns:     NE: failure
*              EQ: success

```

\*-

readmult:

```

        move.w bootdev, -(sp)      ; device = bootdev
        move.w d6, -(sp)          ; record = d6
        move.w d4, -(sp)          ; count = d4
        move.l a3, -(sp)          ; addr = a3
read:   clr.w  -(sp)                ; operation = READ
        move.w #4, -(sp)          ; function = rwabs
        trap  #13                 ; bios trap
        add.w #14, sp             ; cleanup stack
        tst.w d0                  ; test return code
        rts

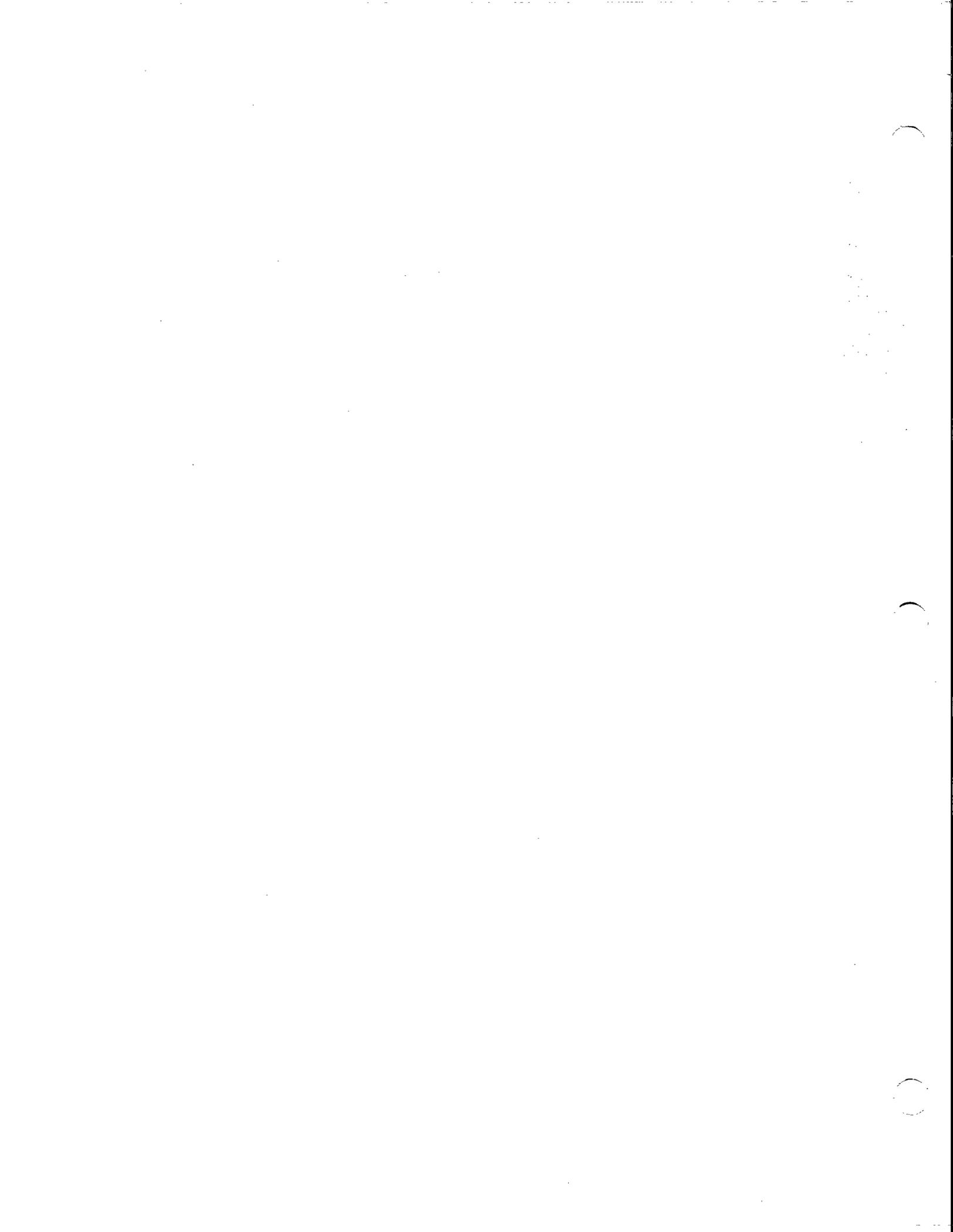
```

\*-----

```

copyrt: dc.b  'Neuter Booter', 13, 10
        dc.b  '(C)1985 Atari Corp.', 13, 10
        dc.b  0

```



```
loadable      equ      1      ; nonzero for loadable driver
```

```
*-----
*
*      ST SASI hard disk driver
*      (C)1985 Atari Corp.
*
*-----
*  9-Apr-1985 lmd      Hacked it up. "Gee, it seems to work ..."
* 14-Apr-1985 lmd      linked with BIOS (***FOR NOW***)
* 20-Apr-1985 lmd      hacked for WD controller (now, wired...)
*
*-----
```

```
flock          equ      $43e      ; FIFO lock variable
hdv_init       equ      $46a      ; hdv_init()
hdv_bpb        equ      $472      ; hdv_bpb(dev)
hdv_rw         equ      $476      ; hdv_rw(rw, buf, count, recno, dev)
hdv_boot       equ      $47a      ; hdv_boot()
hdv_mediach    equ      $47e      ; hdv_mediach(dev)
_drvbits      equ      $4c2      ; block device bitVector
_dskbufp      equ      $4c6      ; pointer to common disk buffer

nretries      equ      3          ; #retries-1
```

```
* ----- Installer -----
      .globl  i_sasi
i_sasi: nop      ; stupid assembler

ifne loadable
      clr.l  -(sp)      ; it's a bird...
      move.w #20, -(sp) ; ... it's a plane ...
      trap  #1          ; ... no, its:
      addq  #6, sp      ; SOOUPERUSER!
      move.l d0, savssp ; "Faster than a prefetched opcode..."
endifc

      bsr   _sasi_init  ; kick controller
      tst.w d0
      bmi  isasq        ; punt -- disk didn't respond

      clr.l  d0
      or.l  _drvbits, d0 ; include C: bit in devVector
      or.l  #$4, d0
      move.l d0, _drvbits

      clr.l  a5          ; zeropage ptr
      move.l hdv_bpb(a5), o_bpb ; save old vectors
      move.l hdv_rw(a5), o_rw
      move.l hdv_mediach(a5), o_mediach

      move.l #hbpb, hdv_bpb(a5) ; install our new ones
      move.l #hrw, hdv_rw(a5)
      move.l #hmediach, hdv_mediach(a5)
```

```

isasq:  nop                                ; stupid assembler

ifne loadable
    move.l  savssp, -(sp)                   ; become a mild mannered user process
    move.w  $$20, -(sp)
    trap   #1
    addq   #6, sp
endc
    rts

```

\* ----- Front End -----

```

**
* LONG hbpb(dev) - return ptr to BPB (or NULL)
*
* Passed:      dev      4(sp).W
*
*--
hbpb:
    move.w  4(sp), d0                       ; d0 = devno
    move.l  o_bpb, a0                       ; a0 -> pass-through vector
    lea    _sasi_bpb(pc), a1                ; a1 -> our handler
    bra    check_dev                       ; do it

```

```

**
* LONG rw(rw, buf, count, recno, dev)
*
* Passed:      dev      $e(sp).W
*              recno    $c(sp).W
*              count    $a(sp).W
*              buf      6(sp).L
*              rw       4(sp).W
*
*--
hrw:
    move.w  $e(sp), d0                       ; d0 = devno
    move.l  o_rw, a0                         ; a0 -> pass-through vector
    lea    _sasi_rw(pc), a1                  ; a1 -> our handler
    bra    check_dev                       ; do it

```

```

**
* LONG mediach(dev)
*
* Passed:      dev      4(sp).W
*
*--
hmediach:
    move.w  4(sp), d0                       ; d0 = devno

```

```

    move.l  o_mediach,a0      ; a0 -> pass-through vector
    lea    _sasi_mediach(pc),a1 ; a1 -> our handler

```

```

**
* check_dev - use handler, or pass vector through
*
* Passed:      d0.w = device#
*              a0 -> old handler
*              a1 -> new handler
*              a5 -> $0000 (zero-page ptr)
*
* Jumps-to:    (a1) if dev in range for this handler
*              (a0) otherwise
*
*-

```

```

check_dev:
    cmp.w   #2,d0           ; devnos match?
    bne    chkd_f          ; (no)
    move.l  a1,a0           ; yes -- follow success vector
chkd_f:   jmp    (a0)       ; do it

```

```

* ----- Medium level driver -----

```

```

**
* _sasi_init - initialize SASI dev
* Passed:      nothing
* Returns:     d0 < 0: error
*              d0 == 0: success
*
*-

```

```

    .globl  _sasi_init
_sasi_init:

```

```

*--- read the boot sector about ten times

```

```

    move.w  #9,d7
isas1:   clr.w   -(sp)           ; dev = 0
    move.l  _dskbufp,-(sp)     ; use disk buffer
    move.w  #1,-(sp)          ; count = 1
    clr.l   -(sp)             ; sector = 0
    bsr    _hread             ; read it
    add.w   #12,sp            ; cleanup stack
    tst.w   d0                 ; test read error return
    dbmi   d7,isas1           ; loop while no error
    bmi    isas2              ; (punt on error)

    bsr    _wd_setup          ; initialize WD parms
    clr.l   d0
isas2:   rts

```

```

**
* _sasi_bpb - return BPB for hard drive
* Synopsis:   LONG _sasi_bpb(dev)

```

```

*          WORD dev;
*
* Returns:  NULL, or a pointer to the BPB buffer
*
*--
        .globl  _sasi_bpb
_sasi_bpb:
        move.l  #thebpb, d0
        rts

**+
* _sasi_rw - read/write hard sectors
* Synopsis:  _sasi_rw(rw, buf, count, recno, dev)
*
* Passed:   dev      $e(sp).W
*           recno    $c(sp).W
*           count    $a(sp).W
*           buf      6(sp).L
*           rw       4(sp).W
*
*--
        .globl  _sasi_rw
_sasi_rw:
        move.w  #nretries, retrycnt      ; setup retry counter

sasrw1:  moveq   #0, d0                    ; coerce word to long, unsigned
        move.w  $c(sp), d0                ; sect.L
        move.w  $a(sp), d1                ; count.W
        move.l  6(sp), d2                 ; buf.L
        move.w  4(sp), d3                 ; rw

        clr.w   -(sp)                     ; dev = 0
        move.l  d2, -(sp)                  ; buf
        move.w  d1, -(sp)                  ; count
        move.l  d0, -(sp)                  ; sect
        tst.w   d3                          ; read or write?
        bne    sasrw3                       ; (write)
        bsr    _hread                        ; read sectors
        bra    sasrw2

sasrw3:  bsr    _hwrite                       ; write sectors
sasrw2:  add.w  #12, sp                     ; (cleanup stack)
        tst.l  d0                          ; errors?
        beq    sasrwr                       ; no -- success
        subq.w #1, retrycnt                 ; drop retry count and retry
        bpl    sasrw1

sasrwr:  rts

**+
* _sasi_mediach - see if hard disk media has changed (it never does)
* Synopsis:  _sasi_mediach(dev)
*           WORD dev;
*

```

\* Returns: OL

\*

\*-

```

        .globl  _sasi_mediach
_sasi_mediach:
        clr.l   d0
        rts
    
```

\*\*

\* BPB for 10MB drive

\* Approximate only. Tweak me.

\*

\*-

```

thebpb: dc.w    512           ; #bytes/sector
         dc.w    2           ; #sectors/cluster
         dc.w   1024         ; #bytes/cluster
         dc.w    16          ; rdlen (256 root files)
         dc.w    41          ; FATsiz (10300 FAT entries)
         dc.w    42          ; 2nd FAT start
         dc.w    99          ; data start
         dc.w   10300        ; #clusters (approximate here)
         dc.w    1           ; flags (16-bit FATs)
    
```

\* ----- Low-level driver -----

\*----- Globals

```

flock      equ      $43e      ; FIFO lock variable
_hz_200    equ      $4ba      ; 200hz system ticker
    
```

\*----- Hardware:

```

wdc        equ      $ff8604
wdl        equ      $ff8606
dmahi      equ      $ff8609
dmamid     equ      dmahi+2
dmalow     equ      dmamid+2
gpip       equ      $fffa01
    
```

\*----- Tunable:

```

ltimeout   equ      $10000    ; long-timeout
sttimeout  equ      $10000    ; short-timeout
    
```

\*\*

\* void \_qdone() - Wait for operation complete

\* Passed: nothing

\*

\* Returns: EQ: no timeout

\* MI: timeout condition

```

*
* Uses:          DO
*--
_qdone:
    move.l    #ltimeout,tocount
qd1:    subq.l    #1,tocount        ; drop timeout count
        bmi     qdq                ; (i give up, return NE)
        move.b   gpip,d0           ; interrupt?
        and.b    #$20,d0
        bne     qd1                ; (not yet)
        move.w   #$80,wdl          ; why do we need to do this
        nop                                     ; to the hardware???
        tst.w    wdc
        moveq    #0,d0             ; return EQ (no timeout)
        rts
qdq:    moveq    #-1,d0            ; return -1 (error)
        rts

**
* void _sel()
* Fiddle with SASI lines
*
* Passed:        nothing
*
* Uses:          nothing
*--
_sel:
    move.w     #$88,wdl            ; _FDC + _HDCS + CA1=0(select_latch)
    nop
    move.w     #$20,wdc            ; iomode Rd=data, Wr=controller
    nop
    move.w     #$8a,wdl            ; _FDC + _HDCS + CA1=1(select_io)
    nop
    move.w     #$01,wdc            ; set direction = 1(output)
    nop
    move.w     #$88,wdl            ; _FDC + _HDCS + CA1=0(select_latch)
    nop
    move.w     #$00,wdc            ; iomode Rd=controller, Wr=data
    nop
    move.w     #$8a,wdl            ; _FDC + _HDCS + CA1=1(select_reg)
    nop
    move.w     #$01,wdc            ; write a $01 to data (?)
    rts

**
* void _req1()
* Wait for /REQ line to go low
*
* Passed:        nothing
*
* Returns:       EQ: ok
*                MI: timeout condition
*
* Uses:          DO
*--

```

```

_reql:
    move.l  #sttimeout,tocount    ; setup timeout counter
    move.w  ##88,wdl              ; select SASI status register
    nop
    move.w  ##20,wdc
    nop
    move.w  ##8a,wdl
reql1:  subq.l  #1,tocount          ; drop timeout count
        bmi     reql               ; (return NE on timeout)
        move.w  wdc,d0             ; get SASI status
        and.w   #2,d0              ; REG low?
        bne    reql1              ; (not yet)
        rts
reql:   moveq   #-1,d0
        rts

```

```

**
* WORD _endcmd()
* Wait for end of SASI command
* Passed:      nothing
*
* Returns:     EQ: success (error code in DO.W)
*              MI: timeout
*              NE: failure (SASI error code in DO.W)
*
* Uses:        DO
*
*-

```

```

_endcmd:
    bsr     _qdone                  ; wait for operation complete
    bmi     endce                  ; (timed-out, so complain)

    move.w  ##88,wdl              ; get completion error code
    nop
    move.w  ##00,wdc
    nop
    move.w  ##8a,wdl
    nop
    move.w  wdc,d1

    bsr     _reql                  ; wait for SASI $00
    bmi     endce                  ; (timeout)

    move.w  ##88,wdl
    nop
    move.w  ##00,wdc
    nop
    move.w  ##8a,wdl
    nop
    tst.w   wdc

    move.w  d1,d0                  ; d0 = error code
    and.w   ##00ff,d0             ; (clean it up)
    rts

endce:   moveq   #-1,d0

```

rts

```

**
* _hinit(dev)
* WORD dev;
* Initialize hard disk
*
* Returns:      -1 if hard disk not there
*
*--

```

```

_hinit:
    st      flock                ; lock FIFO
    tst.b   gpip                 ; magic
    bsr     _sel
    moveq   #5, d0
hi_1:     bsr     _req1
    move.w  #$00, wdc
    dbra   d0, hi_1
    bsr     _endcmd
    clr.w   flock                ; unlock FIFO
    bra     _hdone               ; cleanup after IRQ

```

```

*--
* _hread(sectno, count, buf, dev)
* LONG sectno;      4(sp)
* WORD count;       8(sp)
* LONG buf;         $a(sp)  $b=high, $c=mid, $d=low
* WORD dev;         $e(sp)
*

```

```

* Returns:
*      -1 on timeout
*       0 on success
*      nonzero on error
*
*--

```

```

    .globl _hread
_hread:
    st      flock                ; lock FIFO
    move.l  $a(sp), -(sp)        ; set DMA address
    bsr     _setdma
    addq   #4, sp

    bsr     _sel                 ; select magic
    bmi    _hto
    bsr     _req1                ; wait for ^REQ
    bmi    _hto
    move.w  #$08, wdc            ; read cmd
    bsr     _req1                ; ^REQ
    bmi    _hto
    move.b  5(sp), d0            ; construct sector#
    move.b  $e(sp), d1          ; ORed with devno
    lsl.b  #5, d1
    or.b   d1, d0
    move.w  d0, wdc              ; write MSB sector# + devno
    bsr     _req1                ; ^REQ

```

```

bmi    _hto
move.b 6(sp),d0           ; write MidSB sector#
move.w d0,wdc
bsr    _reql             ; ~REQ
bmi    _hto
move.b 7(sp),d0         ; write LSB sector#
move.w d0,wdc

bsr    _reql             ; write sector count
bmi    _hto
move.w 8(sp),wdc

bsr    _reql
bmi    _hto
move.w #$90,wdl         ; toggle data direction
nop
move.w #$190,wdl
nop
move.w #$90,wdl
nop
move.w 8(sp),wdc       ; write sector count to DMA chip
nop
move.w #$8a,wdl
nop
move.w #$07,wdc        ; end-of-command (+fast_step)
nop
move.w #$00,wdl
bsr    _endcmd
hrx:   clr.w flock      ; unlock FIFO
bra    _hdone           ; cleanup after IRQ

```

```

*-
* _hwrite(sectno, count, buf, dev)
* LONG sectno;          4(sp)
* WORD count;           8(sp)
* LONG buf;             $a(sp)  $b=high, $c=mid, $d=low
* WORD dev;             $e(sp)
*
*-

```

```

.globl _hwrite
_hwrite:
st      flock           ; lock FIFO

move.l $a(sp),-(sp)    ; set DMA address
bsr    _setdma
addq   #4,sp

bsr    _sel
bmi    _hto
bsr    _reql
bmi    _hto
move.w #$0a,wdc
bsr    _reql
bmi    _hto
move.b 5(sp),d0

```

```

move.b   $e(sp), d1           ; ORed with devno
lsl.b    #5, d1
or.b     d1, d0
move.w   d0, wdc
bsr      _req1
bmi      _hto
move.b   6(sp), d0
move.w   d0, wdc
bsr      _req1
bmi      _hto
move.b   7(sp), d0
move.w   d0, wdc

bsr      _req1           ; sector count
bmi      _hto
move.w   8(sp), wdc

bsr      _req1
bmi      _hto
move.w   #$90, wdl
nop
move.w   #$190, wdl
nop
move.w   8(sp), wdc           ; sector count
nop
move.w   #$18a, wdl
nop
move.w   #$07, wdc           ; end-of-command (+fast_step)
nop
move.w   #$100, wdl
bsr      _endcmd
hwx:    clr.w   flock           ; unlock FIFO
bra      _hdone           ; cleanup after IRQ

```

```

*+
* _wd_format - format WD hard disk
* Passed:      nothing
* Returns:     0, or -N
* Uses:        <..?..>
*
*-

```

```

.globl   _wd_format
_wd_format:
st       flock

bsr      _sel
bmi      hfx
bsr      _req1
bmi      hfx
move.w   #4, wdc
bsr      _req1
bmi      hfx
move.w   #0, wdc
bsr      _req1
bmi      hfx

```

```

move.w #0, wdc
bsr    _req1
bmi    hfx
move.w #0, wdc
bsr    _req1
bmi    hfx
move.w #0, wdc

bsr    _req1
bmi    hfx
move.w #$190, wdl
nop
move.w #$90, wdl
nop
move.w #1, wdc
nop
move.w #$8a, wdl
nop
move.w #$07, wdc
nop
move.w #$00, wdl
bsr    _endcmd
hfx:   clr.w  flock
bra    _hdone

```

```

**
* _wd_setup - setup parameters for WD hard disk
*
*-

```

```

.globl _wd_setup
_wd_setup:
    st        flock
    pea      wd_parms(pc)
    bsr      _setdma
    addq     #4, sp

    bsr      _sel
    bmi     wdx
    bsr      _req1
    bmi     wdx
    move.w  #$0c, wdc
    bsr      _req1
    bmi     wdx
    move.w  #$00, wdc

```

```

        bsr     _req1
        bmi     wdx
        move.w  #$90,wdl
        nop
        move.w  #$190,wdl
        nop
        move.w  #$01,wdc
        nop
        move.w  #$18a,wdl
        nop
        move.w  #$00,wdc
        nop
        move.w  #$100,wdl
        bsr     _endcmd
wdx:    clr.w   flock
        bra     _hdone
    
```

```

*--- parameters for 10MB WD
wd_parms: dc.b  $02,$64,$02,$01,$31,$01,$31,$0b
    
```

```

**
* void _setdma(addr)
* LONG addr;
*-
    
```

```

_setdma:
        move.b  7(sp),dmalow
        move.b  6(sp),dmamid
        move.b  5(sp),dmahi
        rts
    
```

```

_hto:   moveq   #-1,d0                ; indicate timeout
_hdone: move.w   #$80,wdl
        tst.w   wdc
        rts
    
```

```

        bss
savssp: ds.l    1                    ; (saved SSP)
tocount: ds.l   1                    ; timeout counter
retrycnt: ds.w   1                    ; retry counter
o_init:  ds.l   1
o_bpb:   ds.l   1
o_rw:    ds.l   1
o_mediach: ds.l  1
dma:     ds.l   1                    ; current DMA loc
count:   ds.w   1                    ; current sector count
sect:    ds.l   1                    ; current logical sector
    
```